

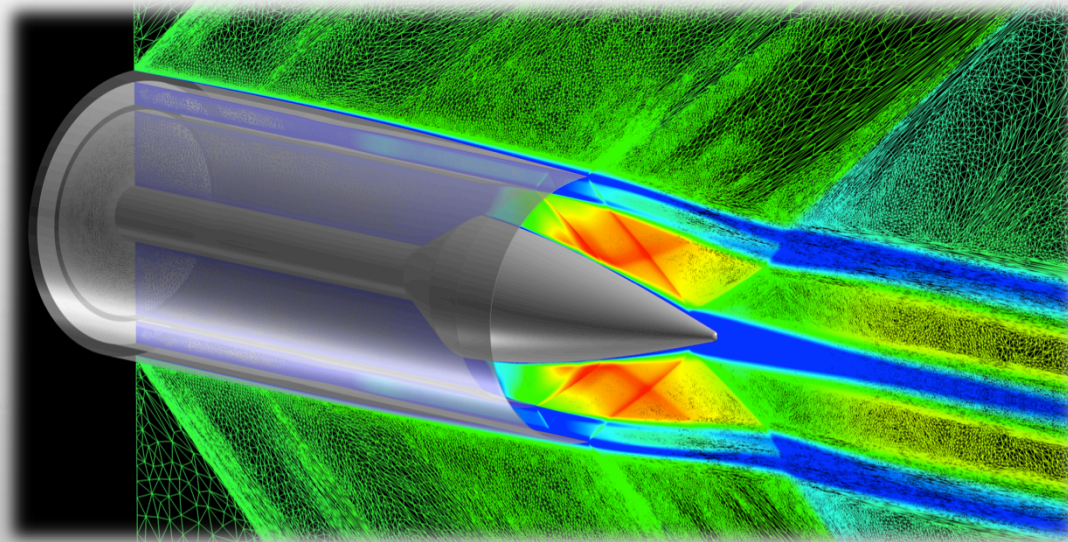
Aerodynamic Shape Optimization of a Dual-Stream Supersonic Plug Nozzle

Christopher M. Heath & Justin S. Gray

NASA GRC – Propulsion Systems Analysis Branch

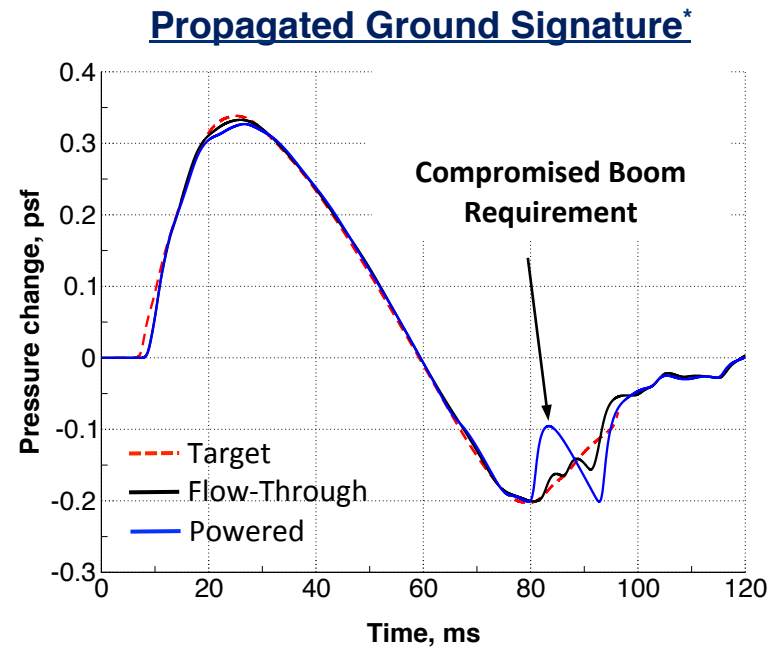
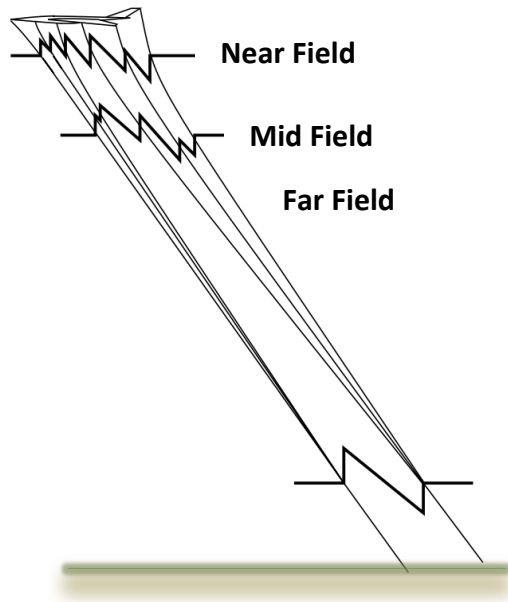
Michael A. Park, Jan-Renee Carlson, & Eric J. Nielsen

NASA LARC – Computational AeroSciences Branch



AIAA SciTech Conference
Kissimmee, FL
January 5-9, 2015

Overland sonic boom requirements challenge supersonic aircraft viability



Current State-of-the-Art:

Aerodynamic shape optimization demonstrated with airframe tailoring to meet low-boom perceived loudness goals

Drawbacks:

Recent experimental and computational research has shown introducing propulsion effects into an optimized airframe pressure signature can compromise the low-boom requirement

*Wintzer, M. et. al., "Aircraft-Nozzle-Plume Interactions in the Context of Low Sonic Boom Design," AIAA SciTech 2015.

Mitigate plume-induced near field pressure disturbances
without compromising nozzle performance

Current Approach:

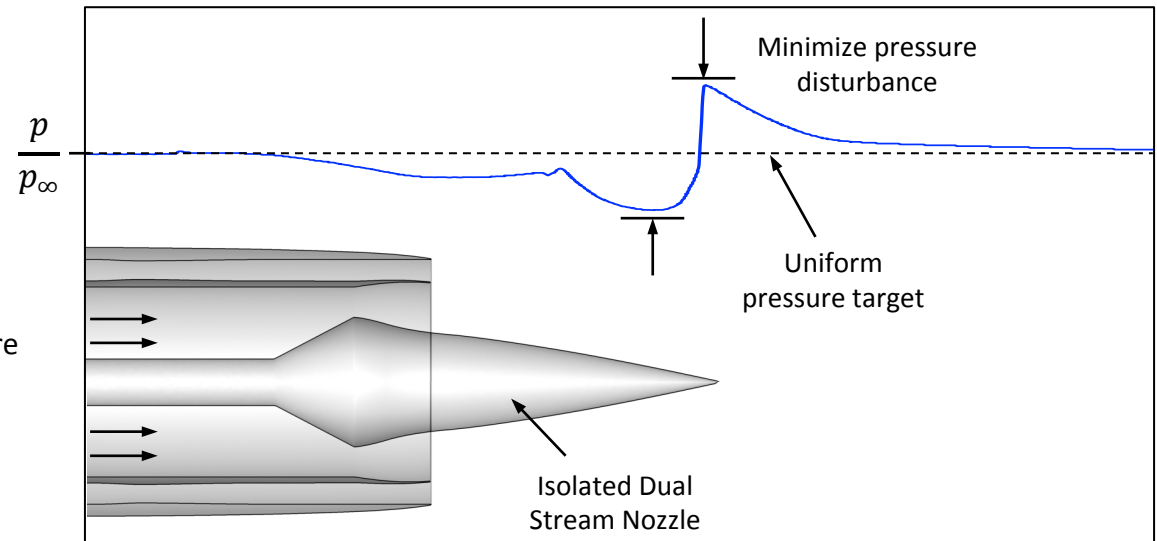
Aerodynamic tailoring of the powered propulsive streamtube to **minimize** all nearfield pressure contributions and simplify propulsion-airframe integration

Minimize:

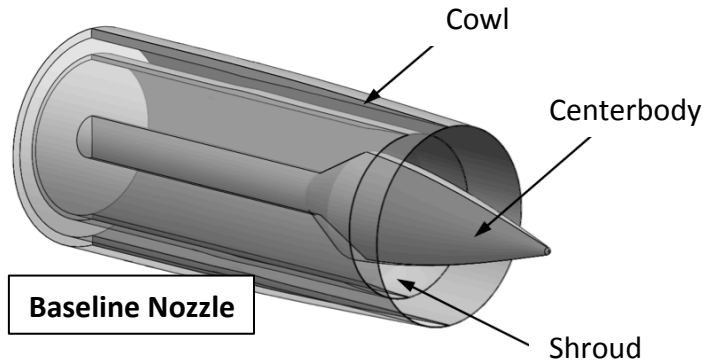
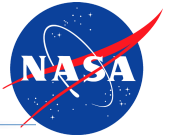
$$f = \sum_{i=1}^N \left(\frac{p}{p_{\infty}} \Big|_i - \frac{p}{p_{\infty}} \Big|_i^* \right)^2$$

Local pressure
ratio

Target pressure
ratio = 1

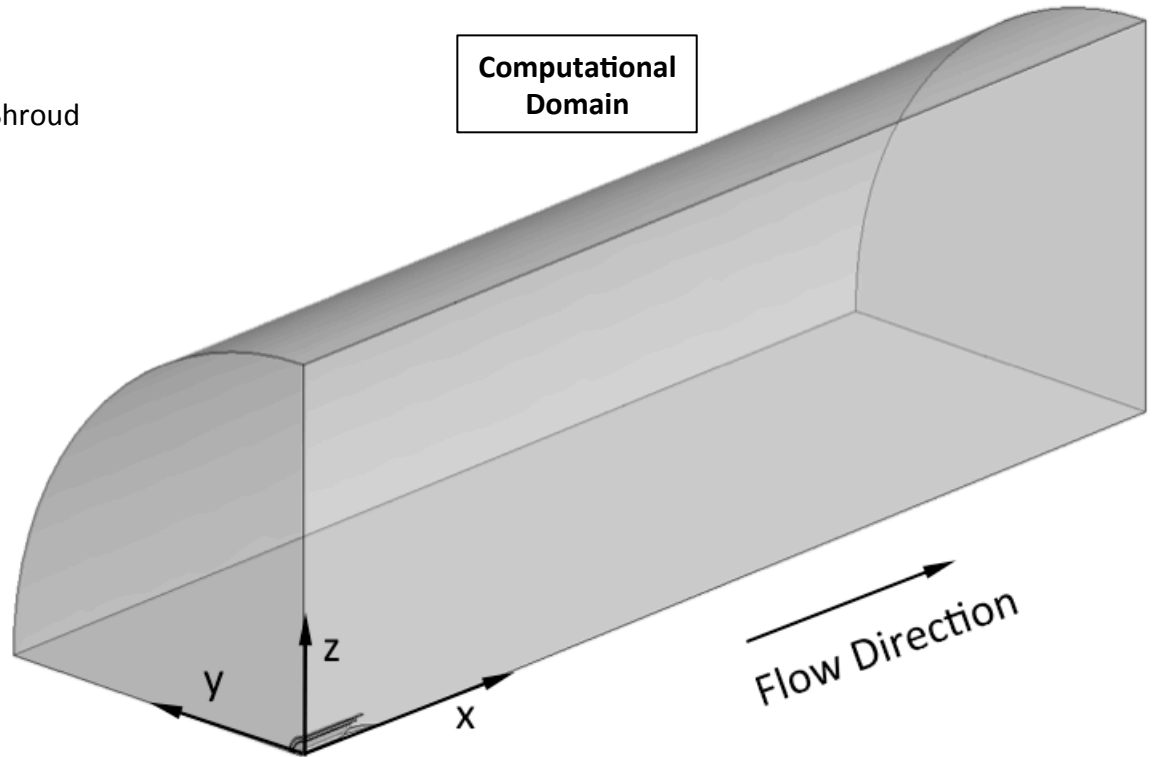


Problem Definition

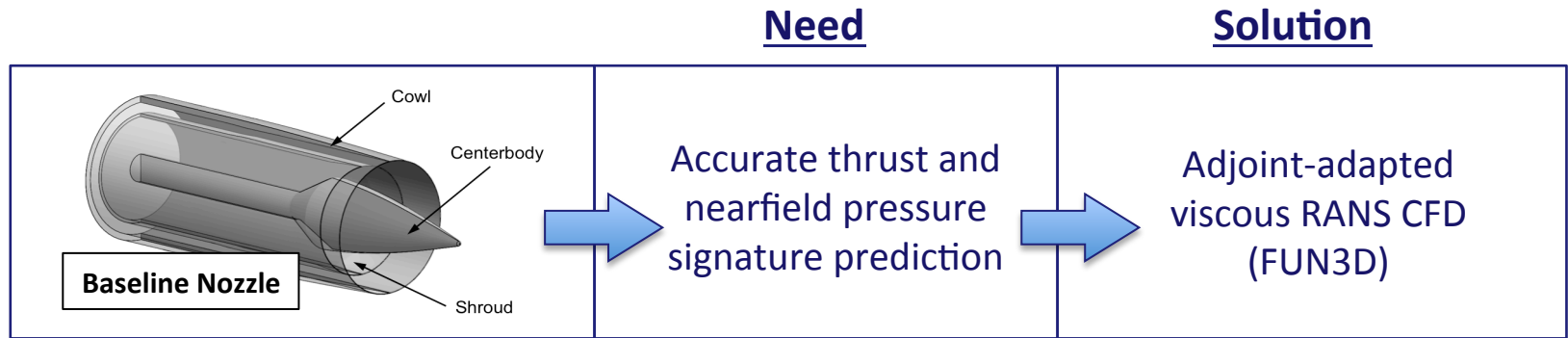
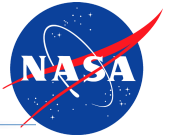


**Optimized @ Design Pt.
45,000-ft std. day**

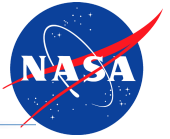
- Mach # = 1.6
- $NPR_{Core} = 6.19$
- $NPR_{Bypass} = 3.24$

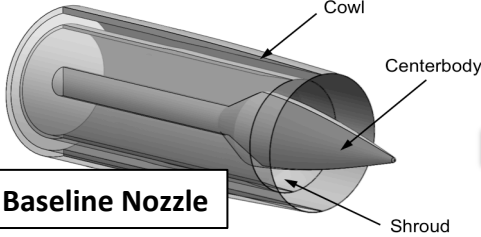



Solution Summary

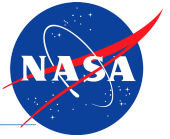


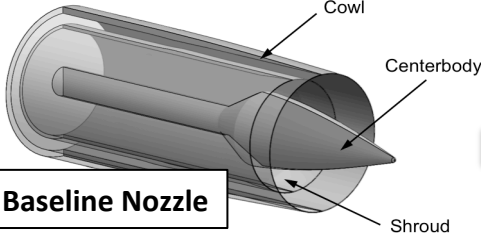

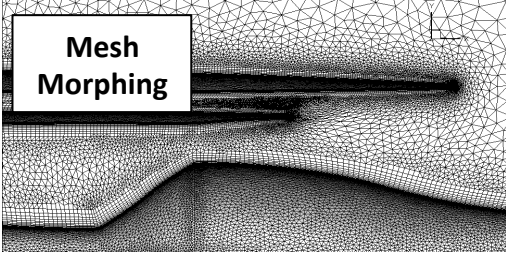
Solution Summary



	<u>Need</u>	<u>Solution</u>
 <p>Baseline Nozzle</p>	Accurate thrust and nearfield pressure signature prediction	Adjoint-adapted viscous RANS CFD (FUN3D)
 <p>Nozzle Surface Deformation</p>	Flexible discrete surface geometry parameterization capability	Axisymmetric free-form deformation based on cubic B-spline interpolants

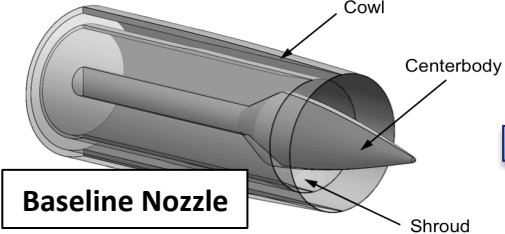

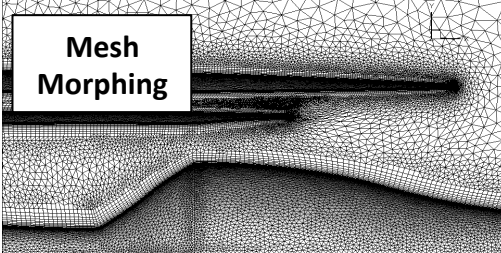
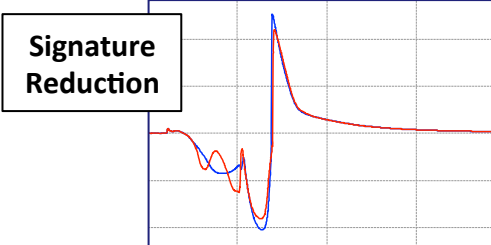
Solution Summary



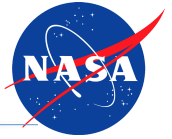
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 <p>Mesh Morphing</p>	Volume grid deformation capability	Solve analogous linear elasticity problem (FUN3D)

Solution Summary

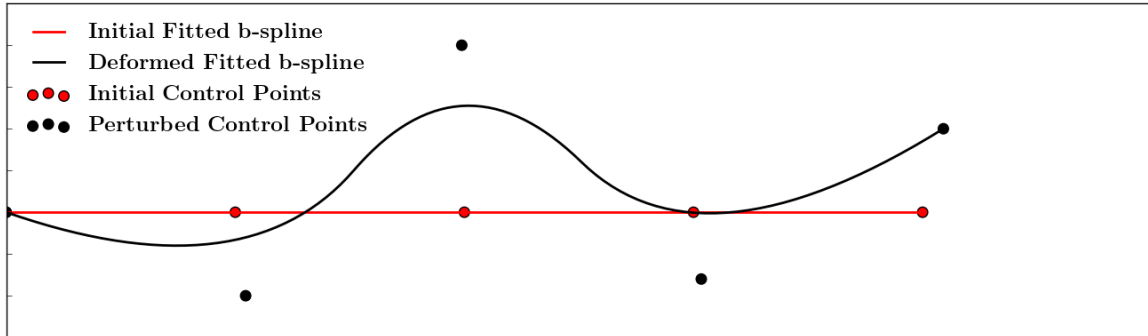


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 <p>Mesh Morphing</p>	Volume grid deformation capability	Solve analogous linear elasticity problem (FUN3D)
 <p>Signature Reduction</p>	Minimize nozzle-induced nearfield pressure disturbances	Gradient-based aerodynamic shape optimization (SNOPT)

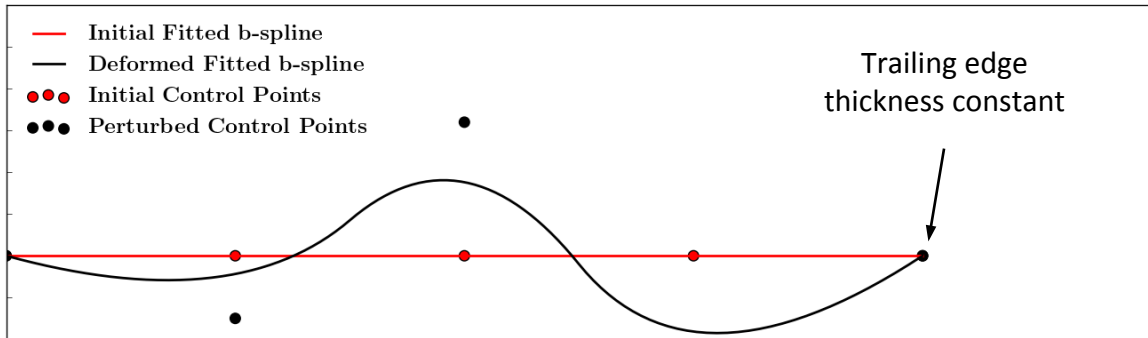
Cowl & Shroud Parameterization



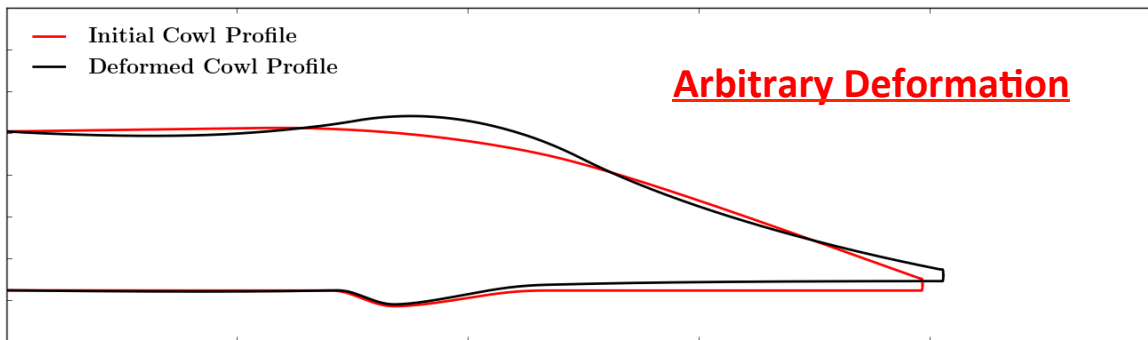
Cowl Centerline Control B-Spline



Cowl Thickness Control B-Spline



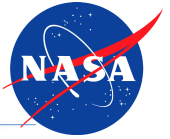
Initial and Deformed Cowl Shape



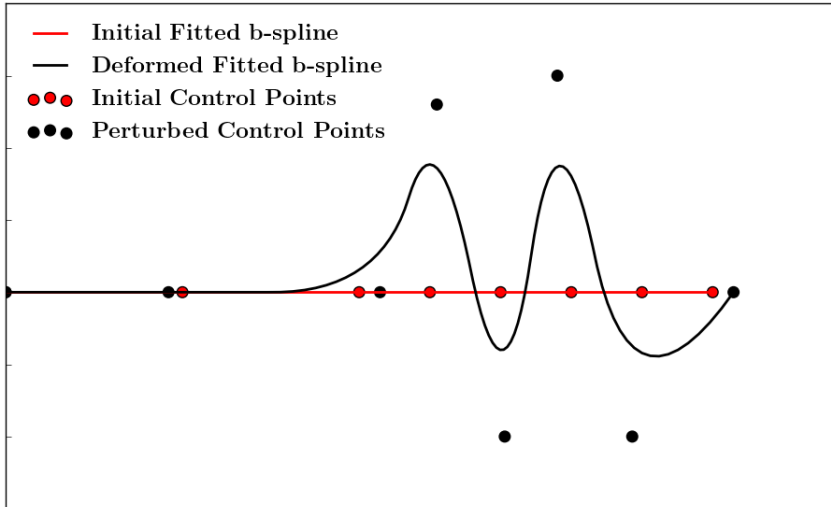
- Annular bodies of revolution
- Characterized by inner and outer surfaces
- Centerline spline (radial & axial DOF)
- Thickness spline (thickness DOF)

Core and bypass entrance flow areas held constant for engine integration

Centerbody Parameterization



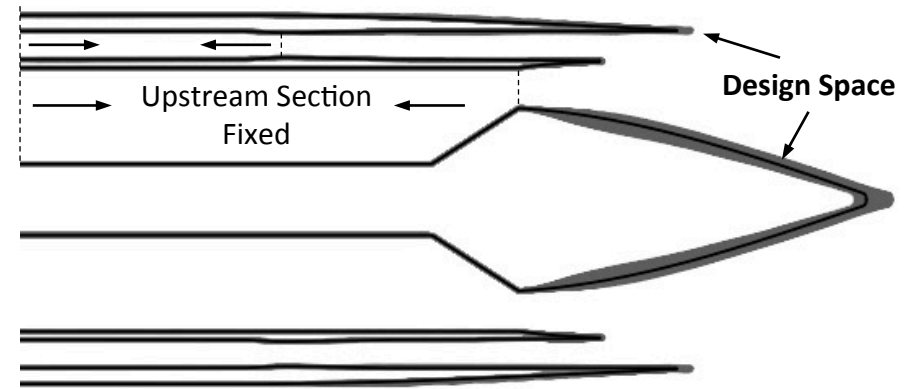
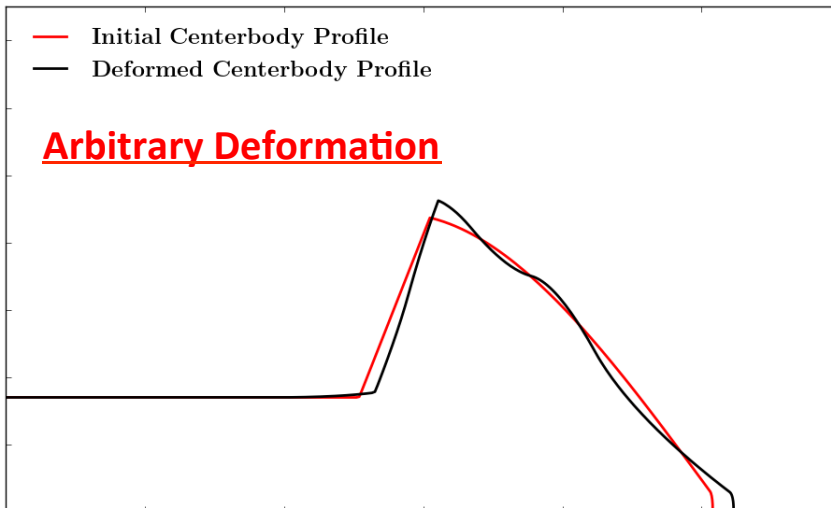
Centerbody Control B-Spline



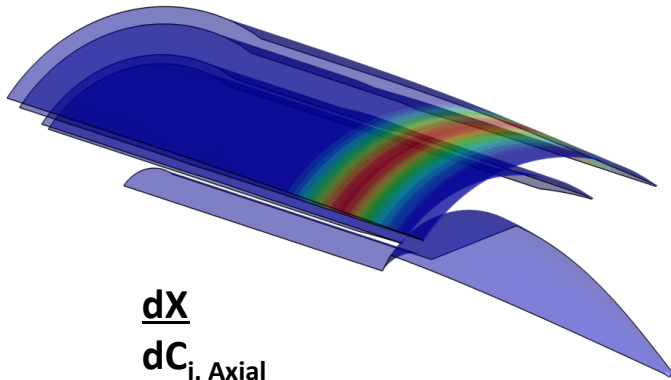
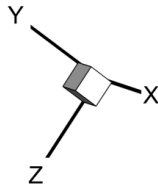
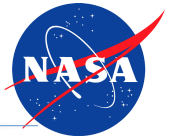
- Closed solid bodies of revolution
- Thickness spline (thickness and axial DOF)

Geometric variable bounds used to constrain core and bypass sections upstream of throats. Constant mass flow rate and thrust.

Initial and Deformed Centerbody Shape

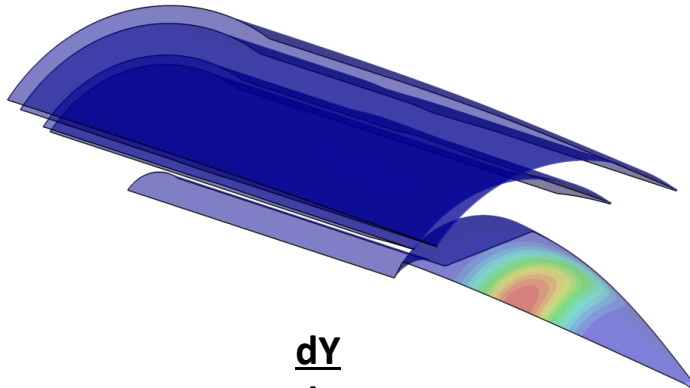


Direct Geometric and Surface Grid Sensitivities



$\frac{dX}{dC_{i, Axial}}$

B-spline interpolants enabled the computation of native analytic derivatives. Continuous sensitivities mapped to the discrete grid coordinates and provided to Fun3D.

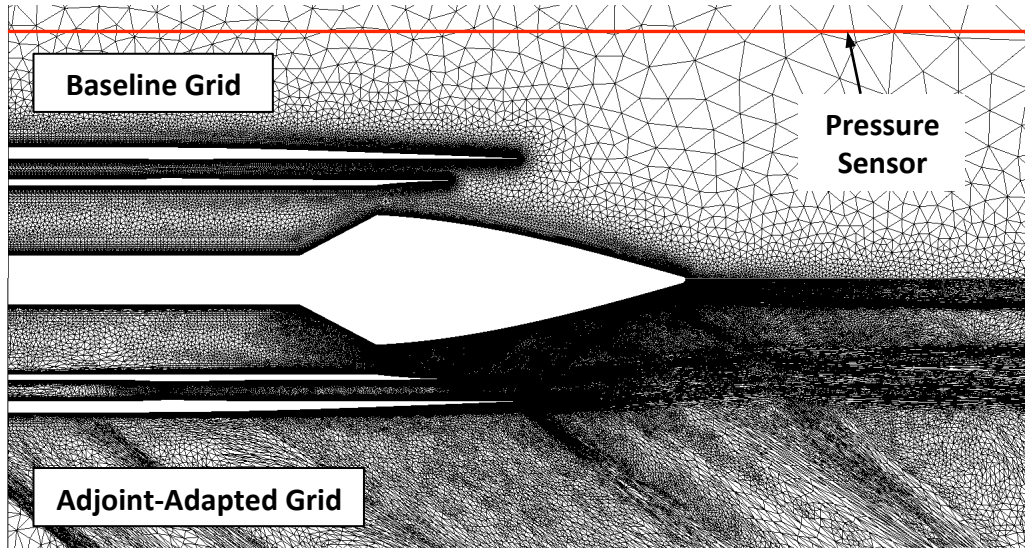
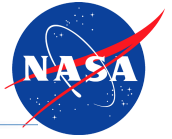


$\frac{dY}{dP_{i, Radial}}$

Derivatives transformed to Cartesian coordinates and provided with respect to control point axial, radial, and thickness degrees of freedom

Derivatives verified using finite difference and complex step

Adjoint-Based Grid Refinement

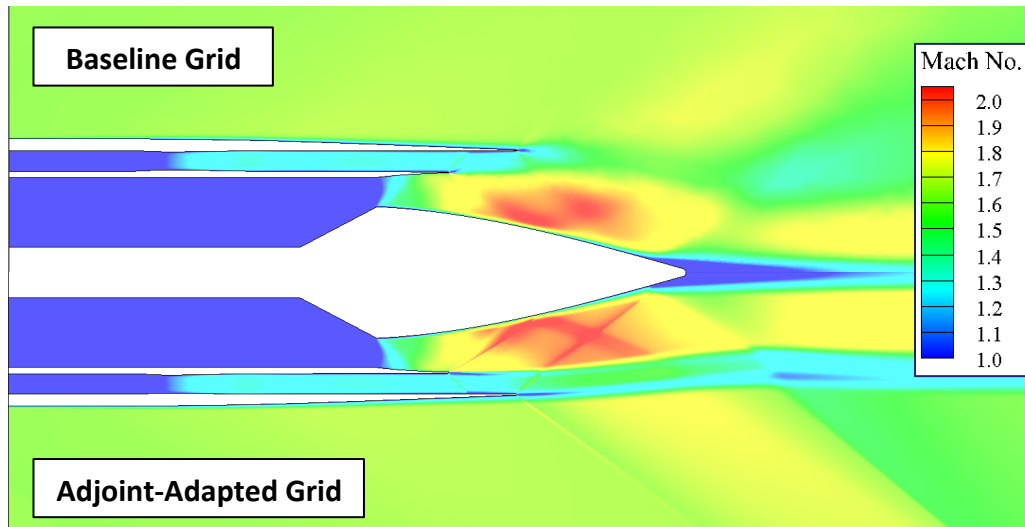


Baseline Grid:

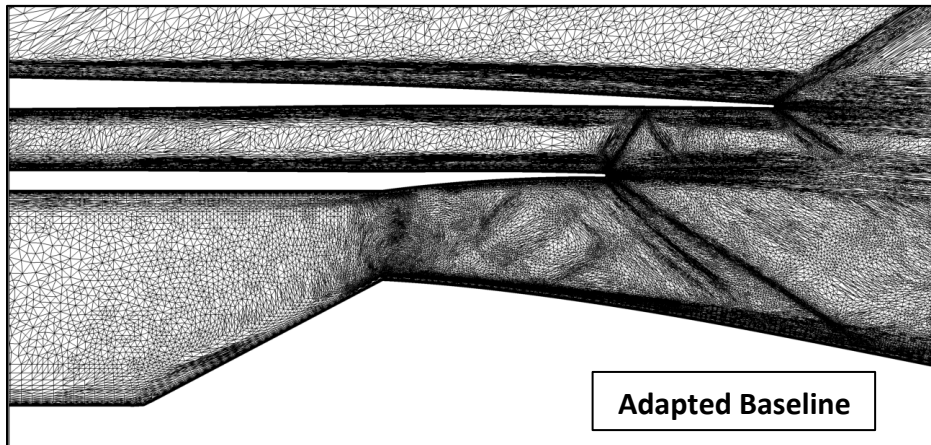
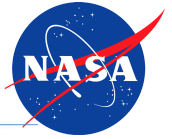
- ~3.5 million nodes
- Fully unstructured 2-D and 3-D T-rex viscous grid transitioning to isotropic tets in farfield ($y^+ < 1$)

Adjoint-Adapted Grid:

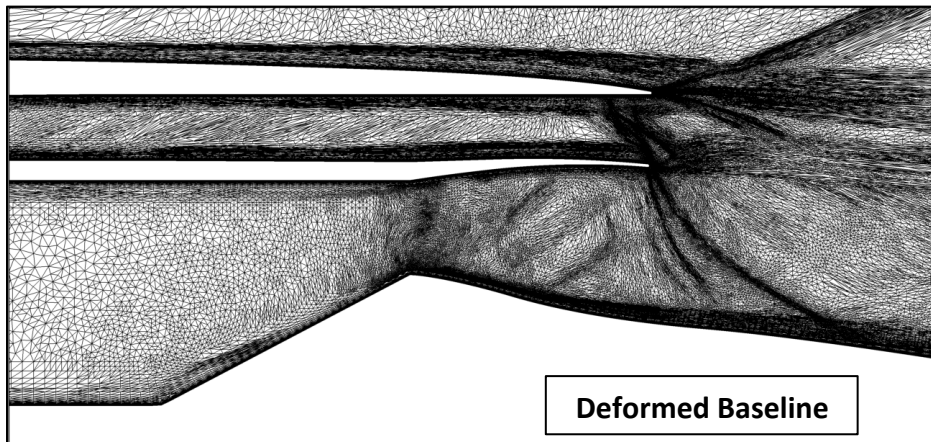
- Adapted to minimize discretization error of pressure integral extracted one nozzle diameter from centerline
- 8 flow/adjoint adaptation cycles
- ~11.5 million nodes
- Constraints used to control maximum anisotropy and grid size during adaptation
- Consumed ~36-hrs on 600 cores



Volume Mesh Morphing



Large Arbitrary Deformation

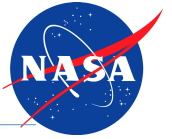


Large deformations compromise grid resolution of critical flow features and require re-adaptation

Surface deformations transferred to the volume using a linear elastic approach

- Young's Modulus inversely proportional to distance from nearest wall boundary.
- Poisson's ratio set uniformly to 0.
- Relatively robust for surface-normal deformations on isotropic grids.
- Less effective for high shear deformations on adapted anisotropic grids.
- Frequent interruption of design optimization process with formation of negative volume cells during deformation step.
- Grid quality deterioration over subsequent deformation steps.

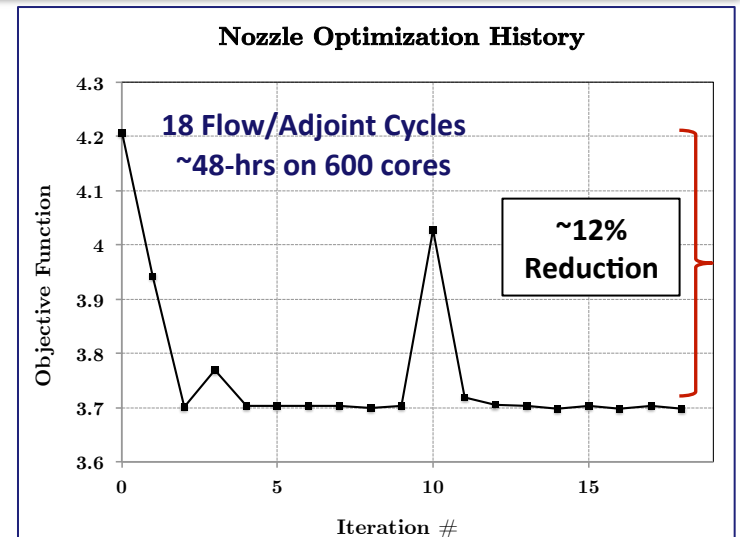
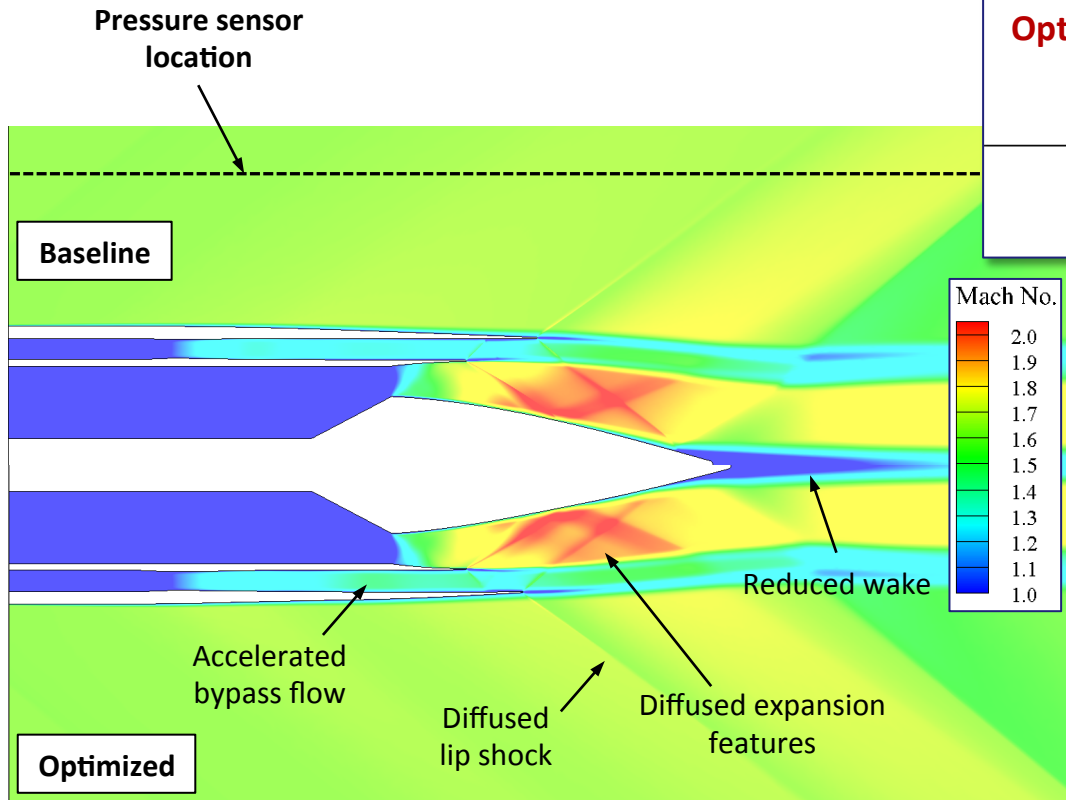
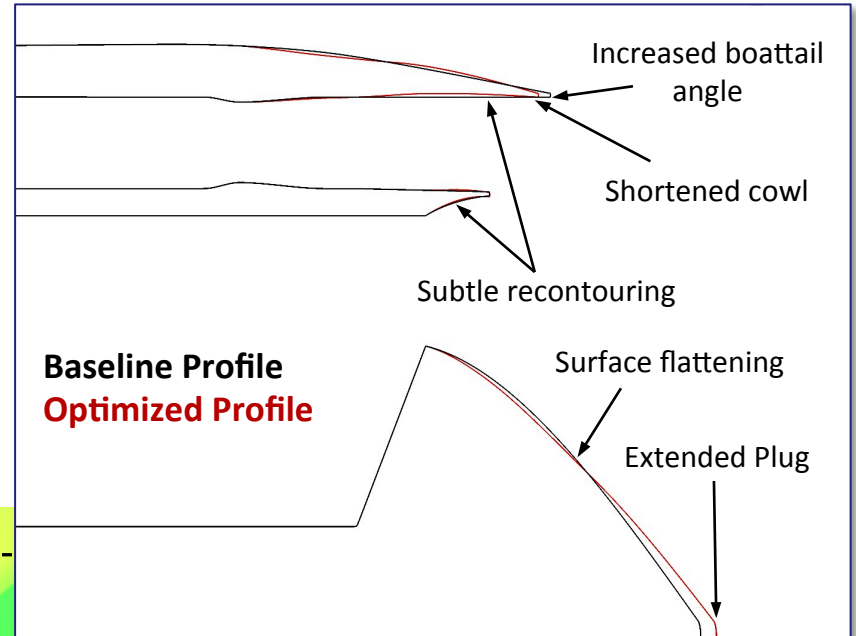
Adjoint-Based Design Optimization



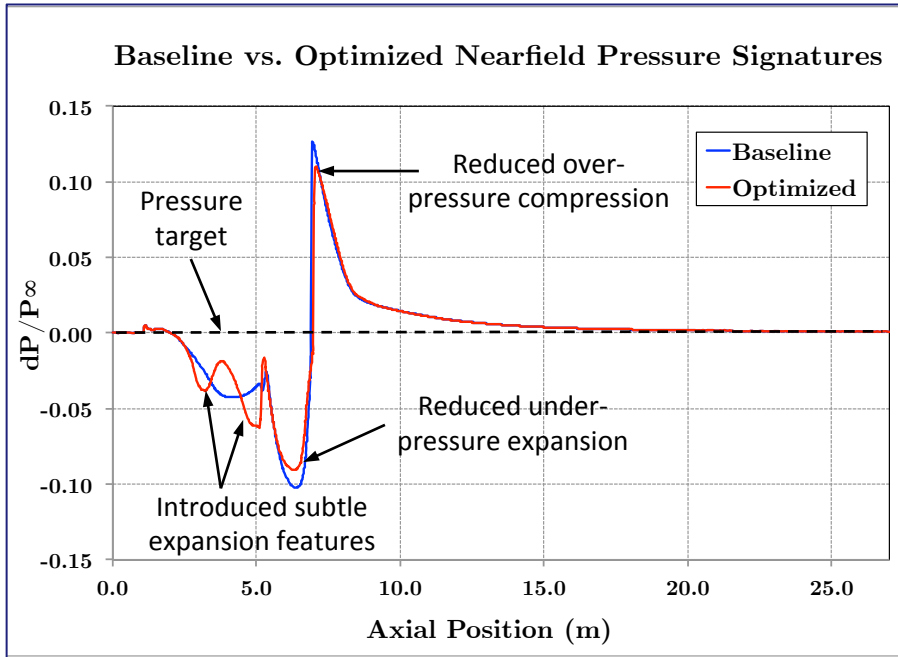
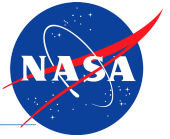
Minimize:

$$f = \sum_{i=1}^N \left(\frac{p}{p_{\infty}} \Big|_i - \frac{p}{p_{\infty}} \Big|_i^* \right)^2$$

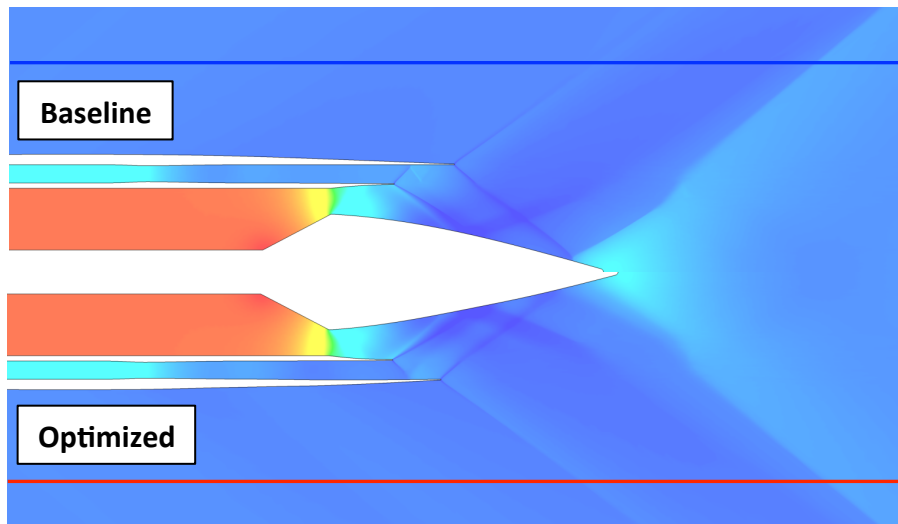
Local pressure ratio Target pressure ratio



Adjoint-Based Design Optimization



Component	Thrust (N) Baseline	Δ Thrust (N) Optimized
Bypass Inflow	26478	+5
Core Inflow	96228	-10
Inner Cowl	-1347	-10
Outer Cowl	-1525	-27
Inner Shroud	1505	+31
Outer Shroud	-1158	-32
Centerbody	-32121	+207
Total	88059	+175



~0.2% Thrust Increase



Aerodynamic shape optimization demonstrated for
dual-stream supersonic plug nozzle to minimize
nearfield pressure waveforms

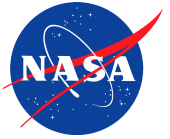
Conclusions



Intent is to optimize propulsive streamtube & reduce plume effects on overall aircraft pressure signature

Could be used in conjunction with airframe shape optimization

Conclusions



New axisymmetric geometry parameterization
developed using 3rd order B-splines and integrated
with FUN3D design optimization framework

Conclusions



Achieved notable reductions in over- and under-pressure disturbances measured one diameter from nozzle centerline

Conclusions



No compromise to nozzle performance
requirement on thrust during optimization

Future Work



- New adjoint thrust derivatives, allowing mass flow rates and thrust to be constrained at optimizer level
- Open geometric bounds on control points to enable greater geometric flexibility upstream of core & bypass throats (trade pressure & viscous forces)
- Consider propagated effects to ground observer
- Investigate alternate volume grid deformation approaches to minimize production of negative volume cells
- Consider B-spline surface-based parameterization for extension to non-axisymmetric engine components
- Opportunity for aggregate objective function including plug volume as a surrogate for nozzle weight
- Preliminary studies indicate ~30% reduction in nozzle pressure disturbance possible with ~4% thrust gain by varying BPR (engine cycle/nozzle coupling)

Acknowledgements



NASA High Speed Project

Jonathan Seidel, Raymond Castner and Nicholas Georgiadis

