

Jan. 5, 2020 at SciTech Forum 2020, Orlando, Florida

Far-field Waveform Prediction by JAXA

Masashi Kanamori, Yusuke Naka and Yoshikazu Makino
Japan Aerospace Exploration Agency



Outline

- ✓ Introduction of Numerical Prediction Tool of Sonic Boom Waveform

- ✓ Case 1, Required
 - ✓ C25P, a powered equivalent of the NASA C25D

- ✓ Case 2, Required
 - ✓ C609, an earlier version of X-59

- ✓ Case 1, Optional
 - ✓ C25P, a powered equivalent of the NASA C25D
 - ✓ Focus case for level acceleration

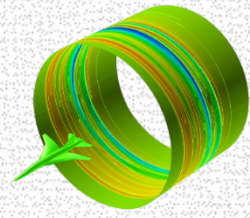


Numerical Simulation
Research Unit

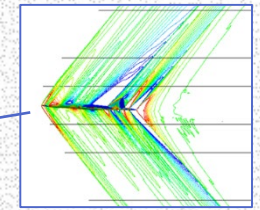


JAXA's Boom Prediction Tools

MPnoise
multipole analysis tool



UPACS/JTAS/FaSTAR
CFD analysis tools

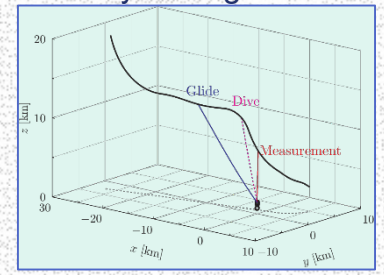


aircraft

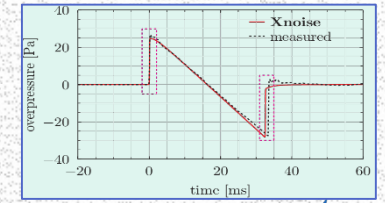
flight path

ray

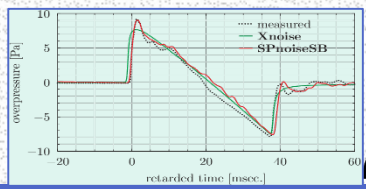
IntegRay
ray tracing tool



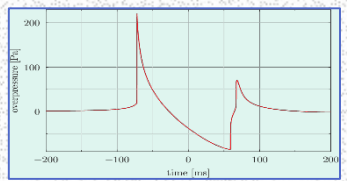
Xnoise
farfield signature prediction tool



SPnoise for Sonic Boom
atmospheric turbulence effect prediction tool



FFnoise
focus boom prediction tool



Isopemp

Atmospheric B.L.

Caustic

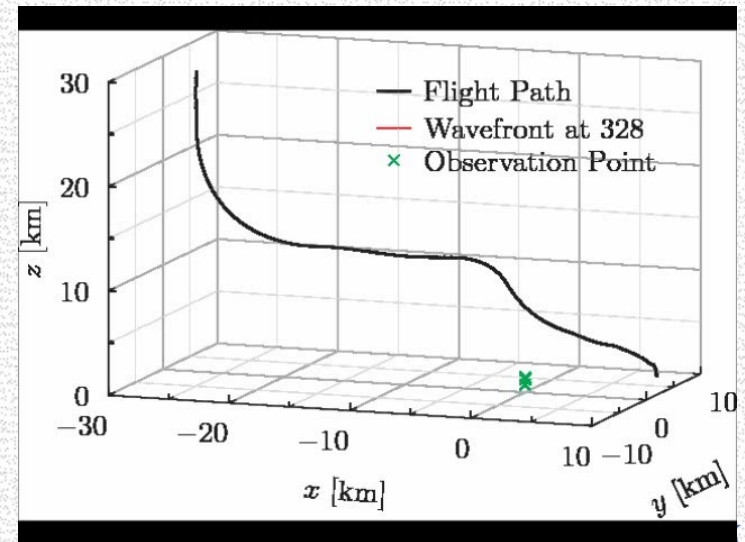
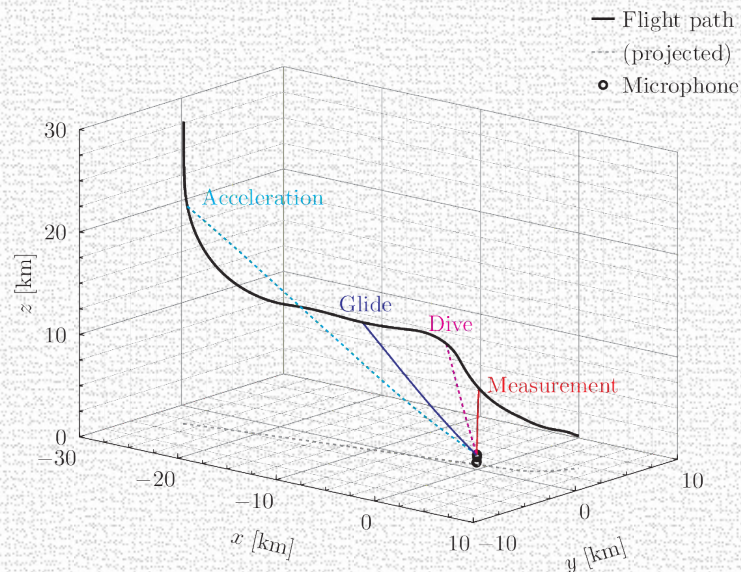
ground

BoomMetre
Noise metric calculation tool



IntegRay – Raypath Integration Tool –

- ✓ calculates acoustical rays by integrating ray path equation
- ✓ has several functionalities:
 - ✓ calculating raypaths, wavefront and caustic
 - ✓ specifying the origin of sound
- ◆ Application to D-SEND#2 flight test
 - eight rays reached to the microphone (Bottom left)
 - progression of wavefront is also shown (Bottom right)



Kanamori et al., AIAA J., vol.56, No.7, pp.2743—2755

Xnoise – Nonlinear Propagation Analysis Tool –

- ✓ solves augmented Burgers equation shown below (Cleveland *et al*, 1995)
- ✓ simulates acoustical effects including nonlinearity, attenuation and dispersion.
- ✓ validated with measurements of D-SEND#1 flight test
 - ◆ Application to D-SEND#1 flight test
 - both *N* wave and flattop signature were tried
 - fairly good agreement was achieved including rise time

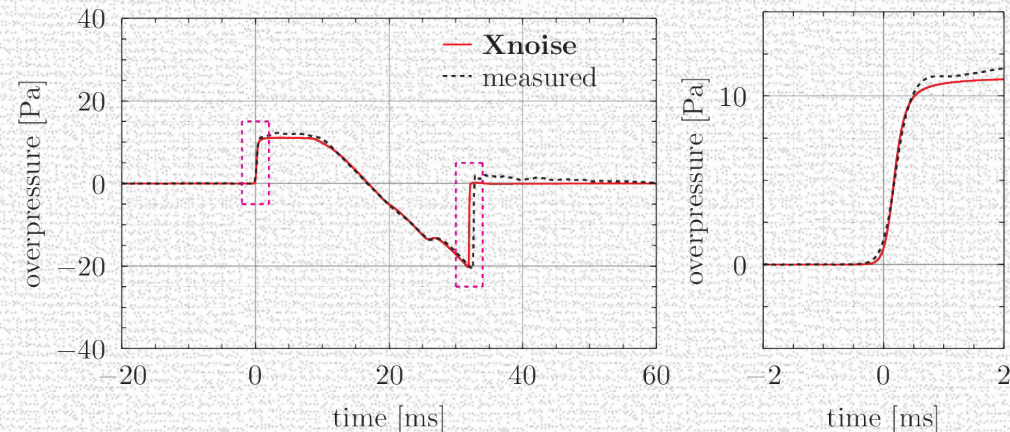
$$\frac{\partial p}{\partial s} = \frac{\beta}{2\rho_0 c_0^3} \frac{\partial p^2}{\partial \tau} \quad : \text{Nonlinearity}$$

$$-\frac{1}{2B} \frac{\partial B}{\partial s} p \quad : \text{Blokhintsev Energy Conservation}$$

$$+\frac{\delta}{2c_0^3} \frac{\partial^2 p}{\partial \tau^2} \quad : \text{Thermo-Viscous Effect}$$

$$+\sum_v \frac{(\Delta c)_v \tau_v}{c_0^2} \left(1 + \tau_v \frac{\partial}{\partial \tau}\right)^{-1} \frac{\partial^2 p}{\partial \tau^2}$$

: Molecular Relaxation Effect

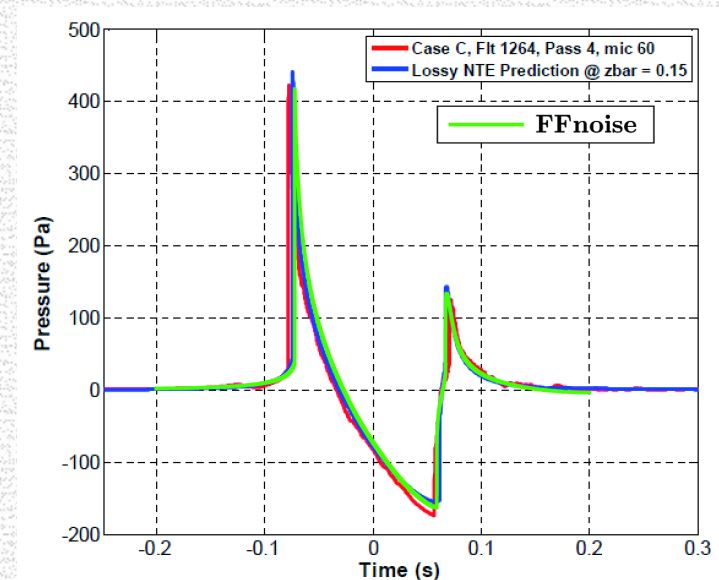


Kanamori et al., AIAA J., vol.56, No.7, pp.2743—2755

FFnoise – Focusing Prediction Tool –

- ✓ solves lossy nonlinear Tricomi equation (Salamone *et al*, 2013)
- ✓ achieves highly accurate predictions with a remarkable speed of computation by combining a splitting scheme and multigrid-like acceleration
- ✓ validated with measurements of SCAMP flight test by NASA
 - ◆ Application to SCAMP flight test
 - focusing of incoming N wave was clearly reproduced

$$\begin{aligned}
 \frac{\partial^2 P}{\partial Z^2} - Z \frac{\partial^2 P}{\partial \tau^2} &: \text{Diffraction} \\
 + \frac{\mu}{2} \frac{\partial^2 P^2}{\partial \tau^2} &: \text{Nonlinearity} \\
 + \left[\frac{\alpha}{\varepsilon^2} + \sum_{\nu} \frac{\theta_{\nu}/\varepsilon^2}{1 + \tau_{\nu} \partial/\partial \tau} \right] \frac{\partial^3 P}{\partial \tau^3} &: \text{Thermo-viscous \& molecular relaxation} \\
 = 0
 \end{aligned}$$



***BoomMetre* – Loudness Metric Calculation Tool –**

- ✓ calculates
 - ✓ Perceived Level(PL) (Stevens, 1972)
 - ✓ A-weighted Sound Exposure Level(ASEL) (ANSI S1.42-2001, 2001)
 - ✓ B-SEL, C-SEL ...

Case 1, Required:
C25P, a powered equivalent of the NASA C25D

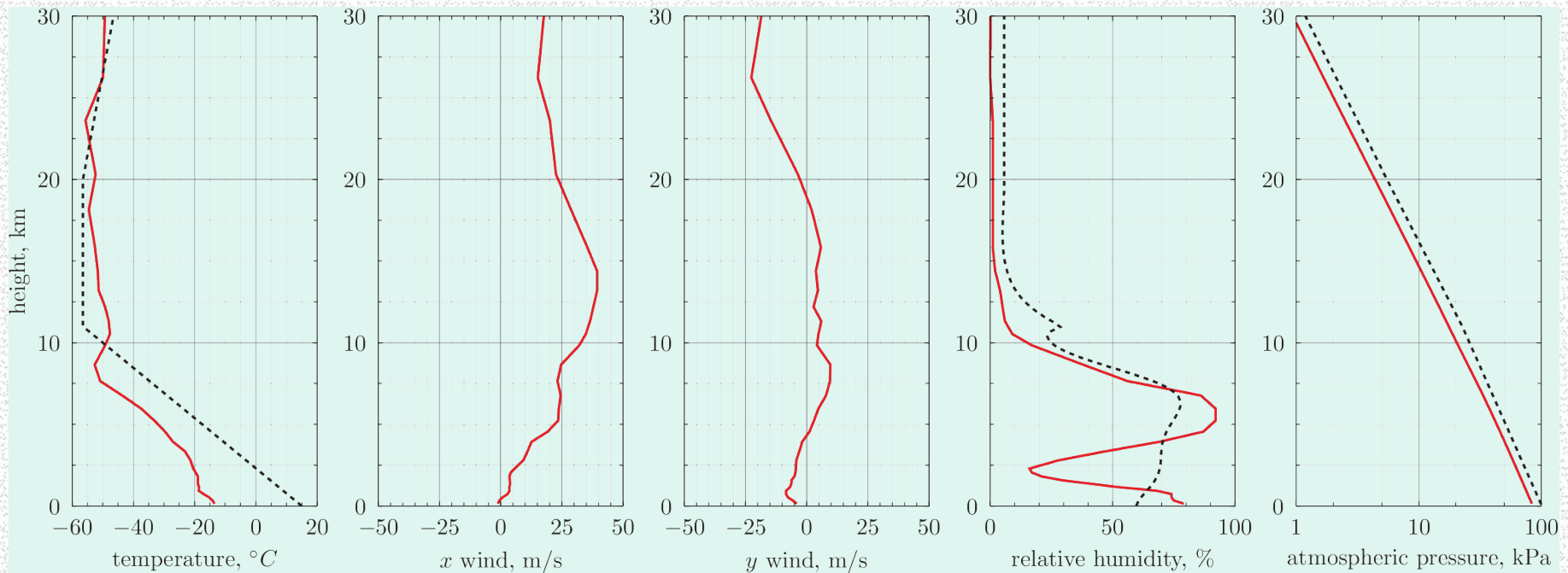
Required Run

1. Use near-field dp/p at all roll angles from -70 to 70 in 10 -degree increments (with 0 being under-track) to predict the ground signatures using the provided atmospheric profile. If a specific azimuthal angle is beyond your computed lateral cut-off, submit $(0.0, 0.0)$ as the ground signature
2. Determine lateral cut-off angles and ground intersection locations on both sides

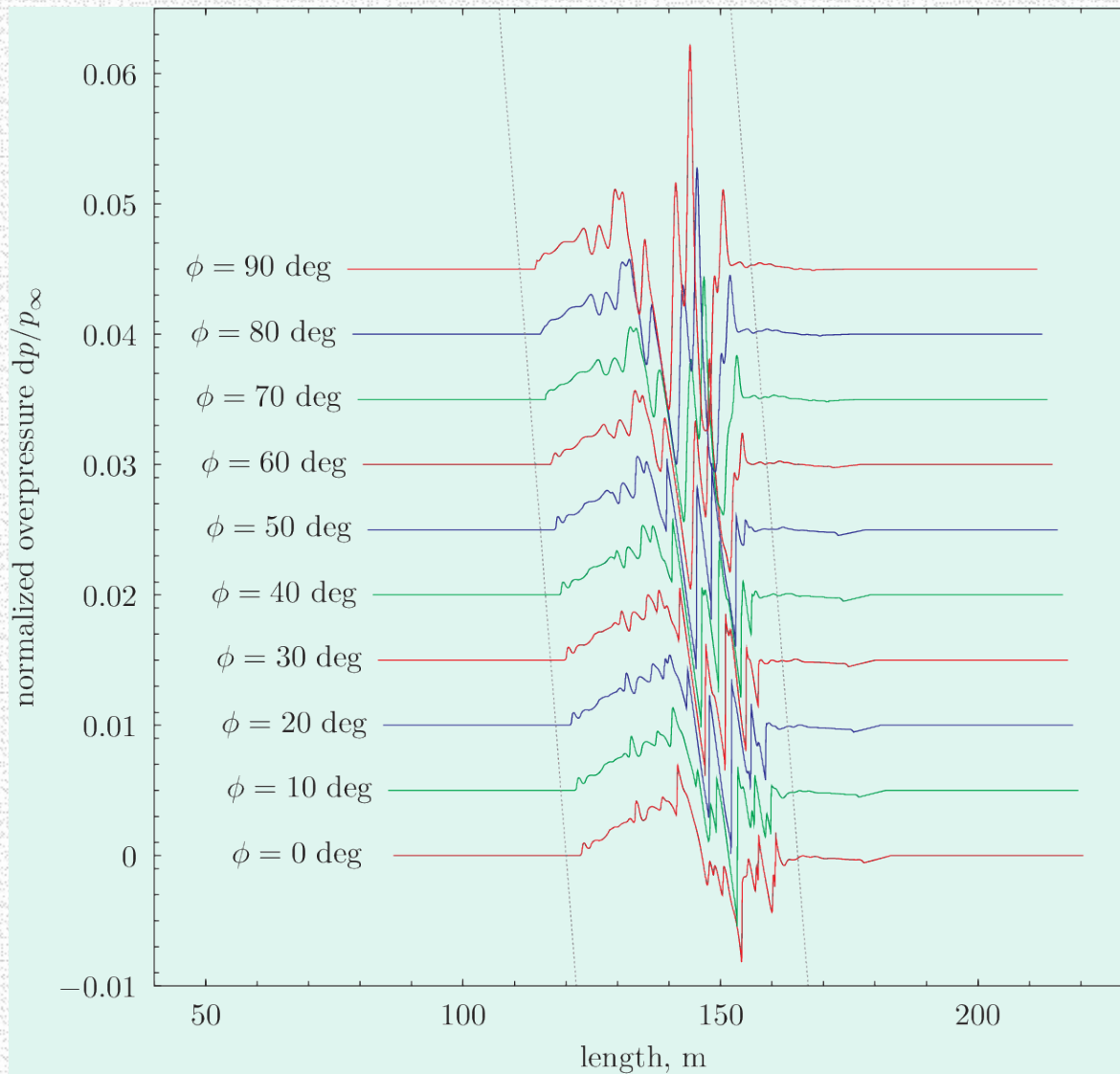
Configuration

Parameters	Values	Unit
Mach number	1.6	-
cruise altitude	15,760.0	m
propagation start distance, R	100.584	m
R/L	3.0	-
ground altitude	264.069	m
ground reflection factor	1.9	-
heading	toward east (x direction)	
role angle	[-70,70] every 10 deg	-

Atmospheric Profiles

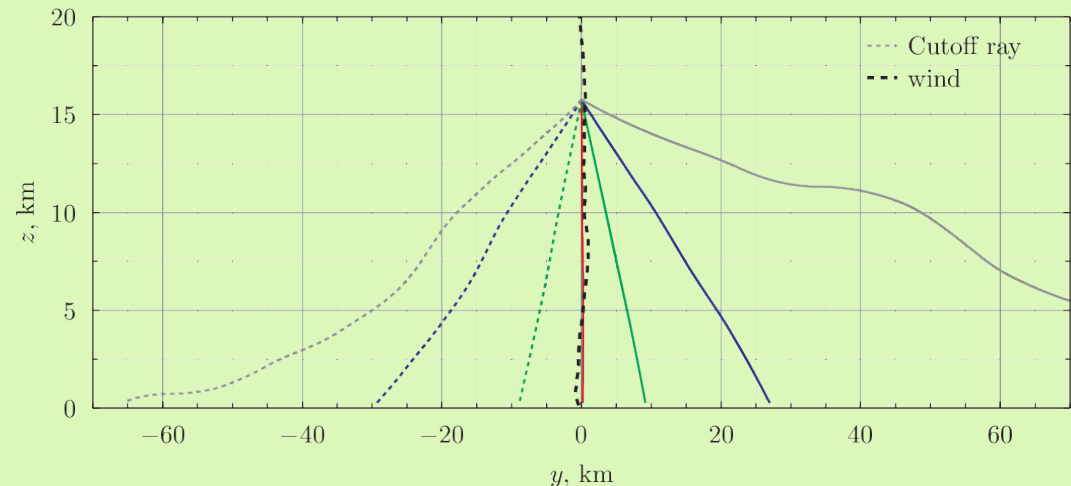
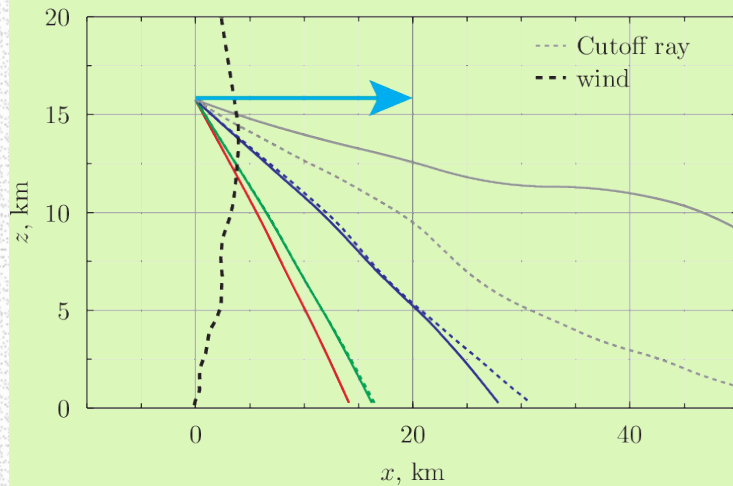
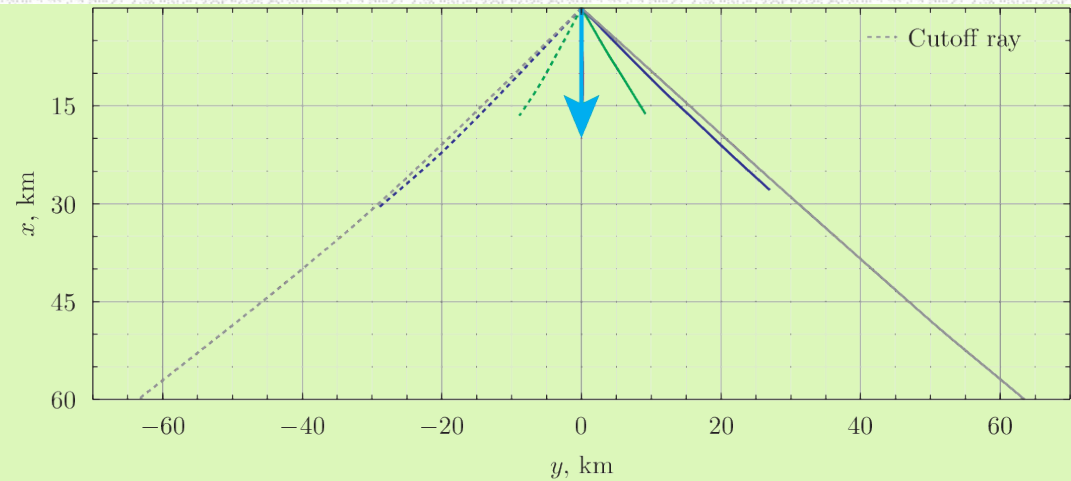


Nearfield (Input) Signature

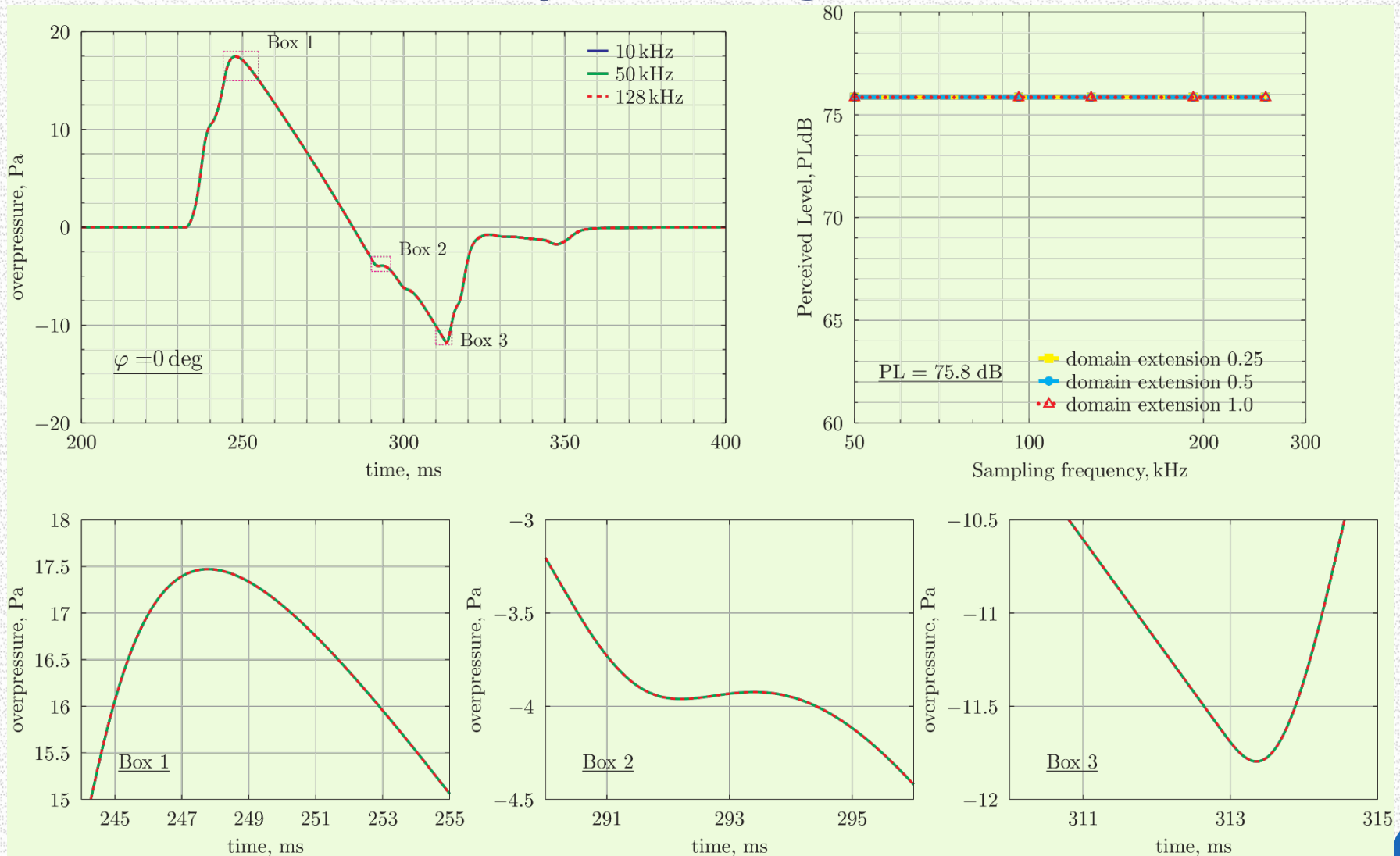


Case 1, Cut-offs and Corresponding Raypaths

Cut-off angle:
 -78.37 deg, 69.01 deg



Case 1, Required, $\varphi = 0$ deg



Case 2, Required: C609, an earlier version of X-59



Numerical Simulation
Research Unit



Required Run

1. For the measured atmospheric profile, use near-field dp/p at the following azimuthal angles to predict the ground signatures. If a specific azimuthal angle is beyond your computed cut-off, submit (0.0, 0.0) as the ground signature
 - i. From -60 to 60 in 10-degree increments (with 0 being under-track)
 - ii. From -70 to -60 in 2-degree increments
 - iii. From 70 to 60 in 2-degree increments

2. For both the standard atmospheric profile and the measured atmospheric profile, determine lateral cut-off angles on both sides

3. Using near-field pressure data as given below, compute ground signatures, ground intersection locations and loudness metrics associated with the lateral cut-off angles computed
 - i. For the measured atmospheric profile, use -70 and 70 degrees from Case2_dpp.plt
 - ii. For the standard atmospheric profile, use -50 and 50 degrees from Case2_dpp.plt

Configuration

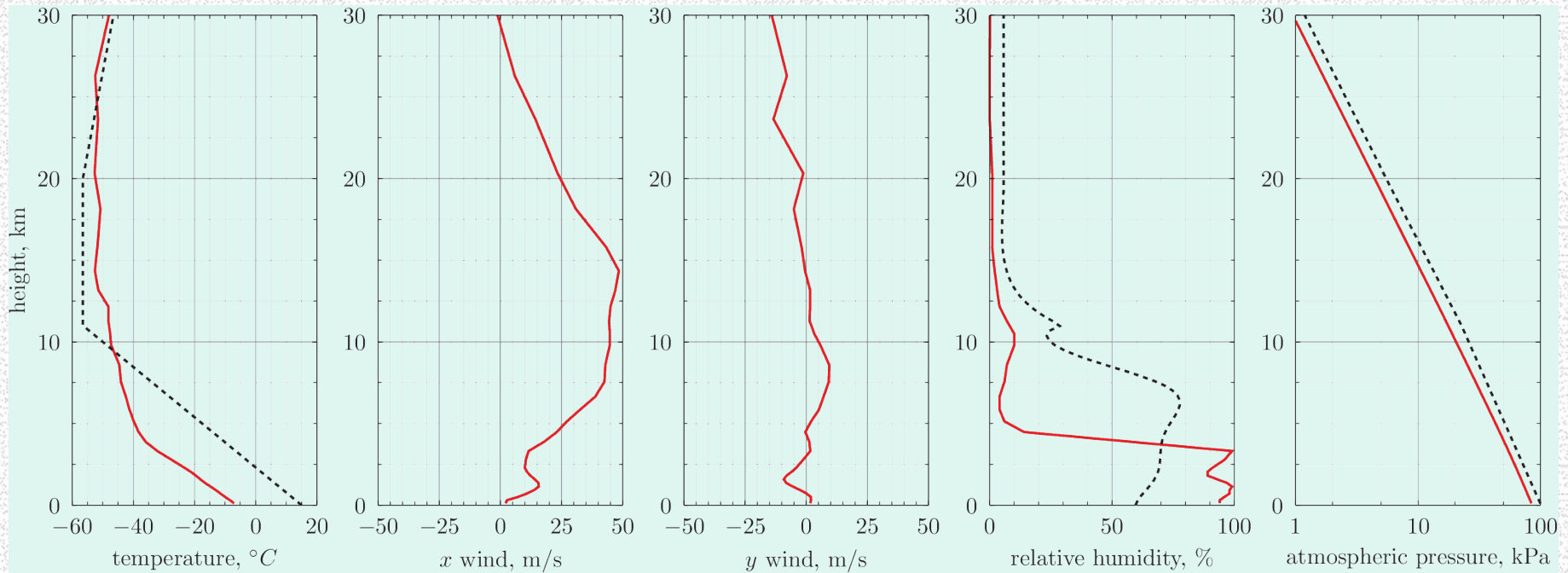
Parameters	Values	Unit
Mach number	1.4	-
cruise altitude	16,459.2	m
propagation start distance, R	82.296	m
R/L	3.0	-
ground altitude	110.011	m
ground reflection factor	1.9	-
heading	toward east (x direction)	-
role angle	[-60, 60] every 10 deg [-70, -60] every 2 deg [60, 70] every 2 deg	-



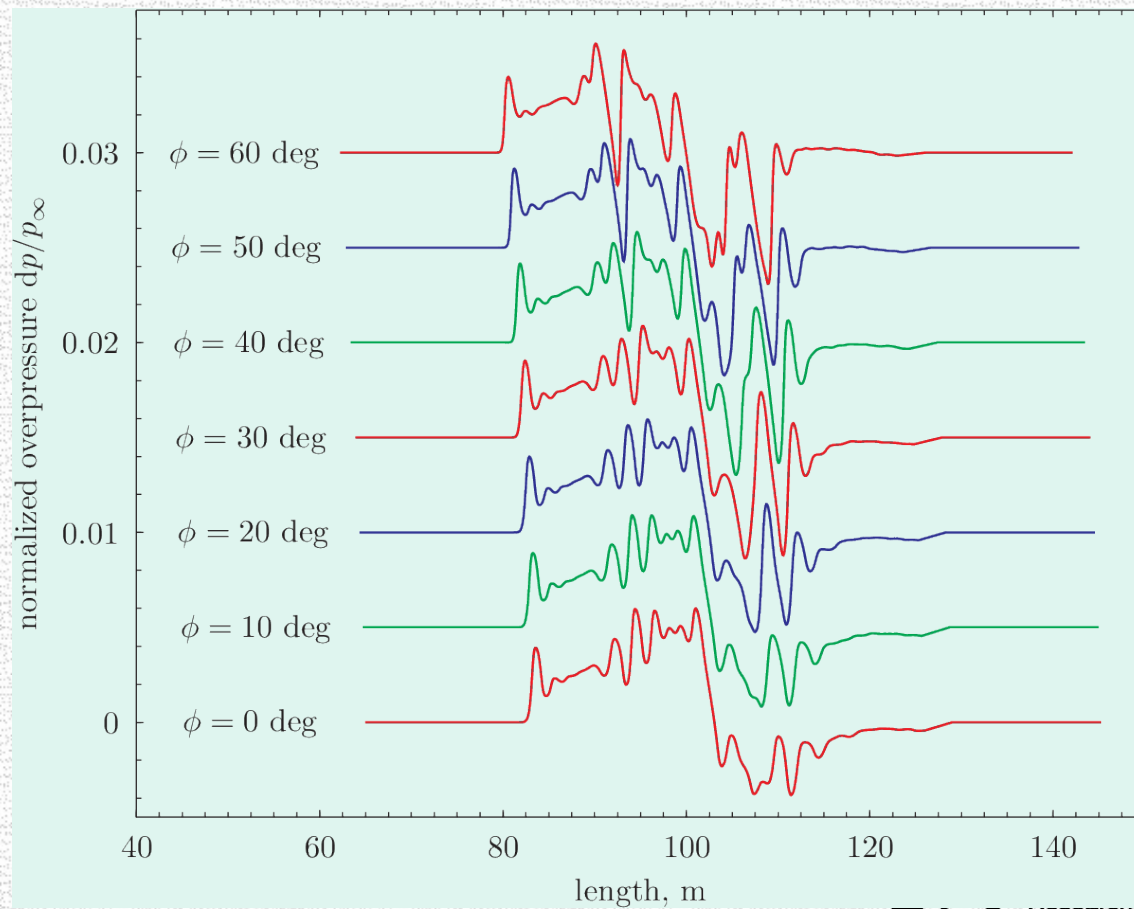
Numerical Simulation
Research Unit



Atmospheric Profiles



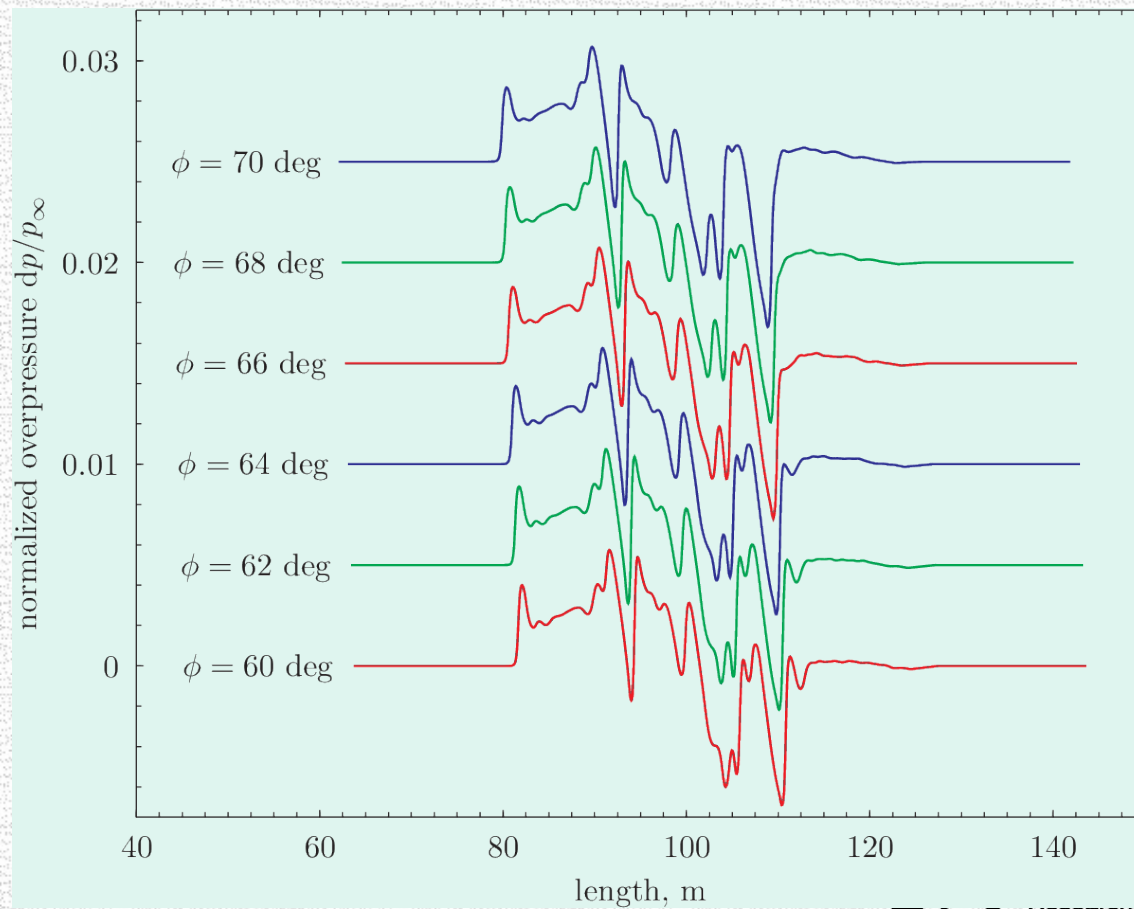
Nearfield (Input) Signatures



Simulation
Jnit



Nearfield (Input) Signatures

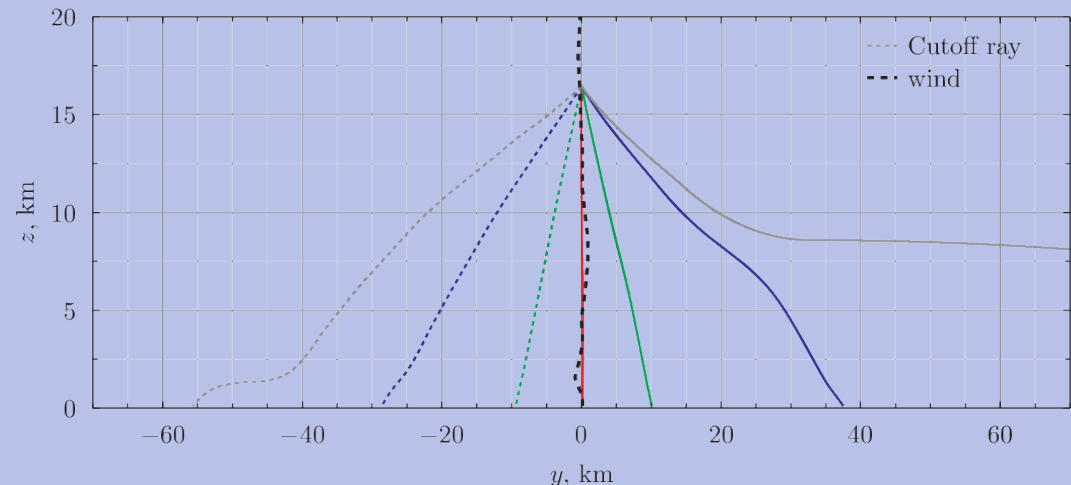
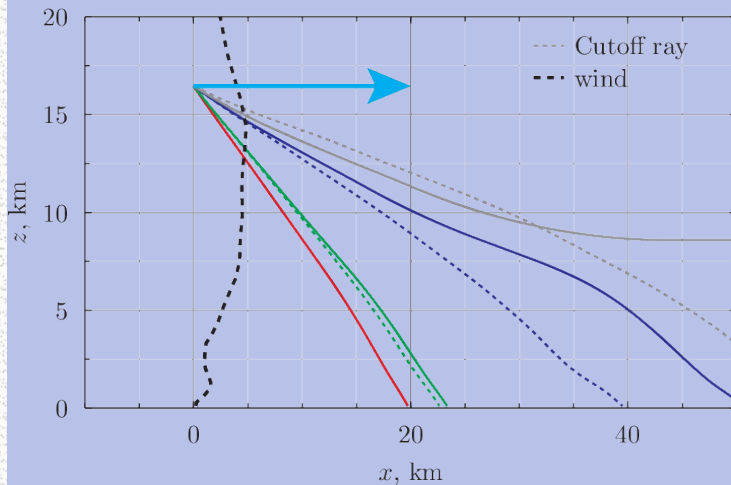
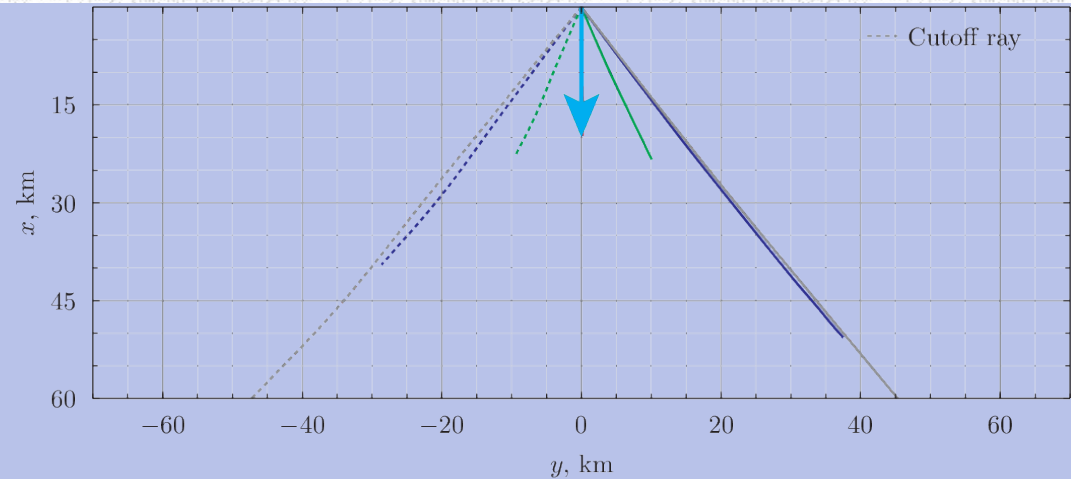


Simulation
Jnit



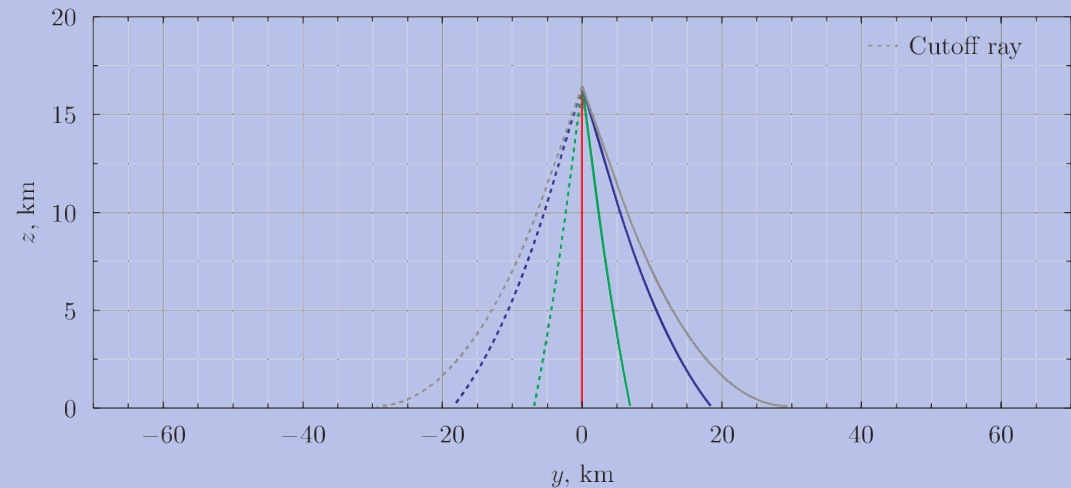
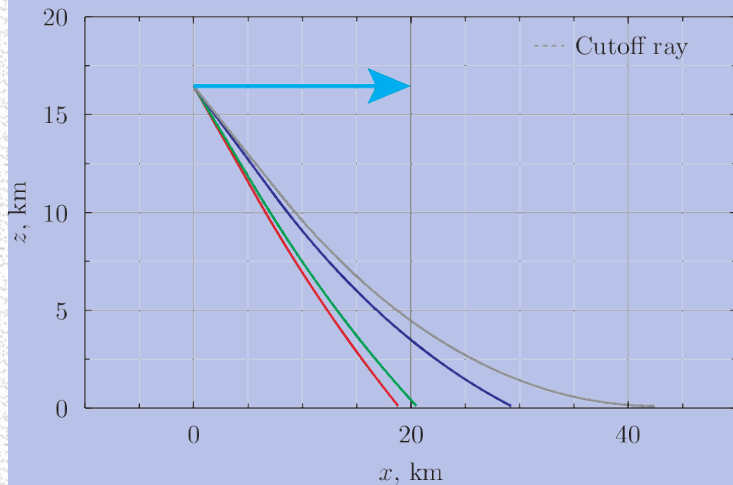
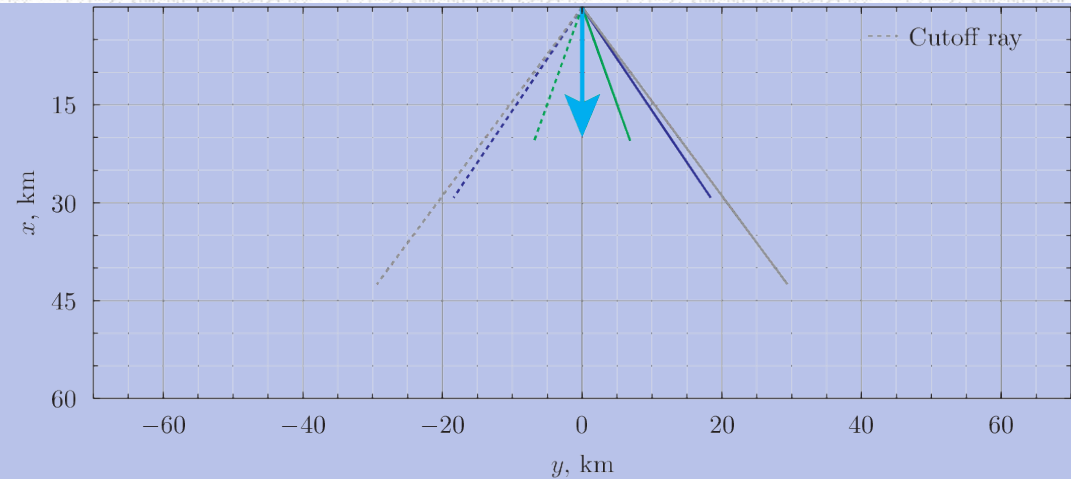
Case 2, Cut-offs for MEASURED Atmos. Profile

Cut-off angle:
 -64.07 deg, 70.49 deg

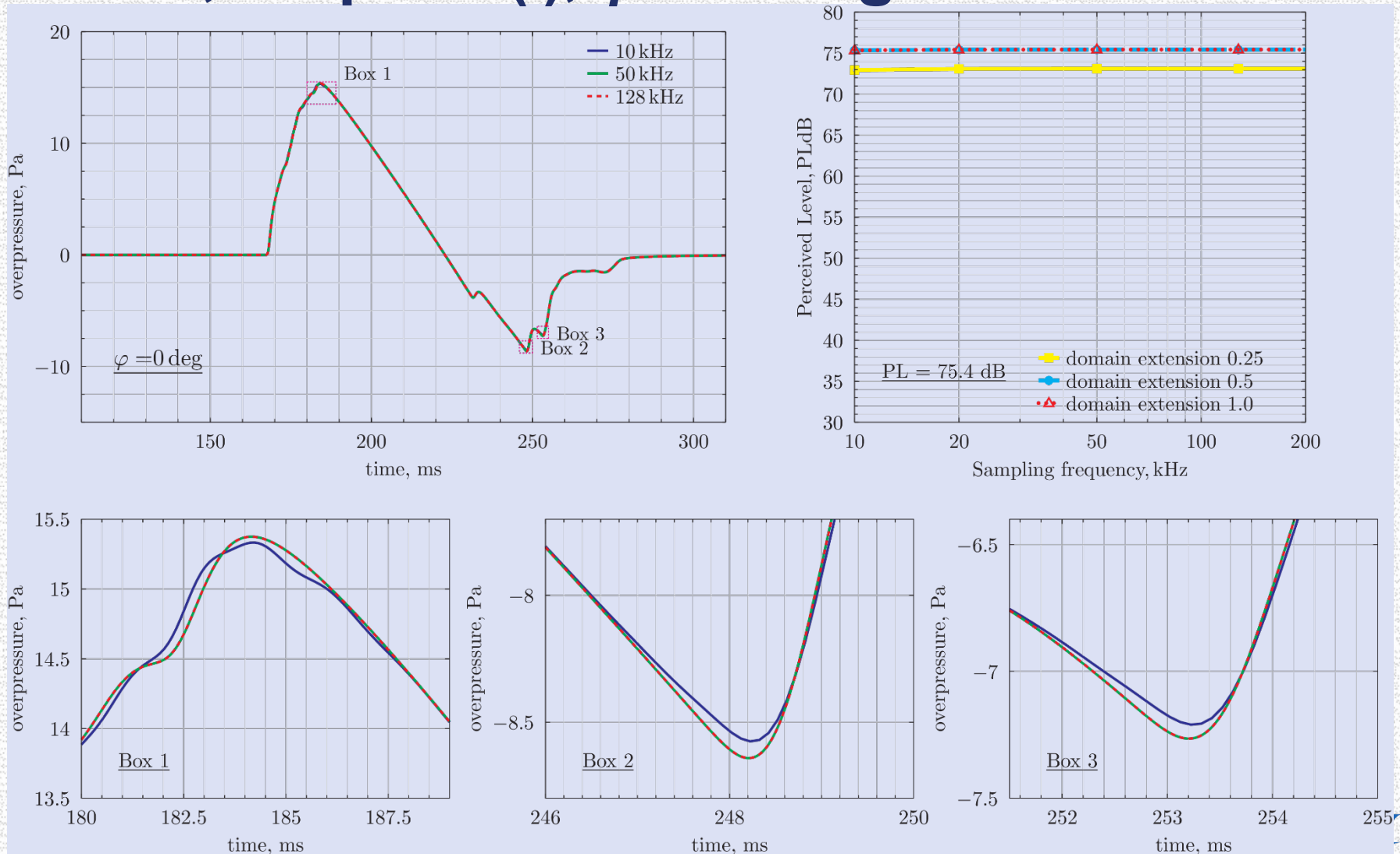


Case 2, Cut-offs for STANDARD Atmos. Profile

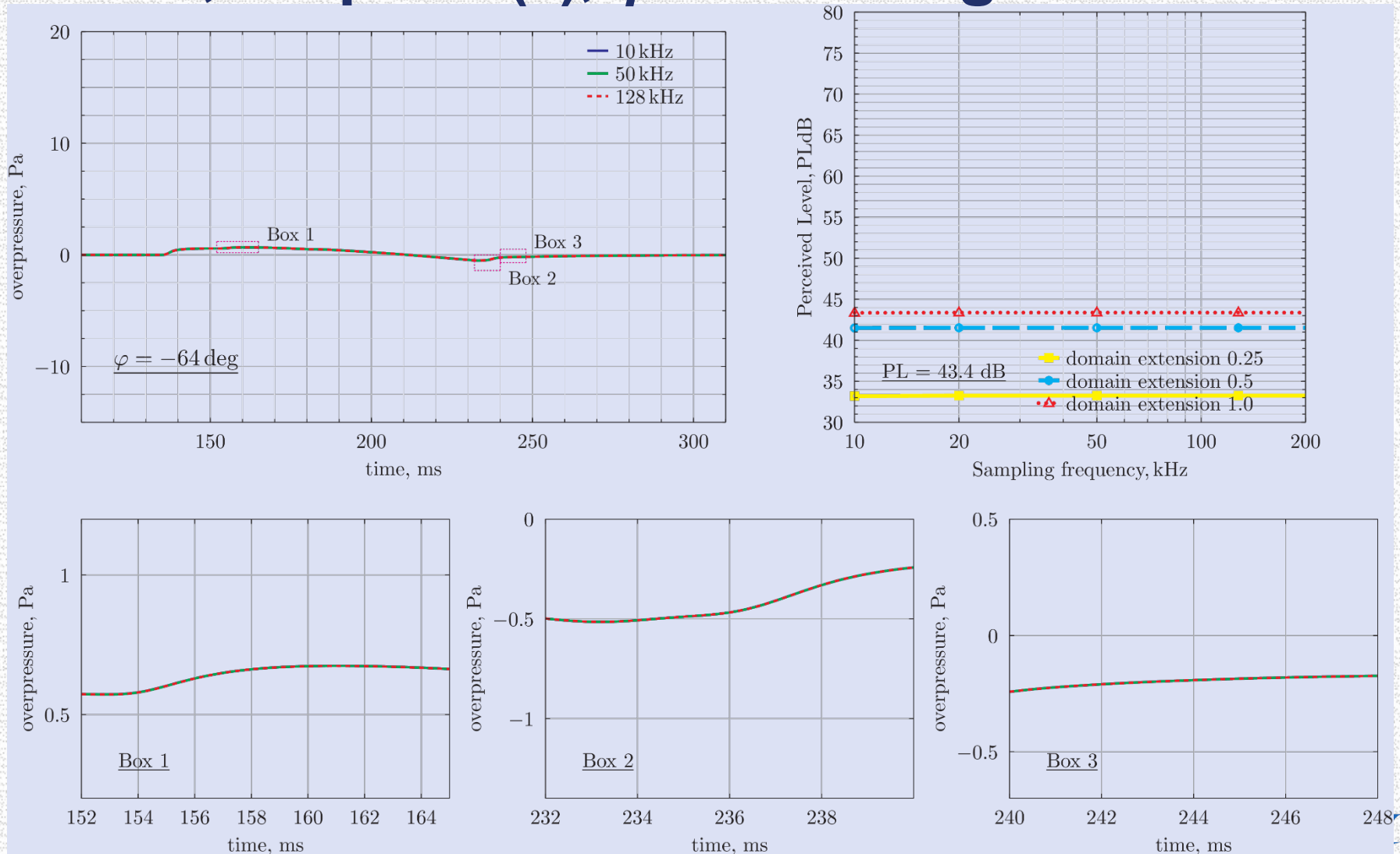
Cut-off angle:
 -44.89 deg, 44.89 deg



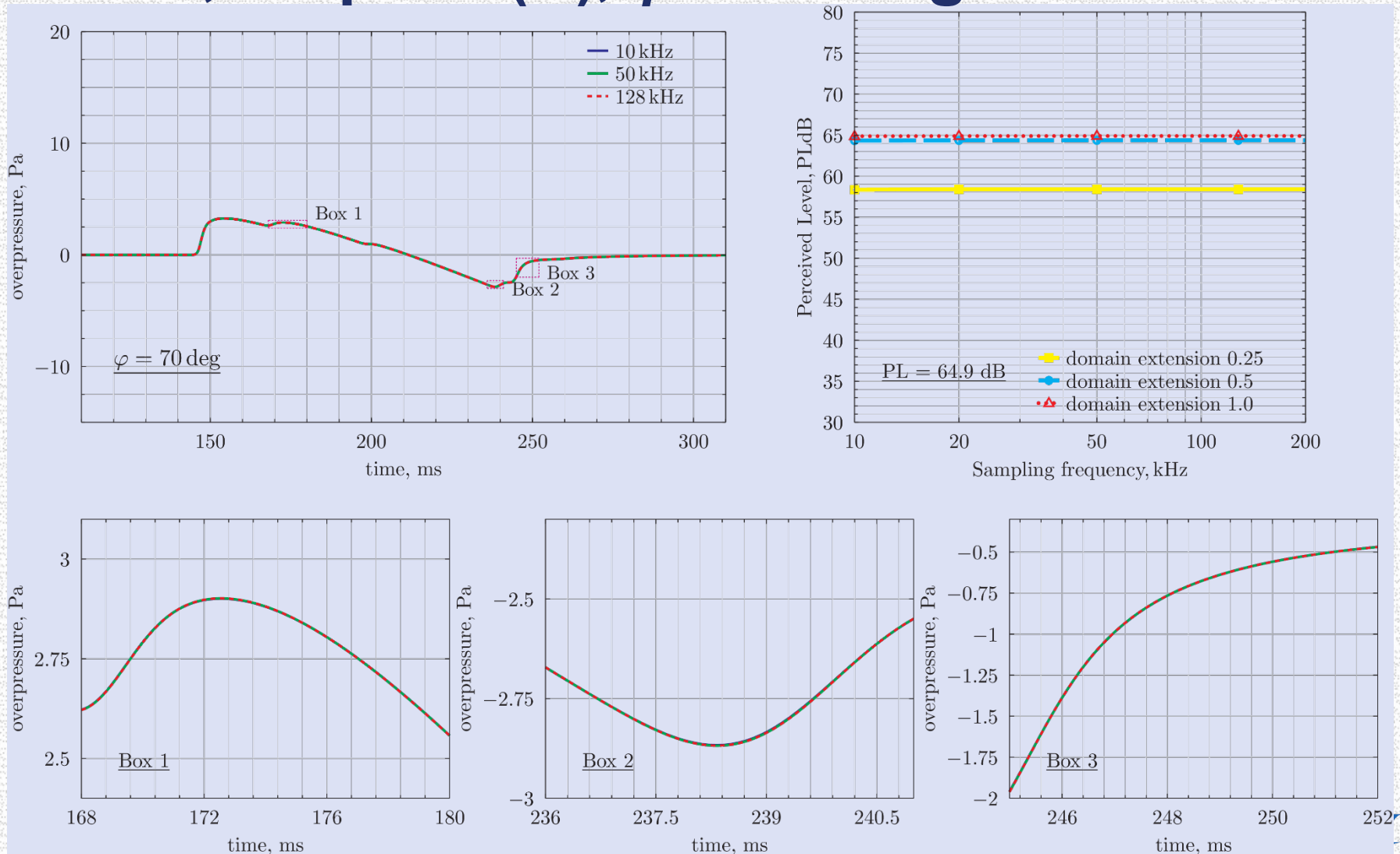
Case 2, Required(i), $\varphi = 0$ deg



Case 2, Required(ii), $\varphi = -64$ deg



Case 2, Required(iii), $\varphi = 70$ deg



Case 1, Optional: C25P, a powered equivalent of the NASA C25D

Optional Run

For zero azimuthal angle, determine focus signature at \bar{z} locations of:
– 1.0 (Evanescent wave), 0.0 (Focus location) and 1.0 (Edge of post-focus region predicting the outgoing wave)

1. Ground signatures (Time (seconds) vs. Pressure (Pascals))
2. Loudness metrics (PL, ASEL, BSEL, CSEL) corresponding to all the ground signatures
3. The ground intersection location in meters corresponding to $\bar{z} = 0.0$ and propagation time in seconds

Configuration

✓ Parameters provided:

Parameters	Values	Unit
Mach number, M	1.4121	-
\dot{M}	0.015681	1/s
\ddot{M}	0.000359	1/s ²
Flight path angle	0	deg
diffraction boundary layer thickness, δ	682.45	m
Atmospheric profile	Standard Atmosphere	-

✓ Some additional conditions must be specified:

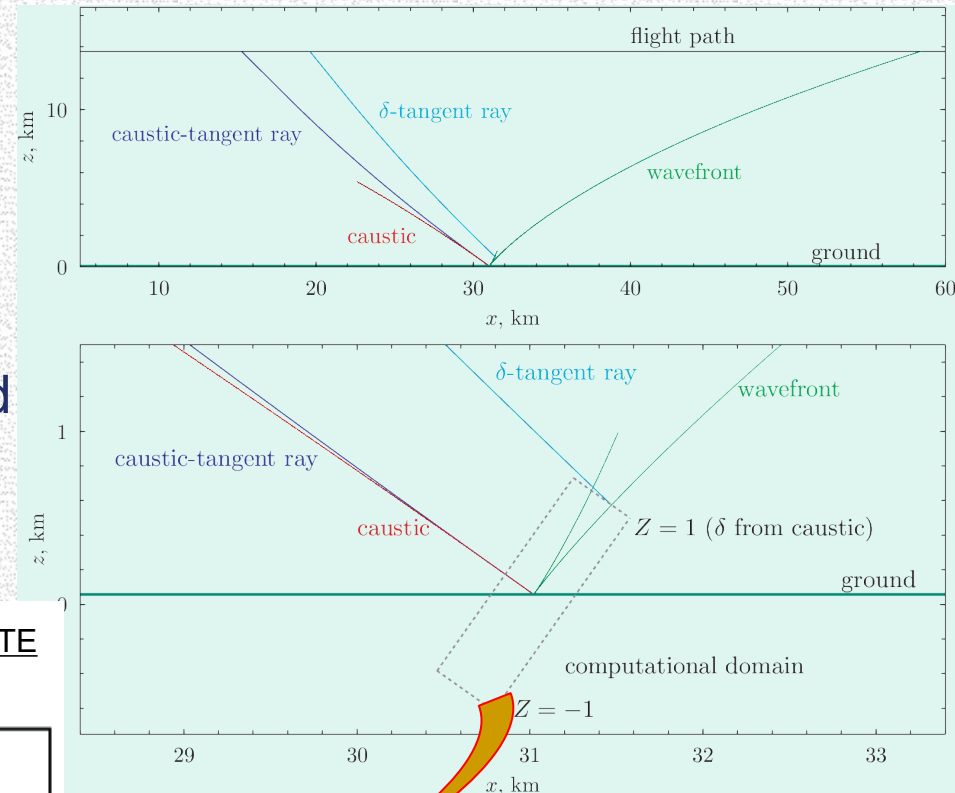
- ✓ δ -tangent ray and corresponding flight conditions FOR obtaining incoming waveform
- ✓ Few parameters FOR specifying the parameters appeared in Lossy NTE

What We Need for Lossy NTE Analysis?

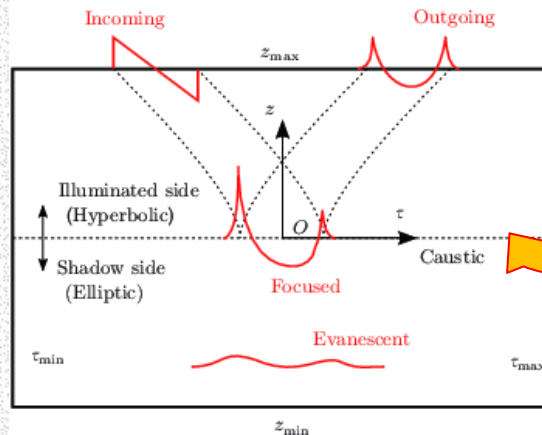
- ✓ To set computational domain
- ✓ To specify δ -tangent ray

Questions:

- ✓ Where is the caustic?
- ✓ Which raypath does the provided condition (M, \dot{M}, \ddot{M}) correspond?



Computational domain of Lossy NTE



Setting Flight Path

✓ Assuming $\dot{M} = \text{Const.}$:

$$\dot{a} = \ddot{M}c$$

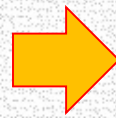
$$a(t) = a_0 + \dot{a}t$$

$$u(t) = u_0 + a_0t + \frac{1}{2}\dot{a}t^2$$

✓ At the time $t = \bar{t}$, $a(\bar{t}) = \dot{M}c$, $u(\bar{t}) = Mc$:

$$a_0 = (\dot{M} - \ddot{M}\bar{t})c$$

$$u_0 = \left(M - \dot{M}\bar{t} + \frac{1}{2}\ddot{M}\bar{t}^2 \right) c$$



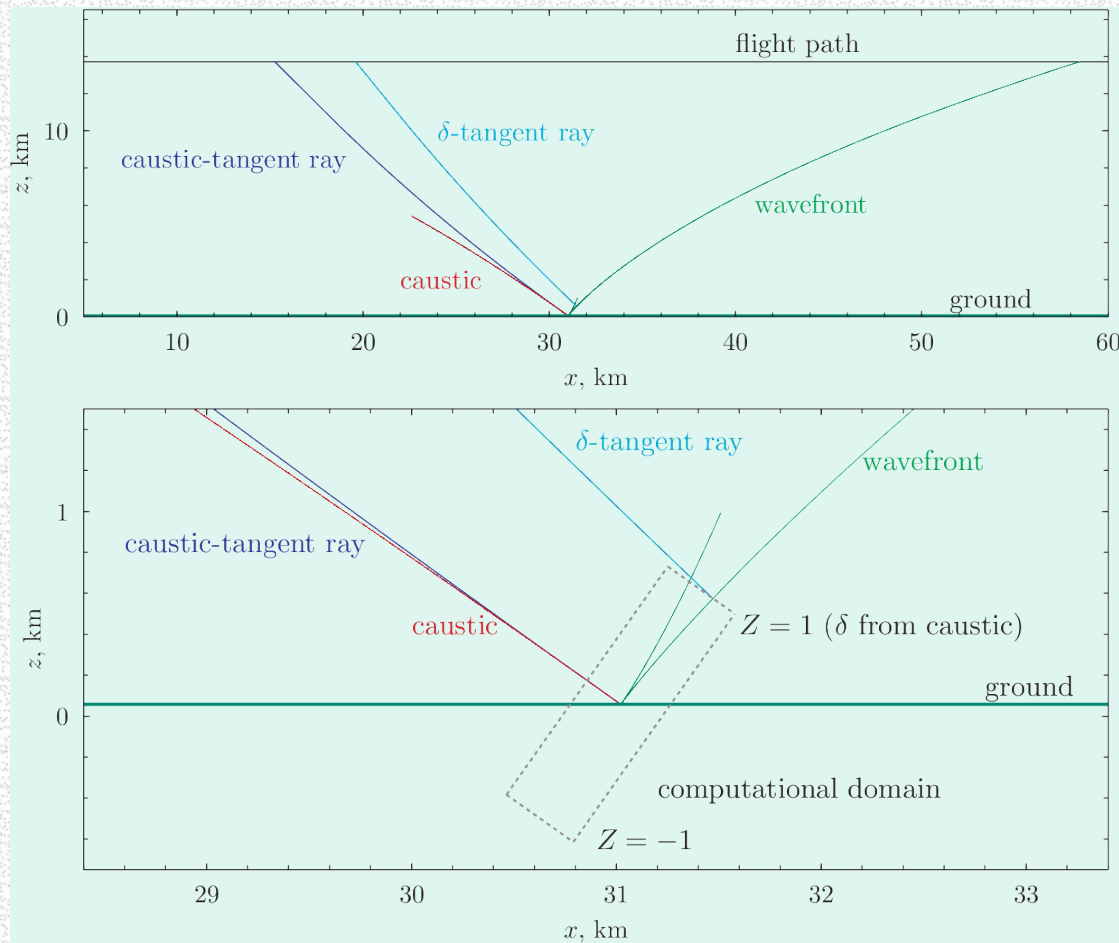
$$a(t) = \dot{M}c + \ddot{M}c(t - \bar{t})$$

$$u(t) = Mc + \dot{M}c(t - \bar{t}) + \frac{1}{2}\ddot{M}c(t - \bar{t})^2$$



Flight path, Wavefront, Raypaths and Caustic

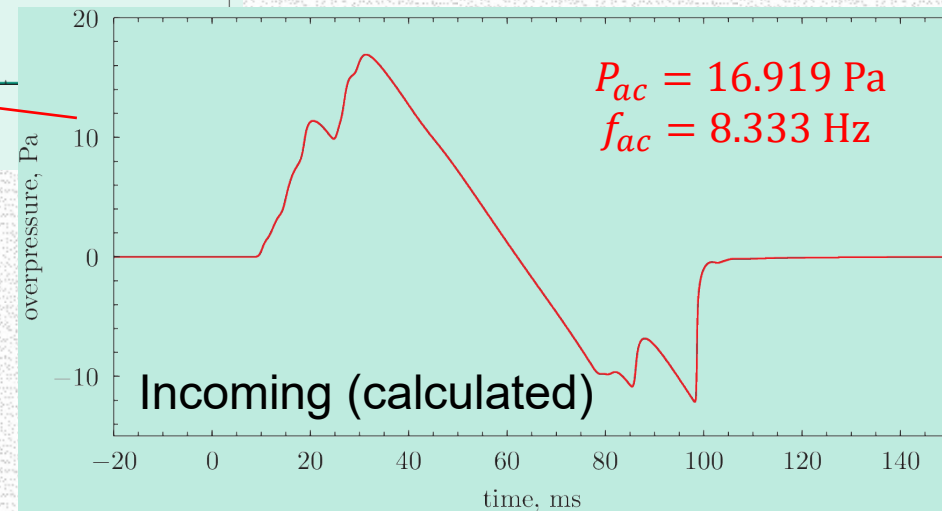
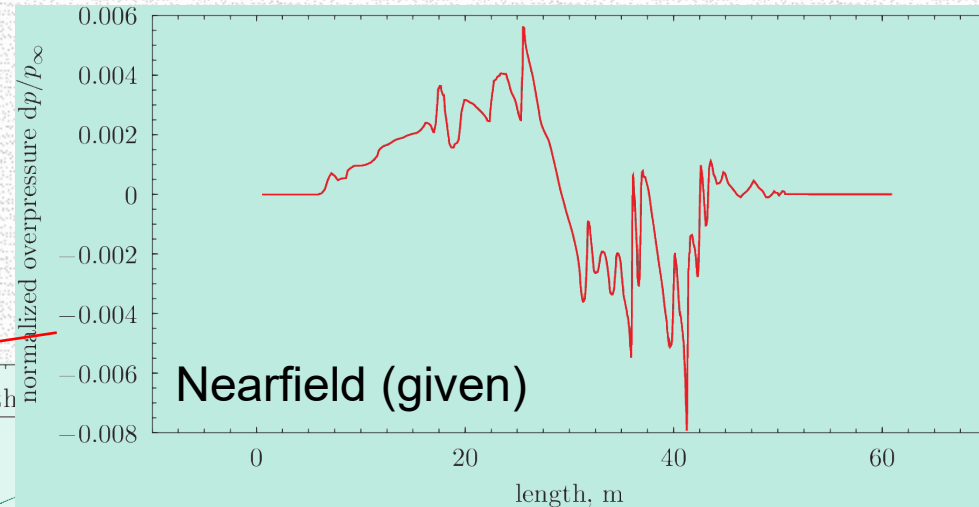
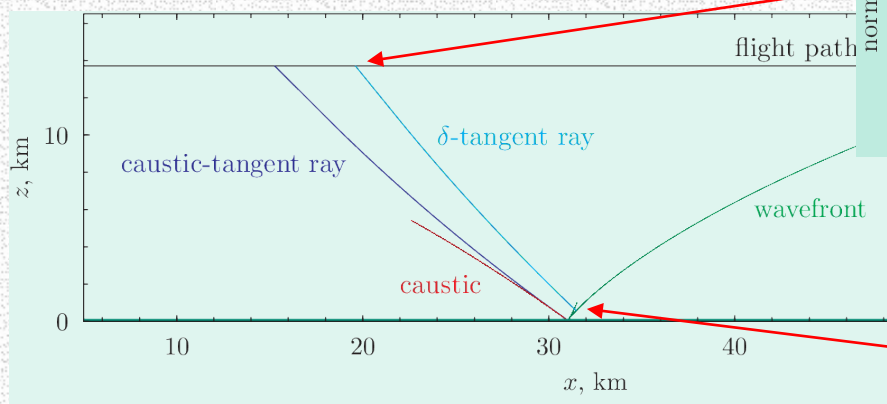
- ✓ The provided condition (M, \dot{M}, \ddot{M}) corresponds to “caustic-tangent ray”
- ✓ δ -tangent ray should be specified to calculate incoming waveform



Nearfield (Input) Signature for Focusing case

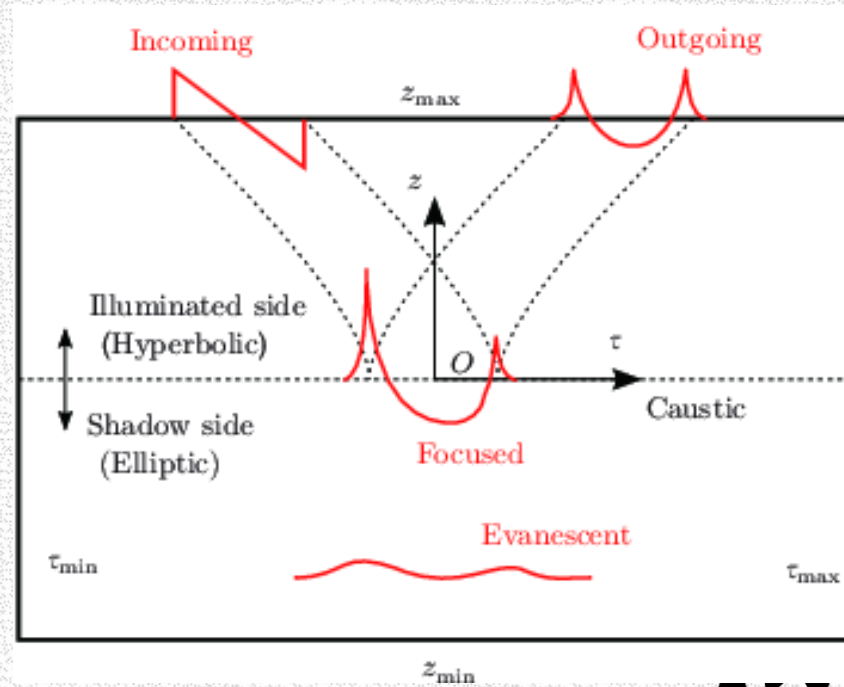
Conditions corr. δ - tangent ray

Parameters	Values	Unit
Mach number, M	1.5839	-
\dot{M}	0.019215	1/s



Definition of Computational Region

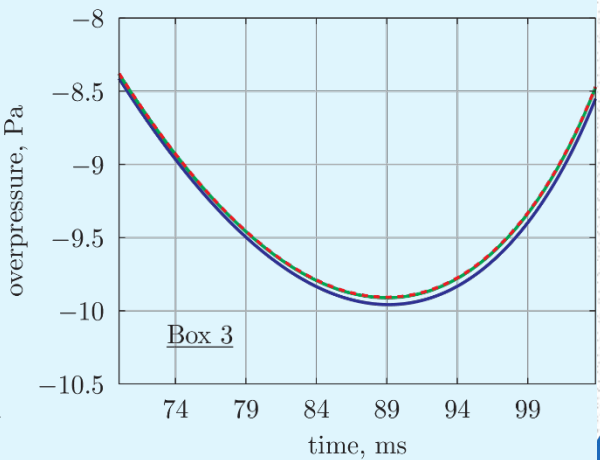
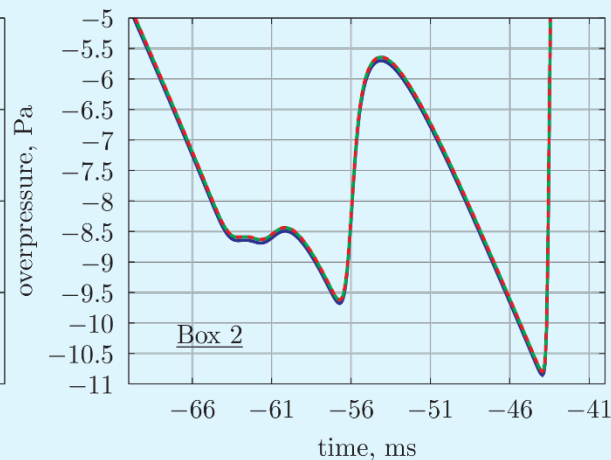
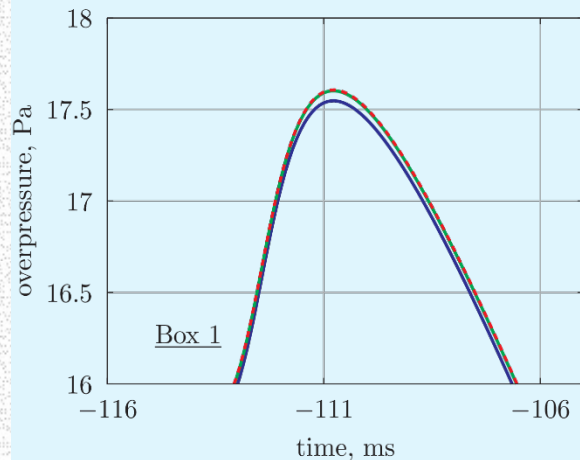
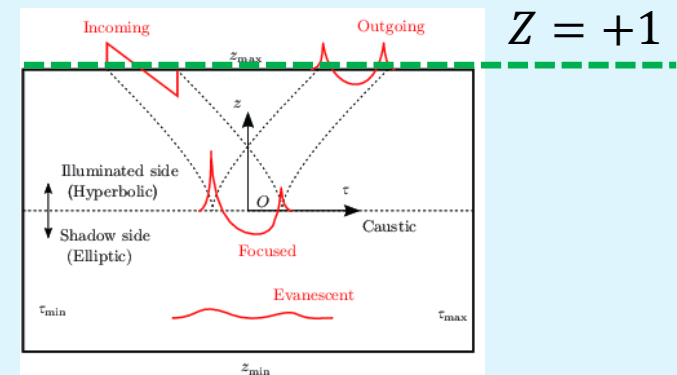
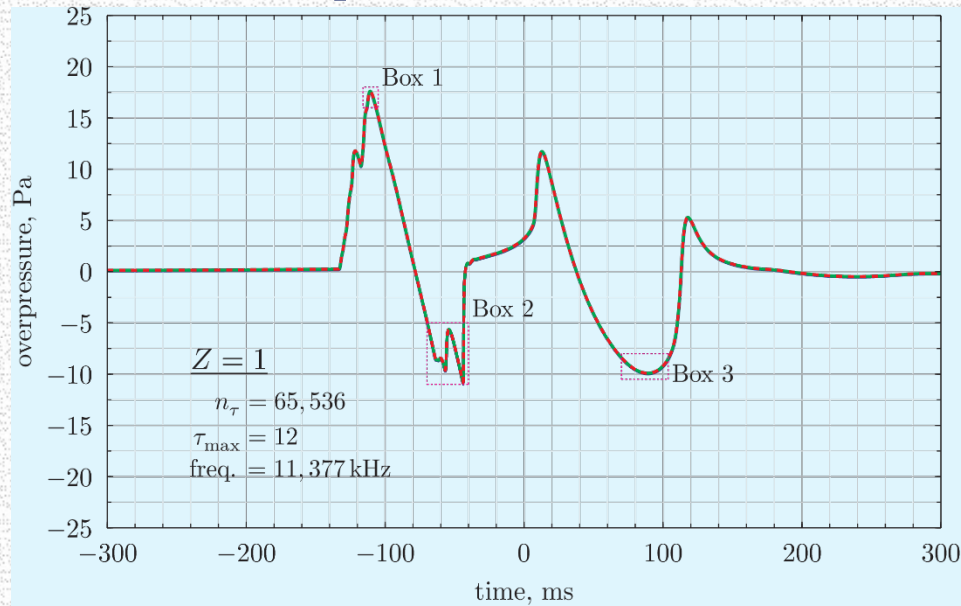
parameters	range
number of division in τ , n_τ	16,384 – 131,072
number of division in Z , n_Z	4,096 – 16,384
lower bound of Z , Z_{\min}	-1, -3, -7
lower/upper bound of τ , $\tau_{\max} = \tau_{\min} $	-3, -6, -12



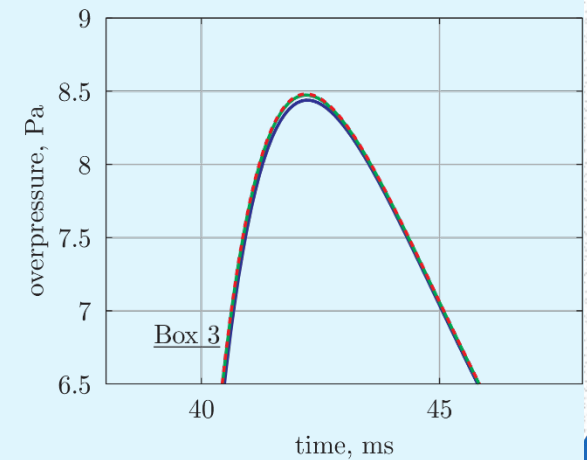
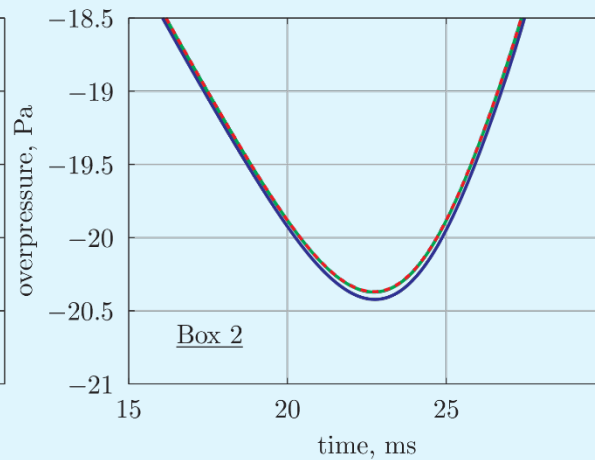
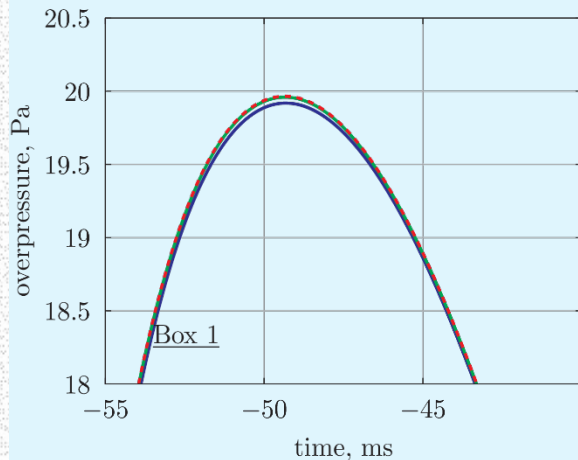
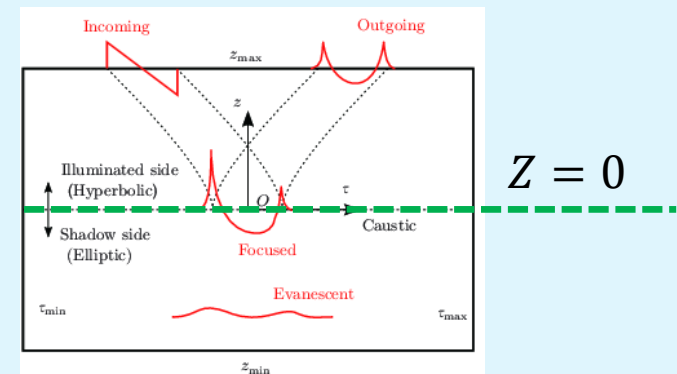
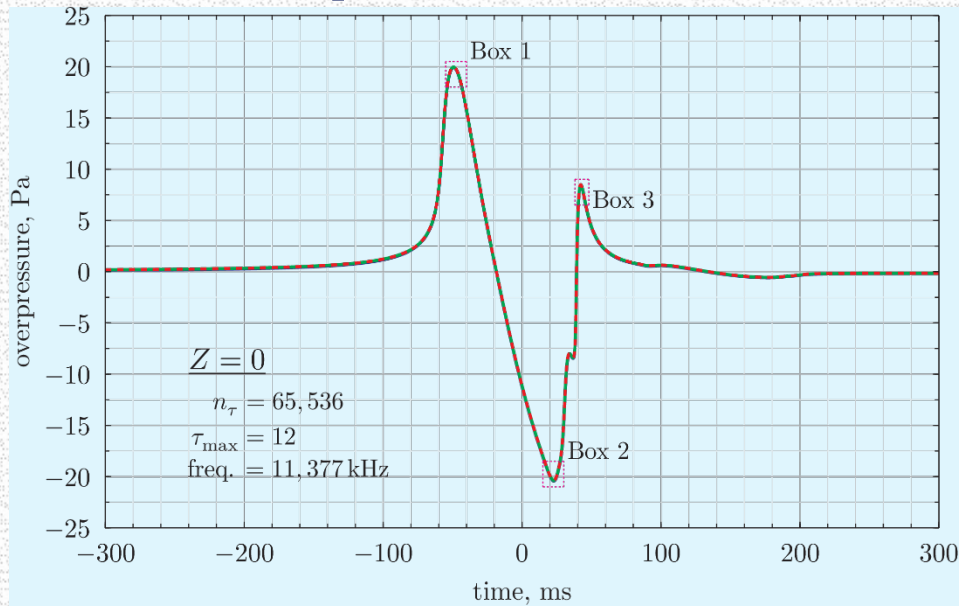
Numerical Simulation
Research Unit



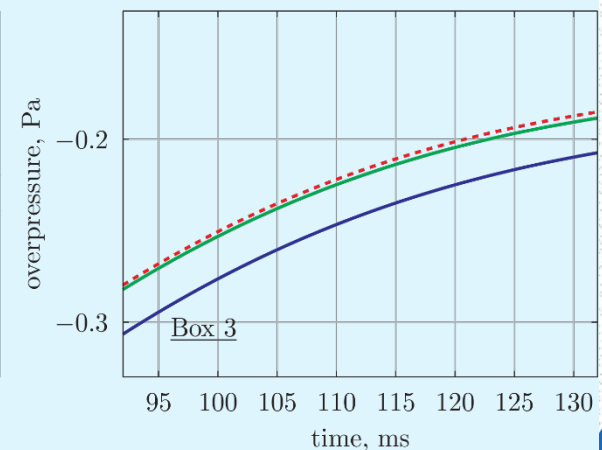
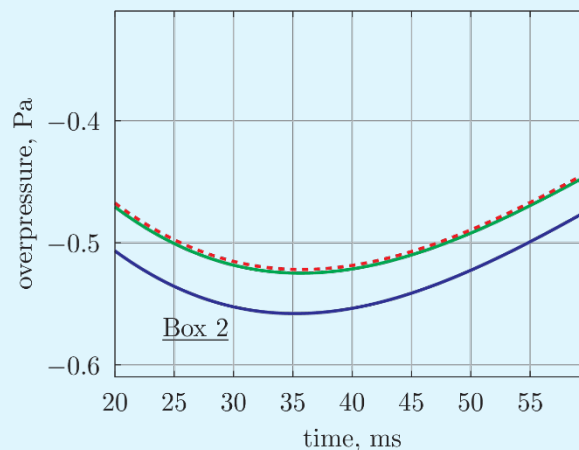
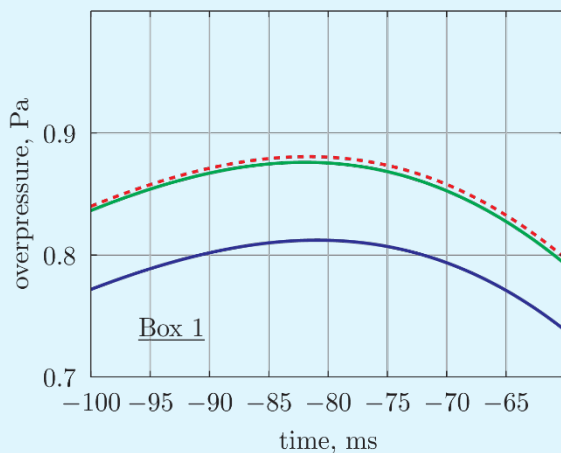
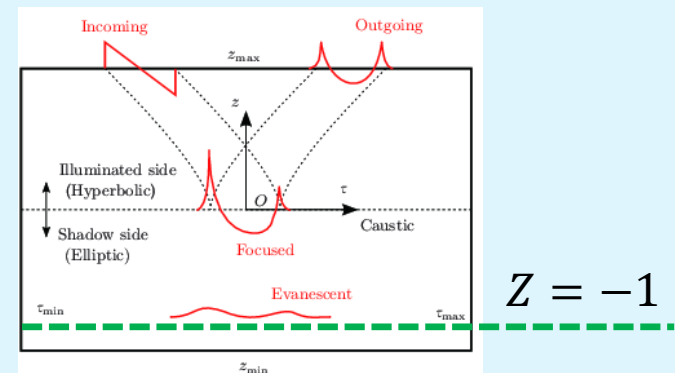
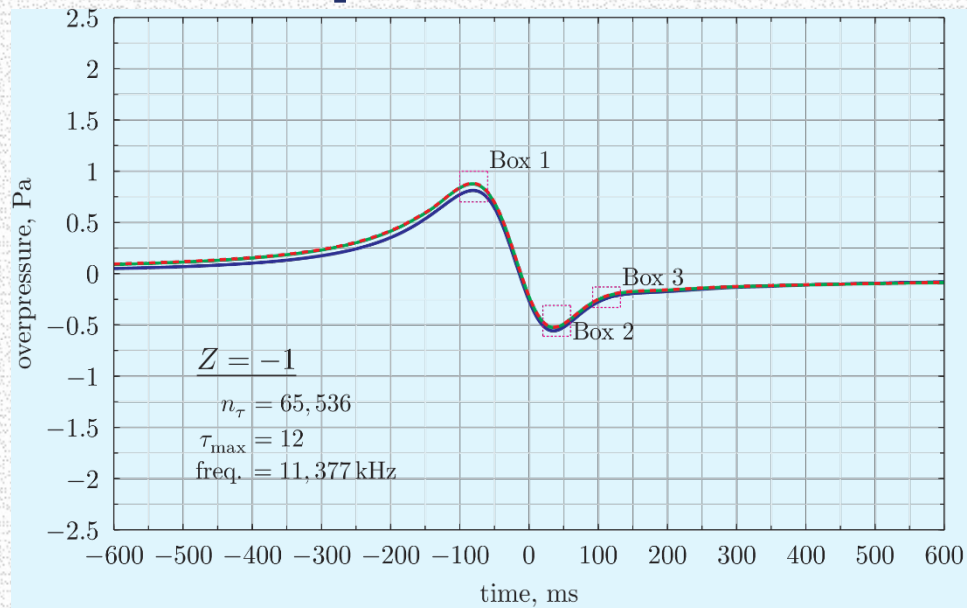
Case1, Optional, Variable Domain Size in Z



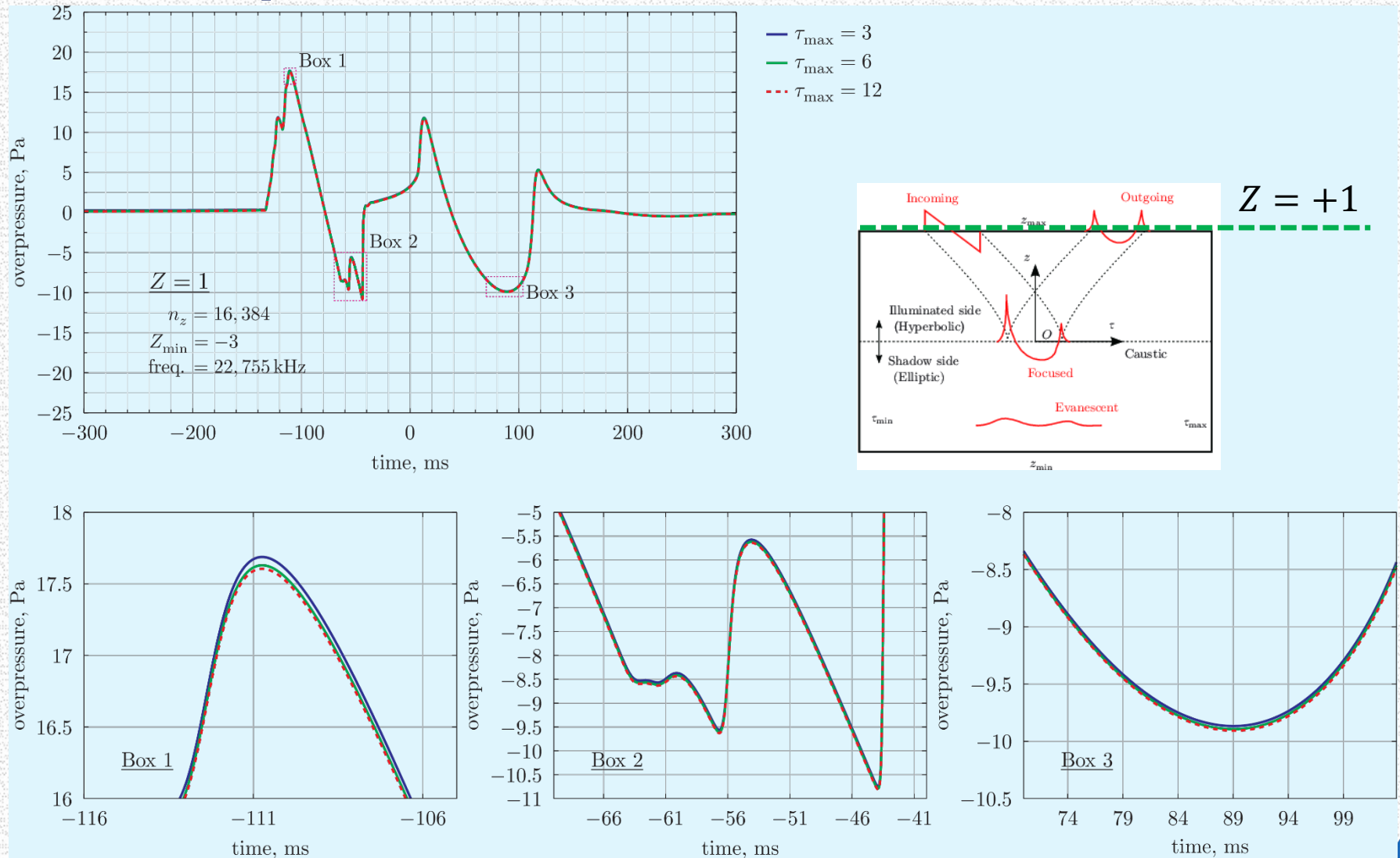
Case1, Optional, Variable Domain Size in Z



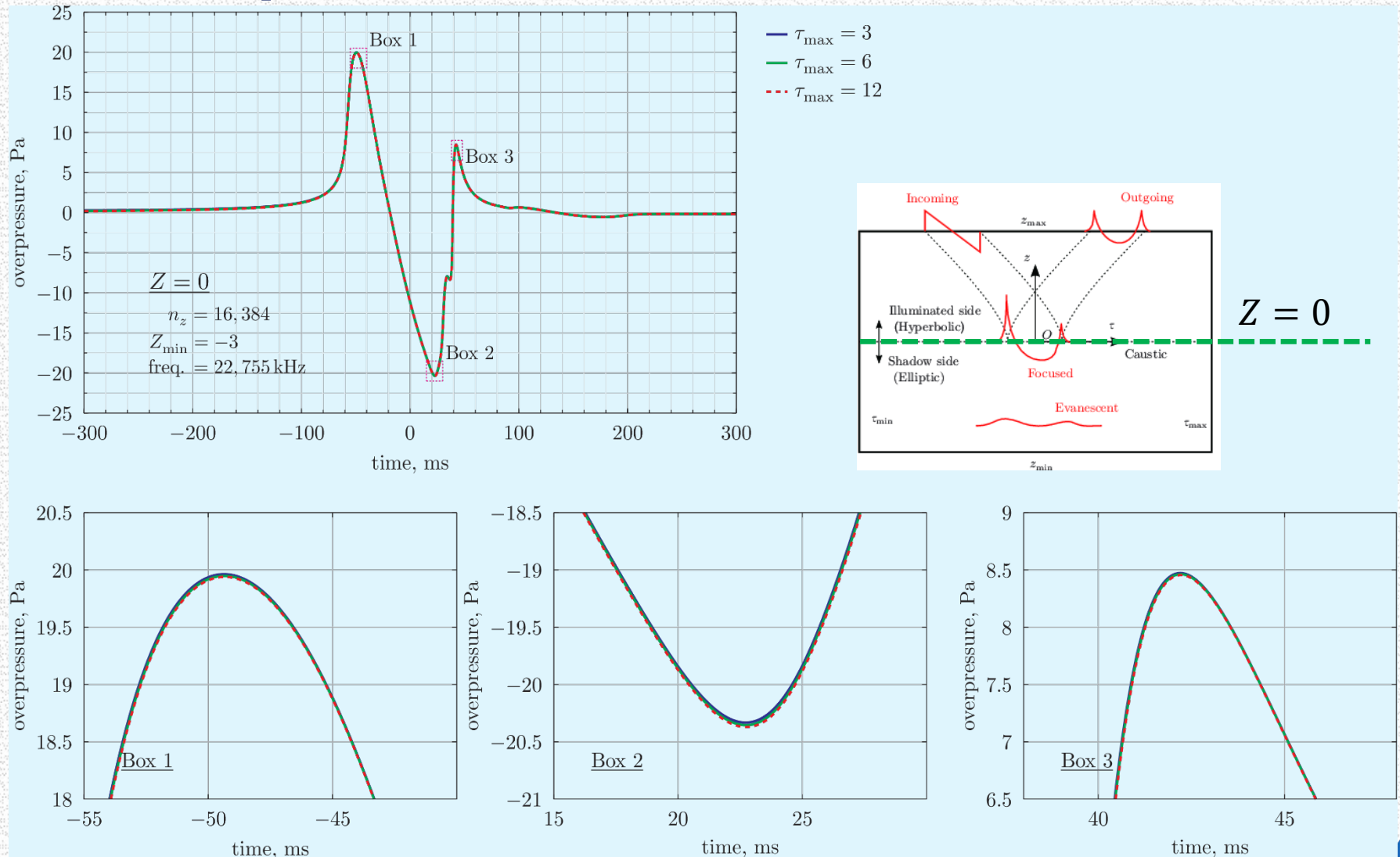
Case1, Optional, Variable Domain Size in Z



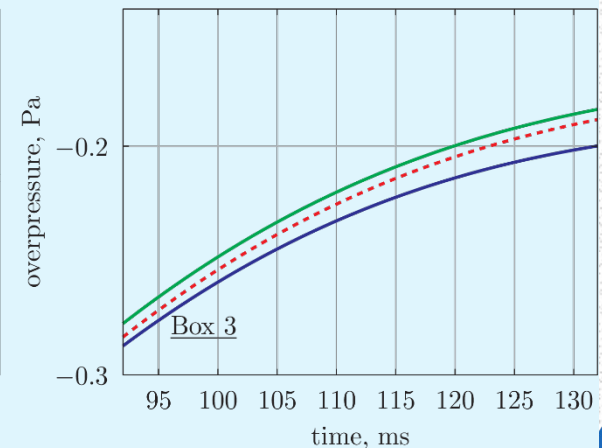
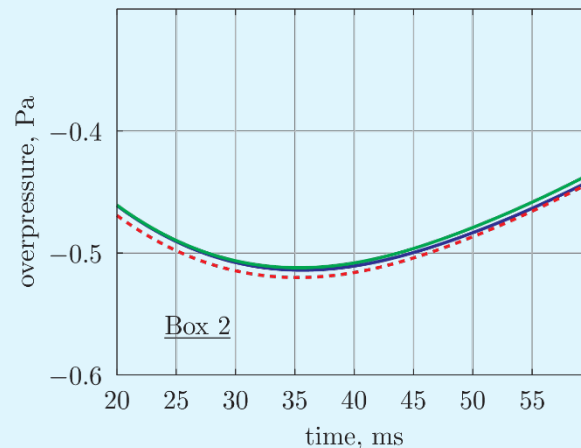
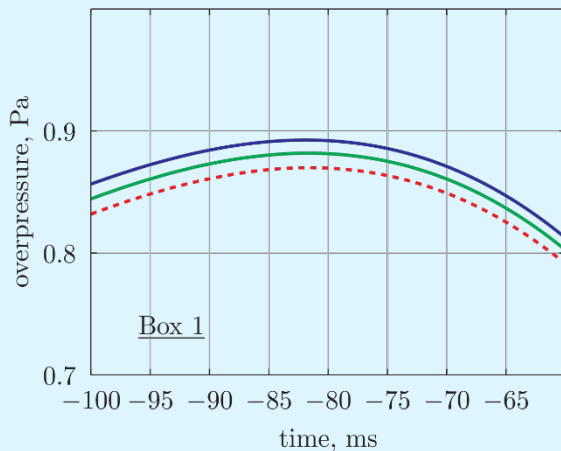
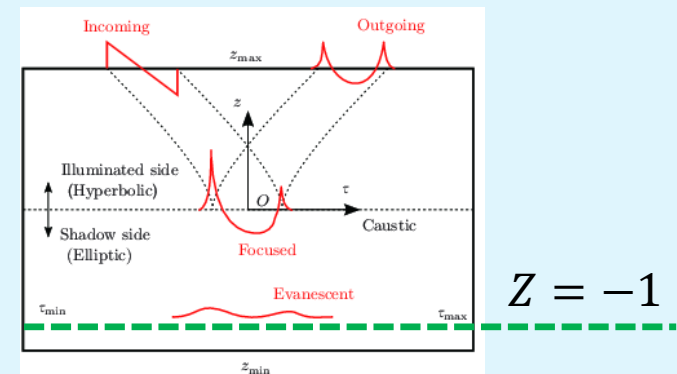
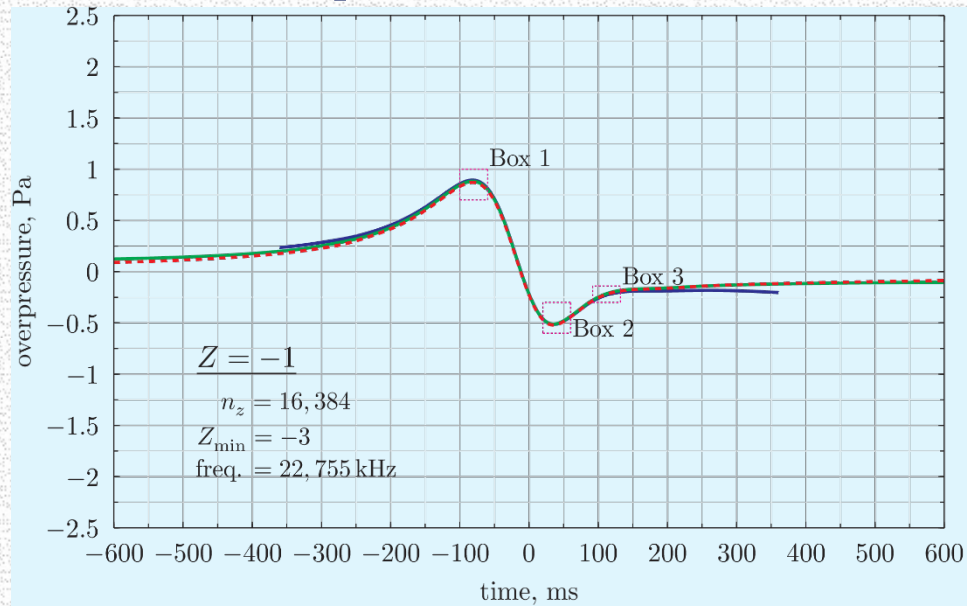
Case1, Optional, Variable Domain Size in τ



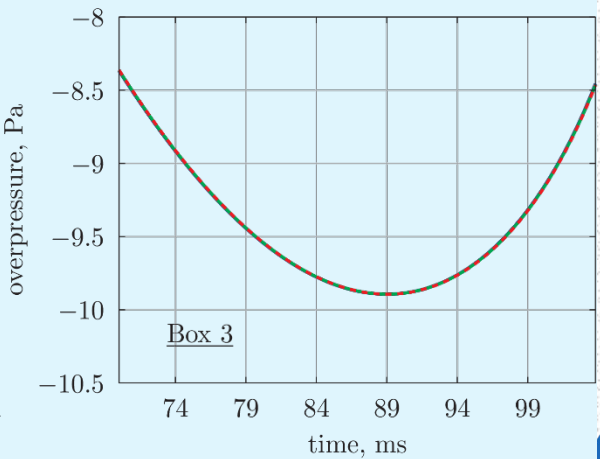
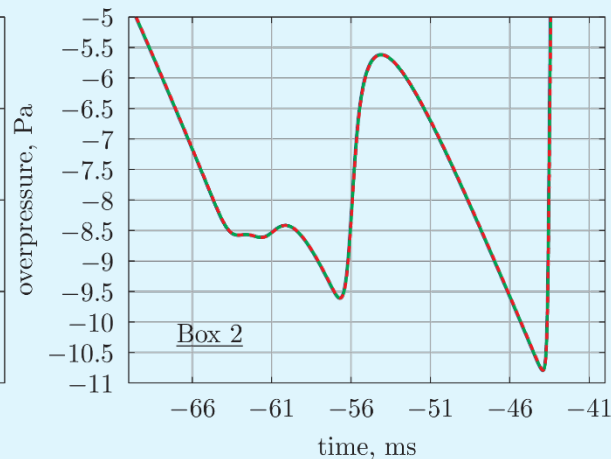
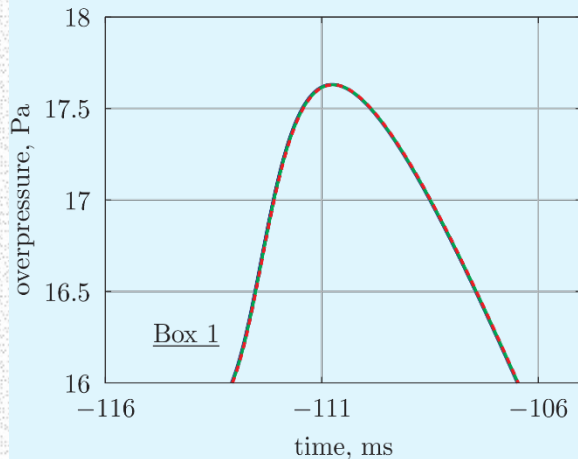
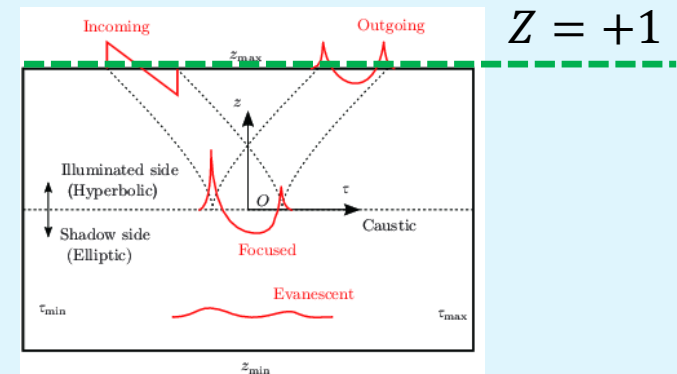
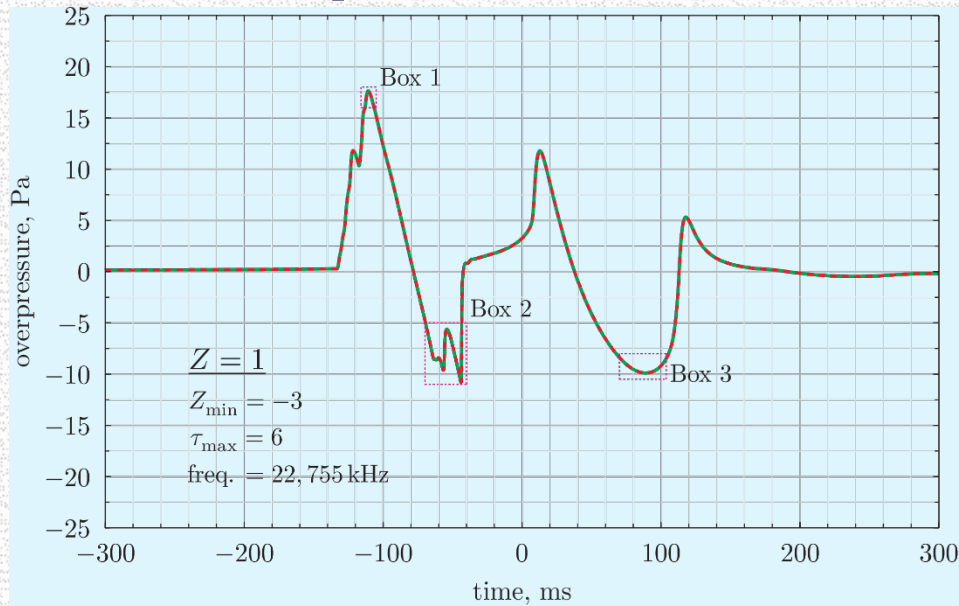
Case1, Optional, Variable Domain Size in τ



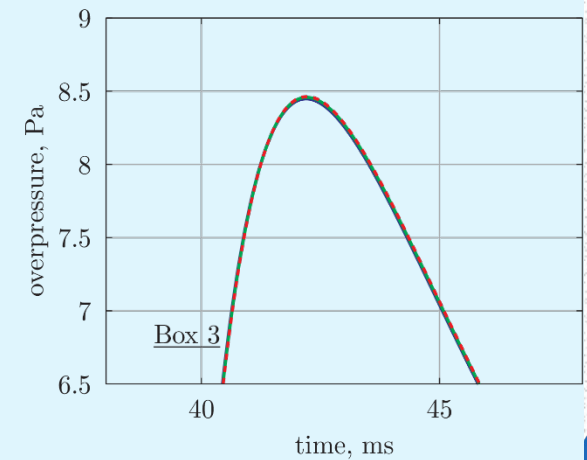
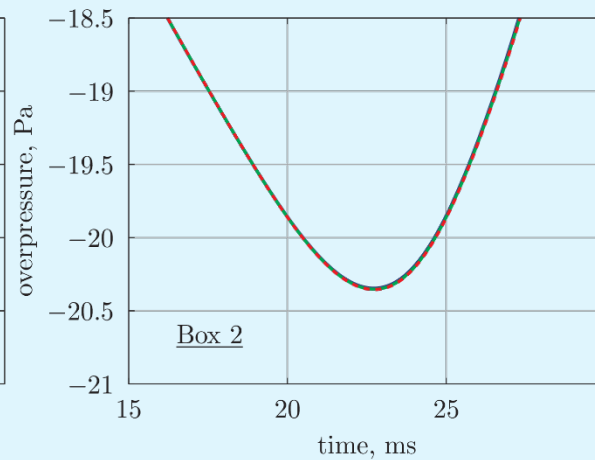
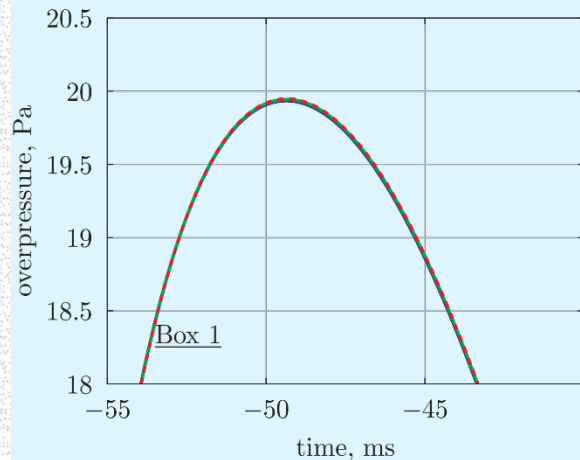
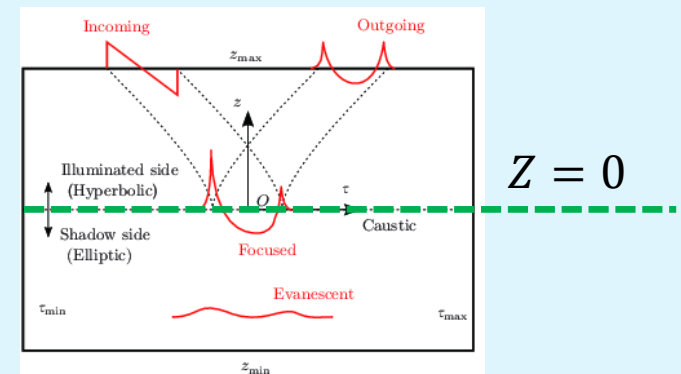
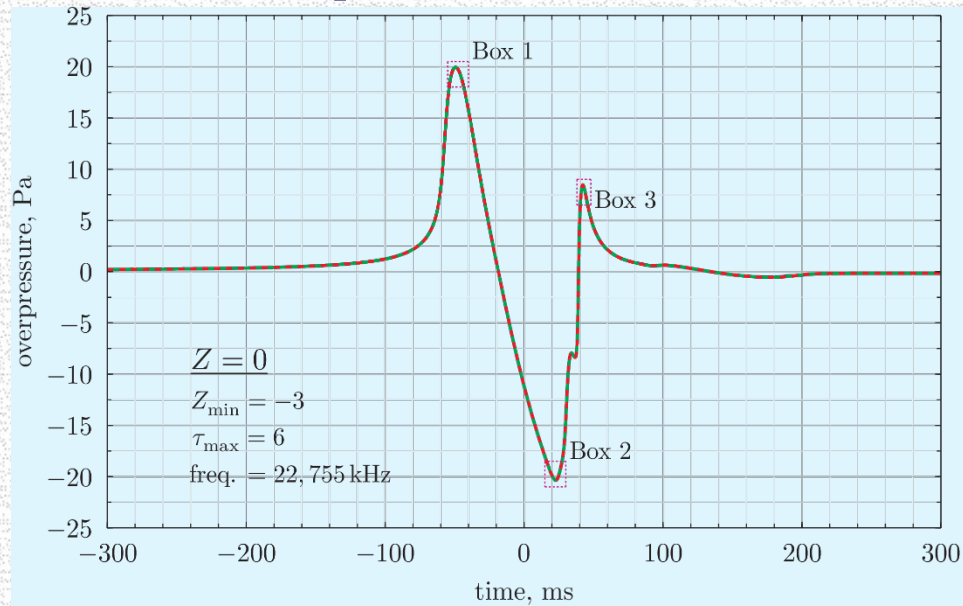
Case1, Optional, Variable Domain Size in τ



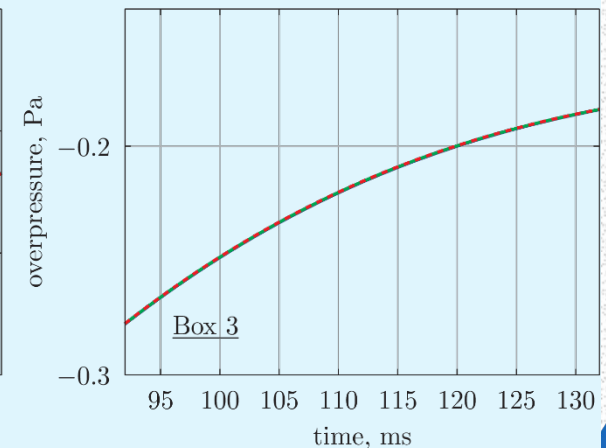
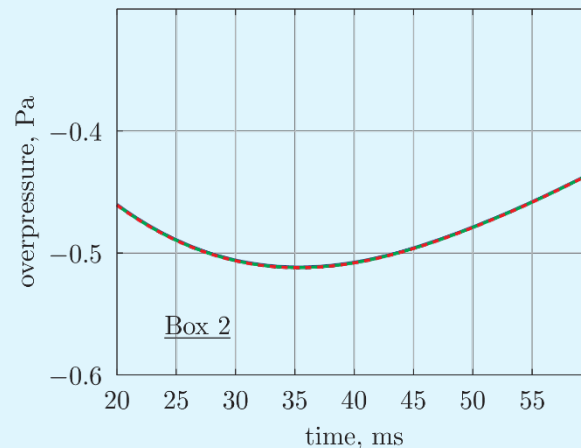
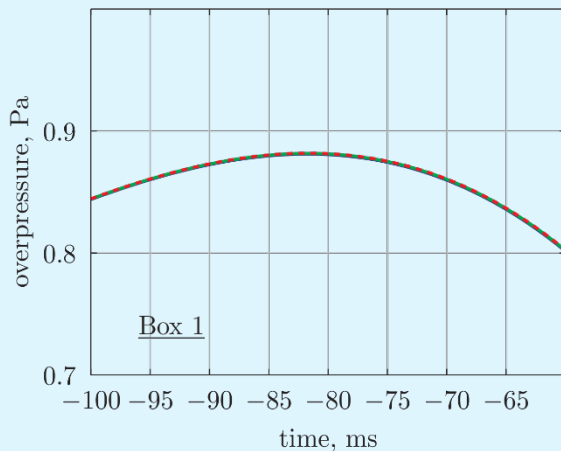
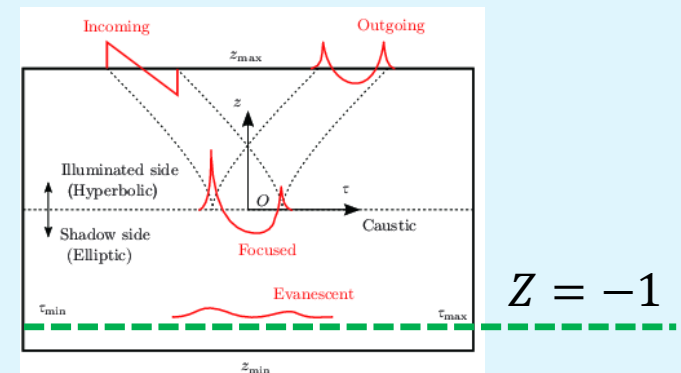
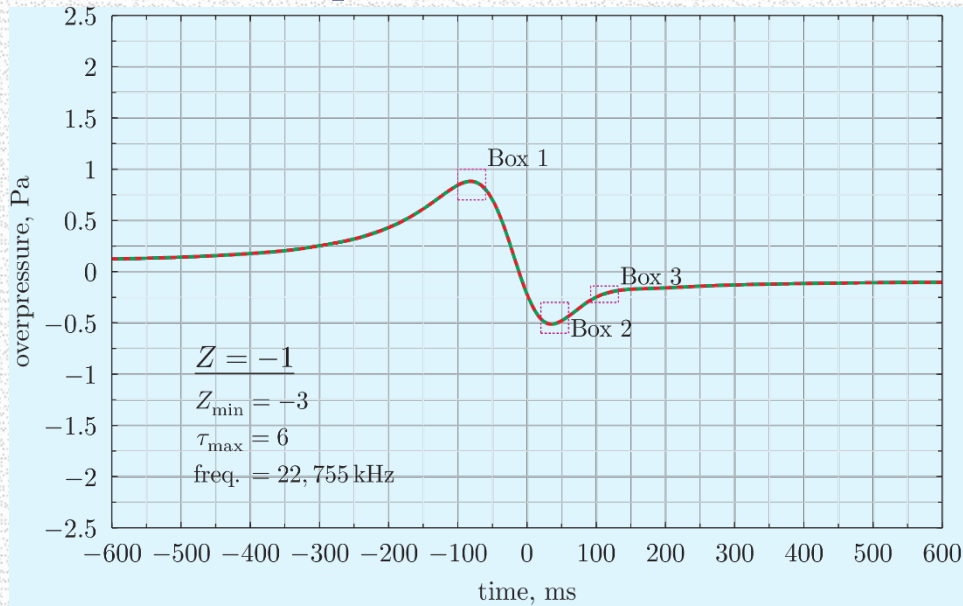
Case1, Optional, Variable Resolution in Z



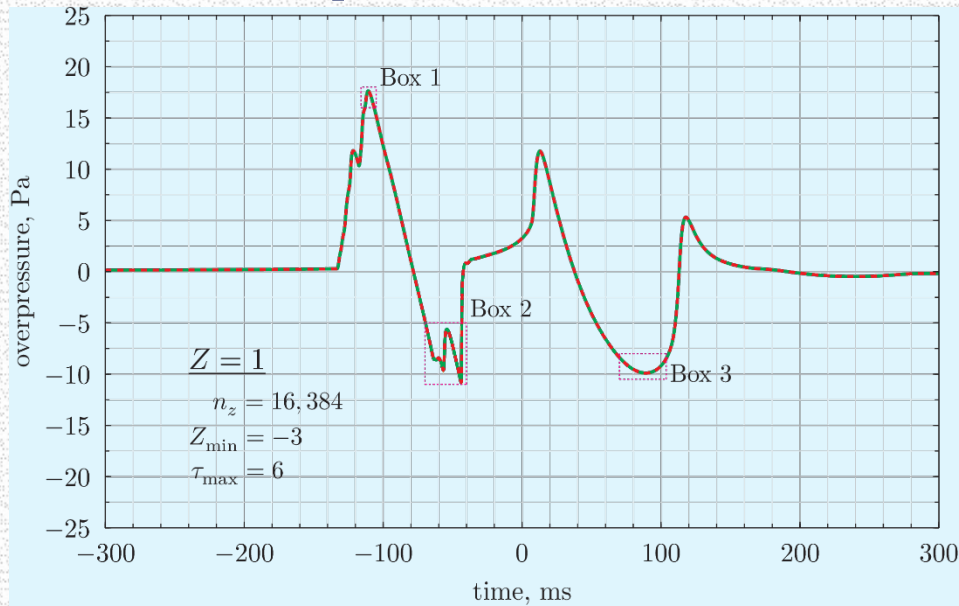
Case1, Optional, Variable Resolution in Z



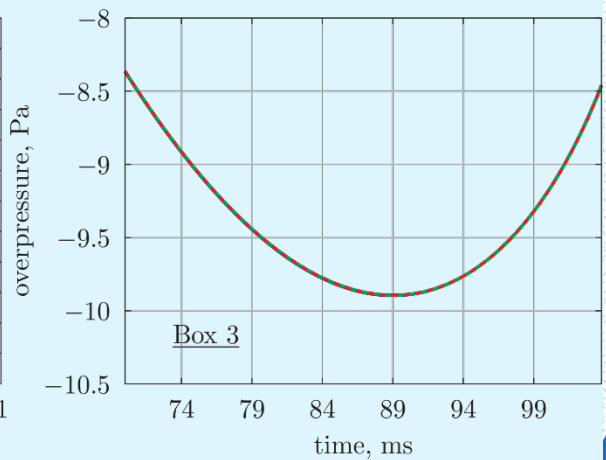
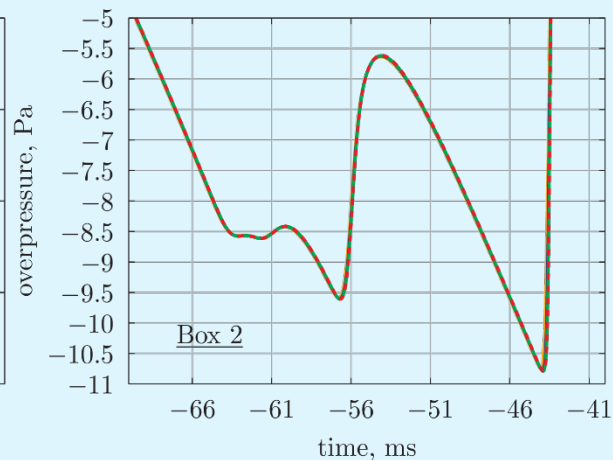
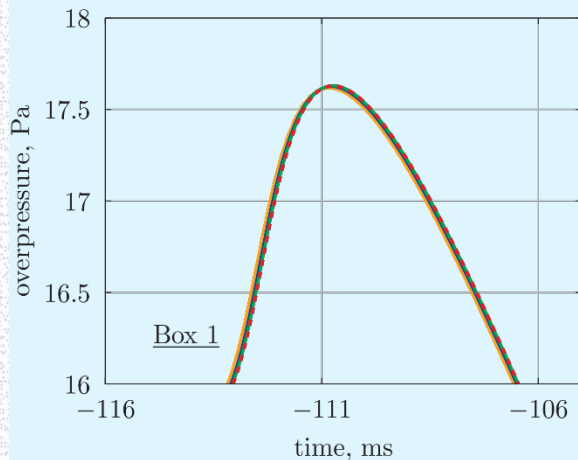
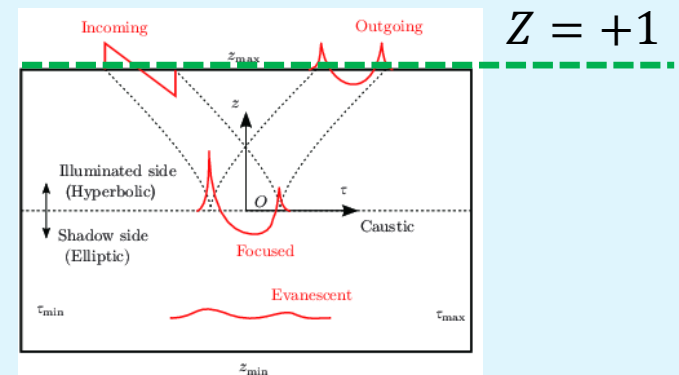
Case1, Optional, Variable Resolution in Z



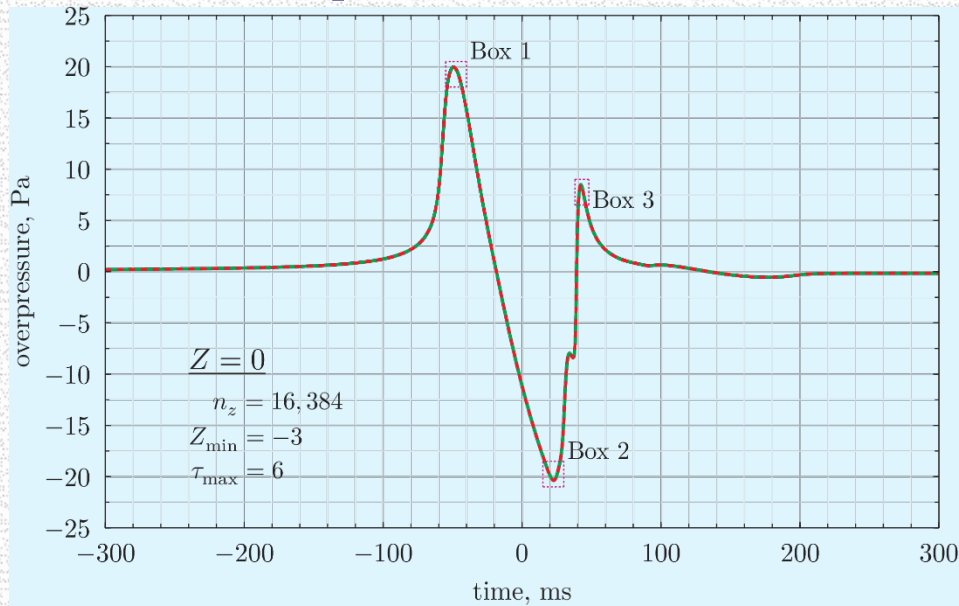
Case1, Optional, Variable Resolution in τ



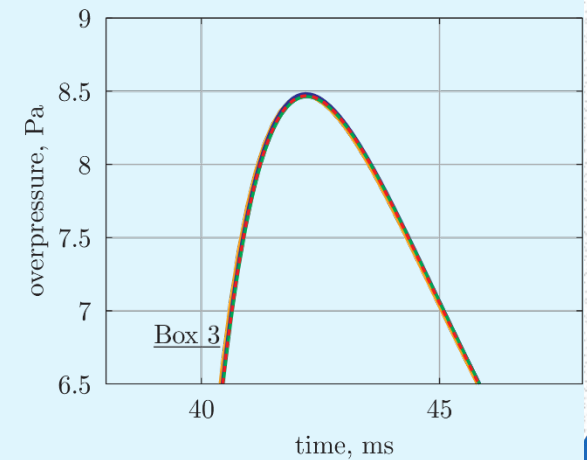
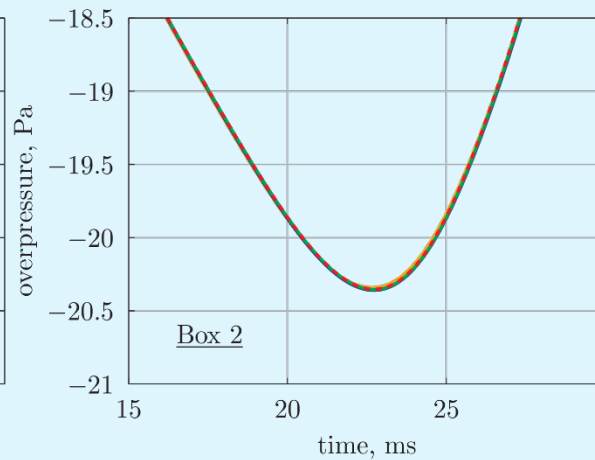
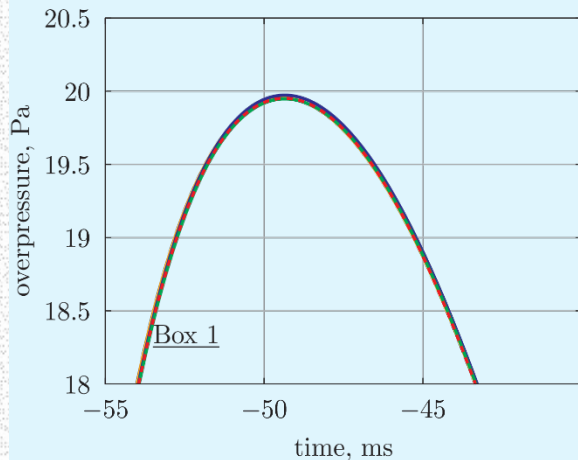
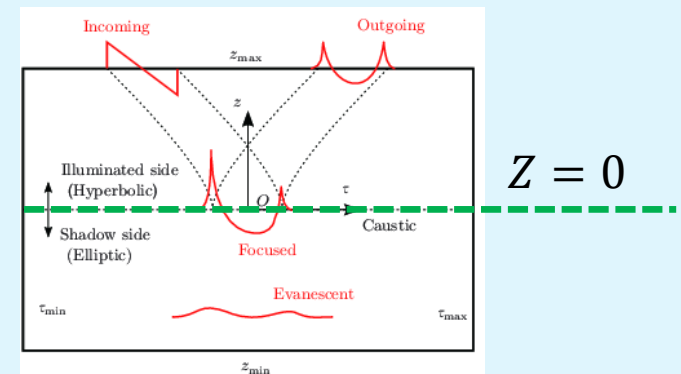
- $n_\tau = 16,384$ (freq. = 5,689 kHz)
- $n_\tau = 32,768$ (freq. = 11,377 kHz)
- $n_\tau = 65,536$ (freq. = 22,755 kHz)
- - - $n_\tau = 13,1072$ (freq. = 45,509 kHz)



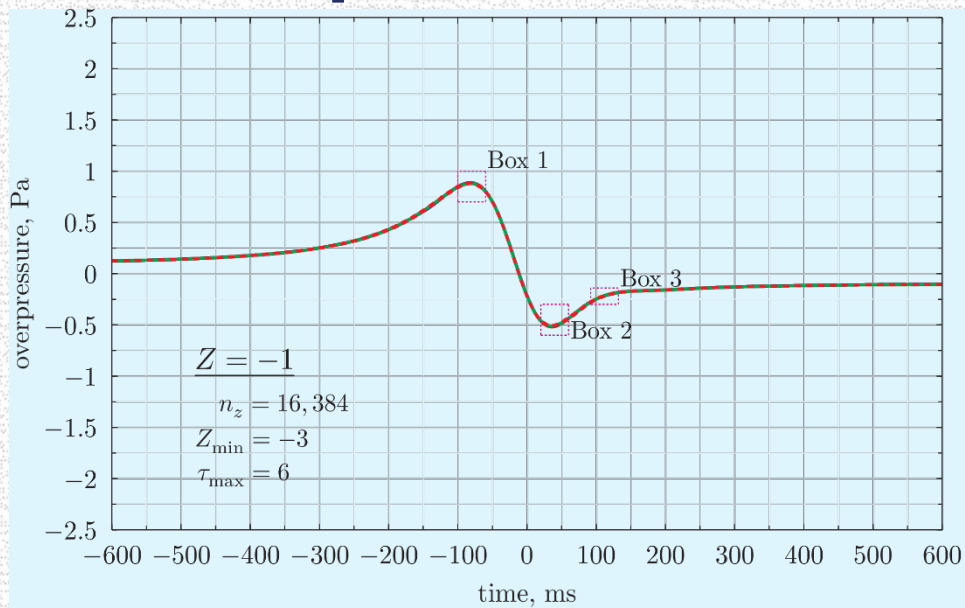
Case1, Optional, Variable Resolution in τ



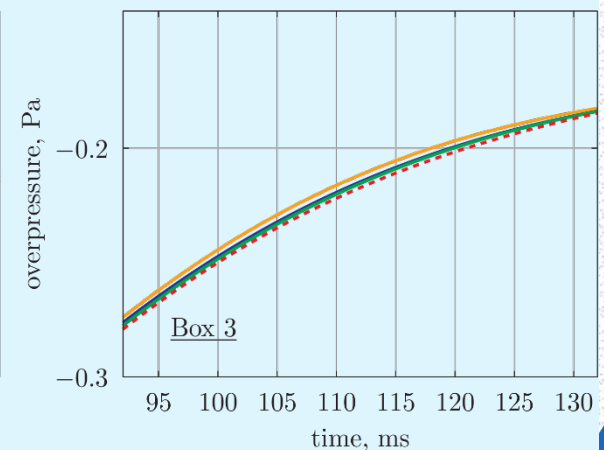
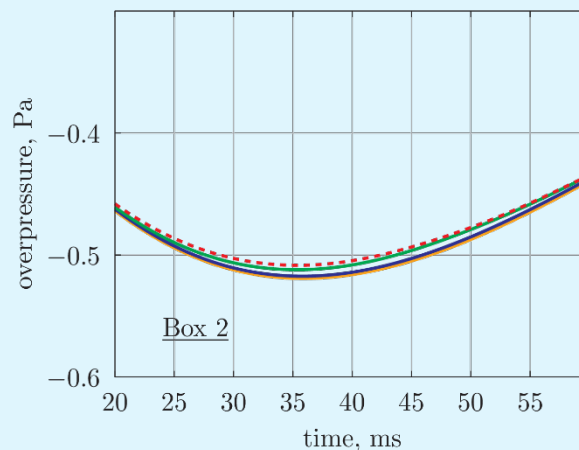
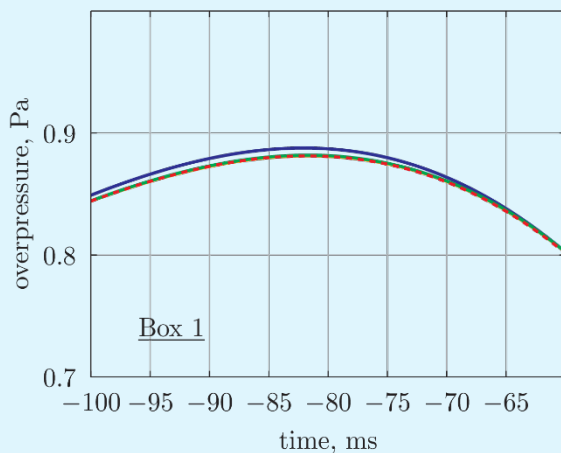
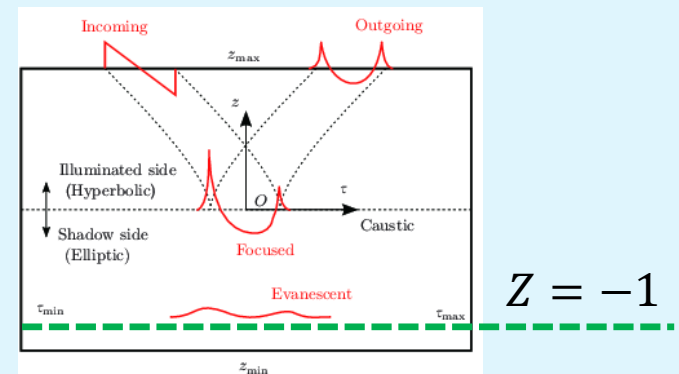
- $n_\tau = 16,384$ (freq. = 5,689 kHz)
- $n_\tau = 32,768$ (freq. = 11,377 kHz)
- $n_\tau = 65,536$ (freq. = 22,755 kHz)
- - - $n_\tau = 13,1072$ (freq. = 45,509 kHz)



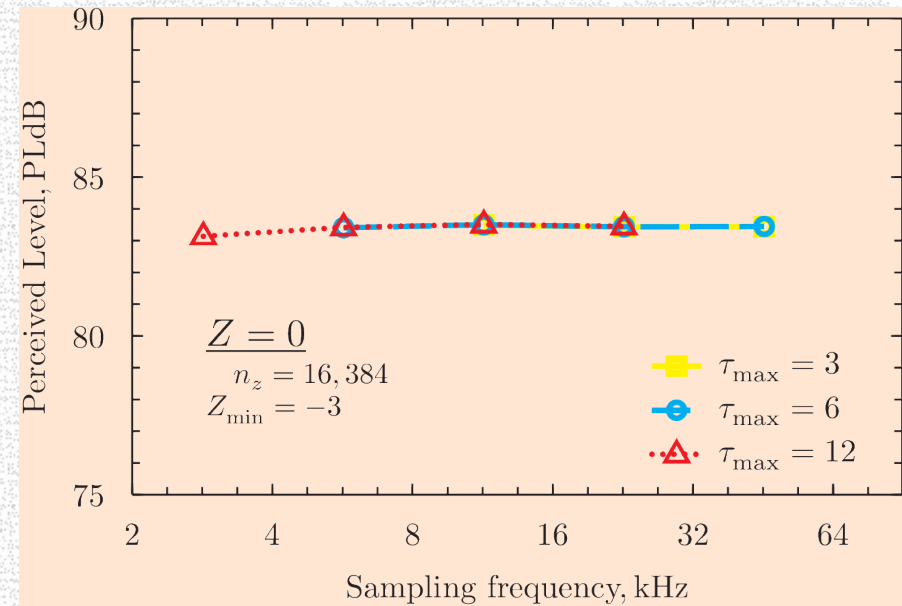
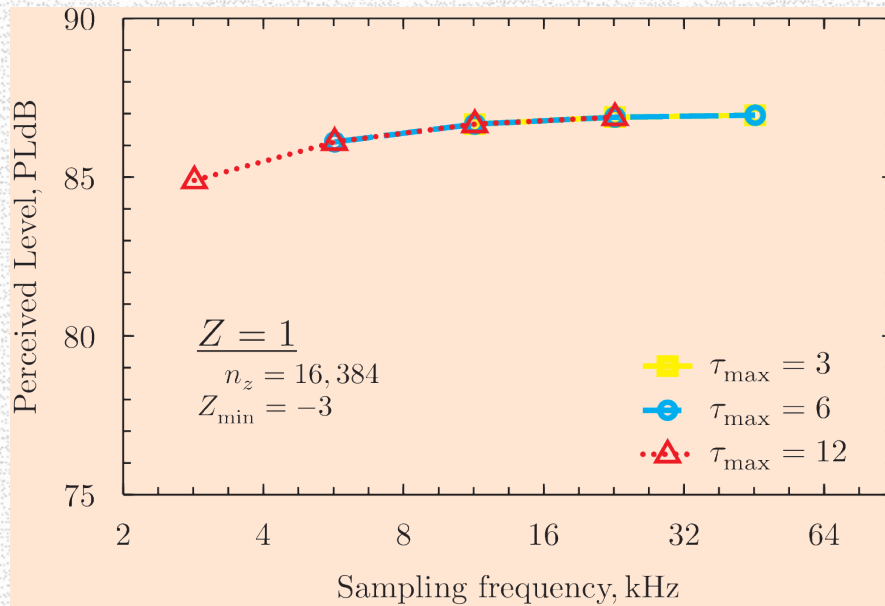
Case1, Optional, Variable Resolution in τ



- $n_\tau = 16,384$ (freq. = 5,689 kHz)
- $n_\tau = 32,768$ (freq. = 11,377 kHz)
- $n_\tau = 65,536$ (freq. = 22,755 kHz)
- - - $n_\tau = 13,1072$ (freq. = 45,509 kHz)

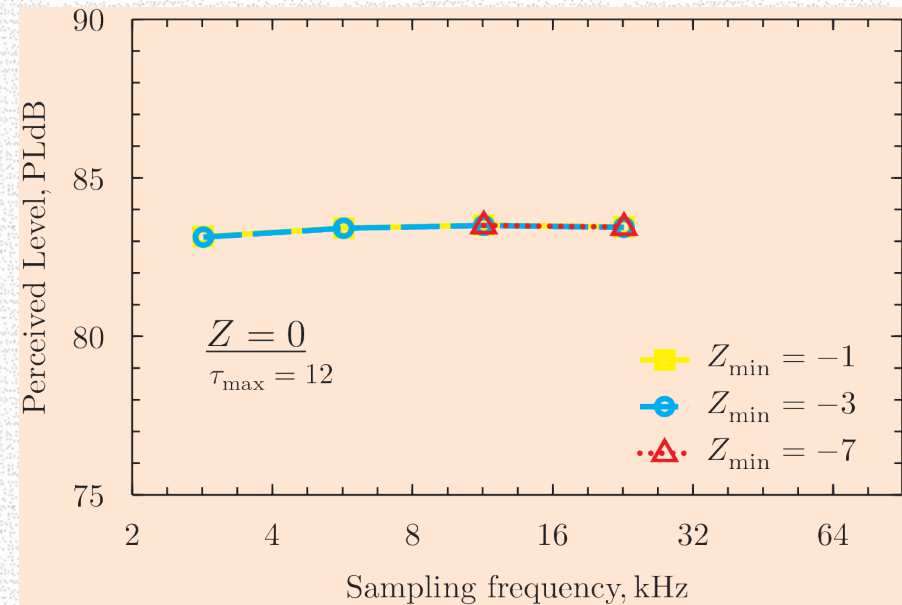
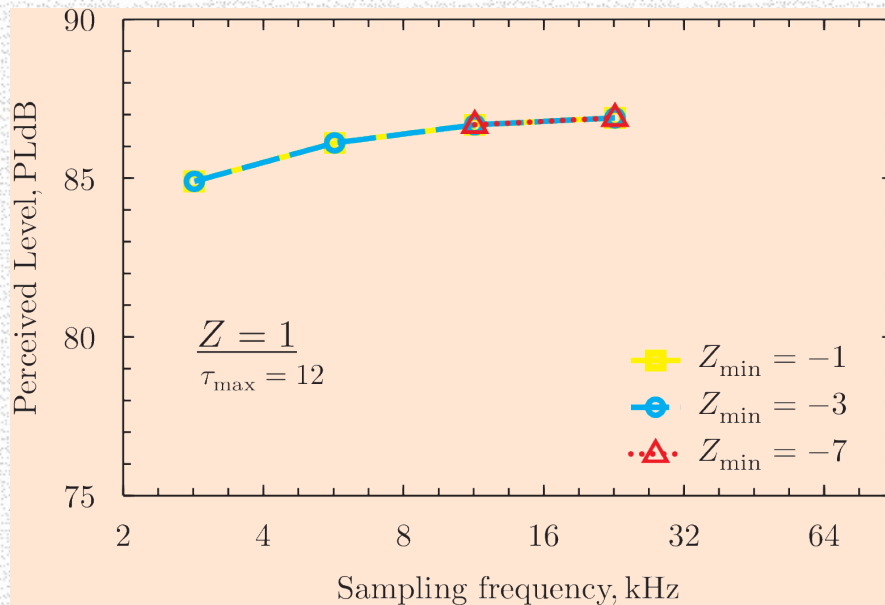


Case1, Optional, Fixed Domain size in Z



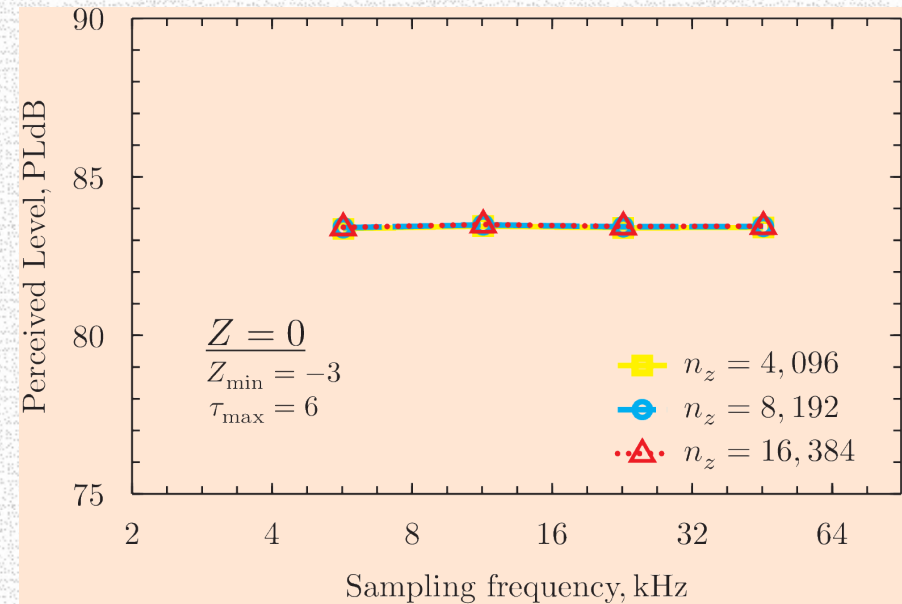
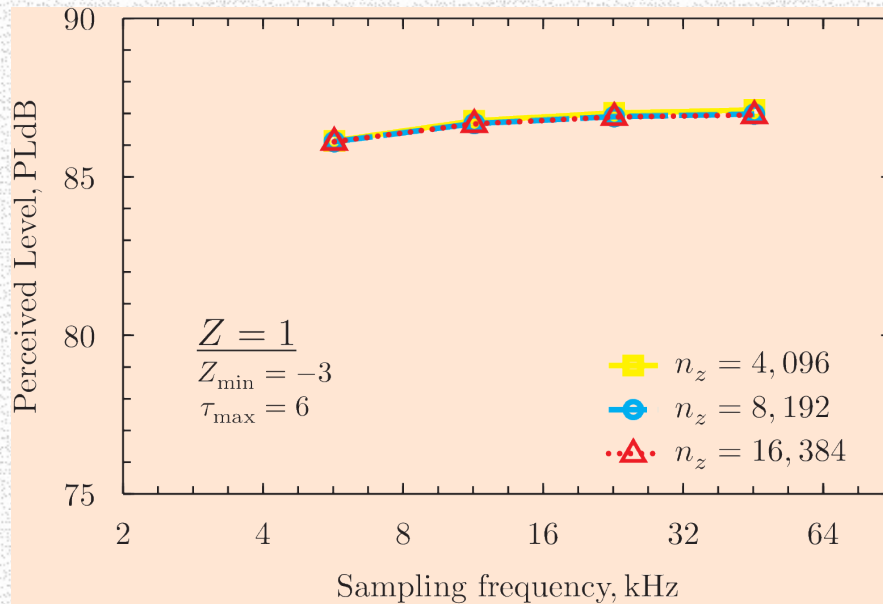
$Z = -1$, N/A

Case1, Optional, Fixed Domain size in τ



$Z = -1, N/A$

Case1, Optional, Fixed Domain size in Z and τ



$Z = -1, \text{N/A}$

Summary

- ✓ Case 1, required & Case 2, required:
 - ✓ Addition of buffer region on both side should be tried when calculating loudness. (Sometimes very important, sometimes no need.)

- ✓ Case 1, optional
 - ✓ Determining delta-tangent ray is the key point to perform the lossy NTE analysis.



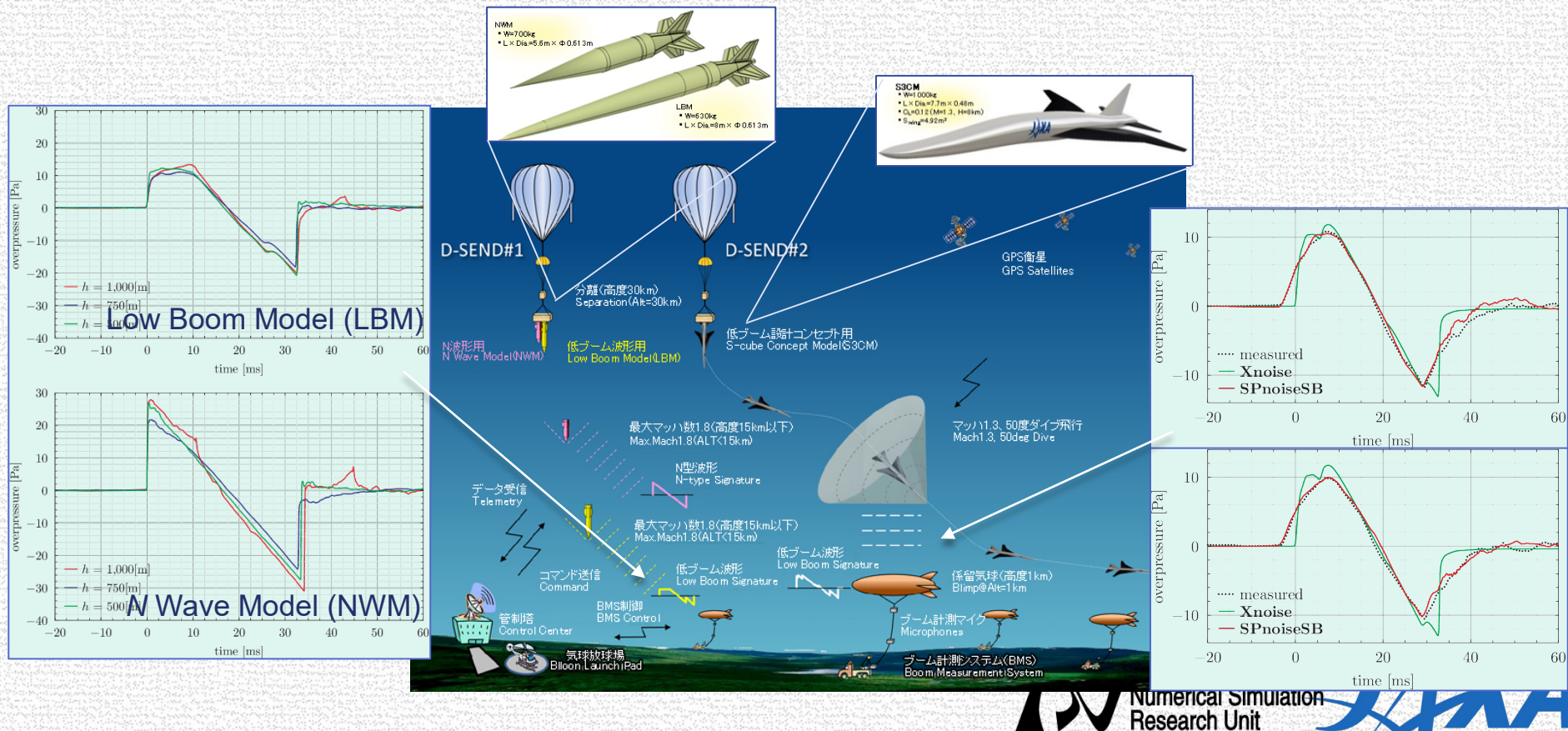
Thank you for your attention!

Any questions?

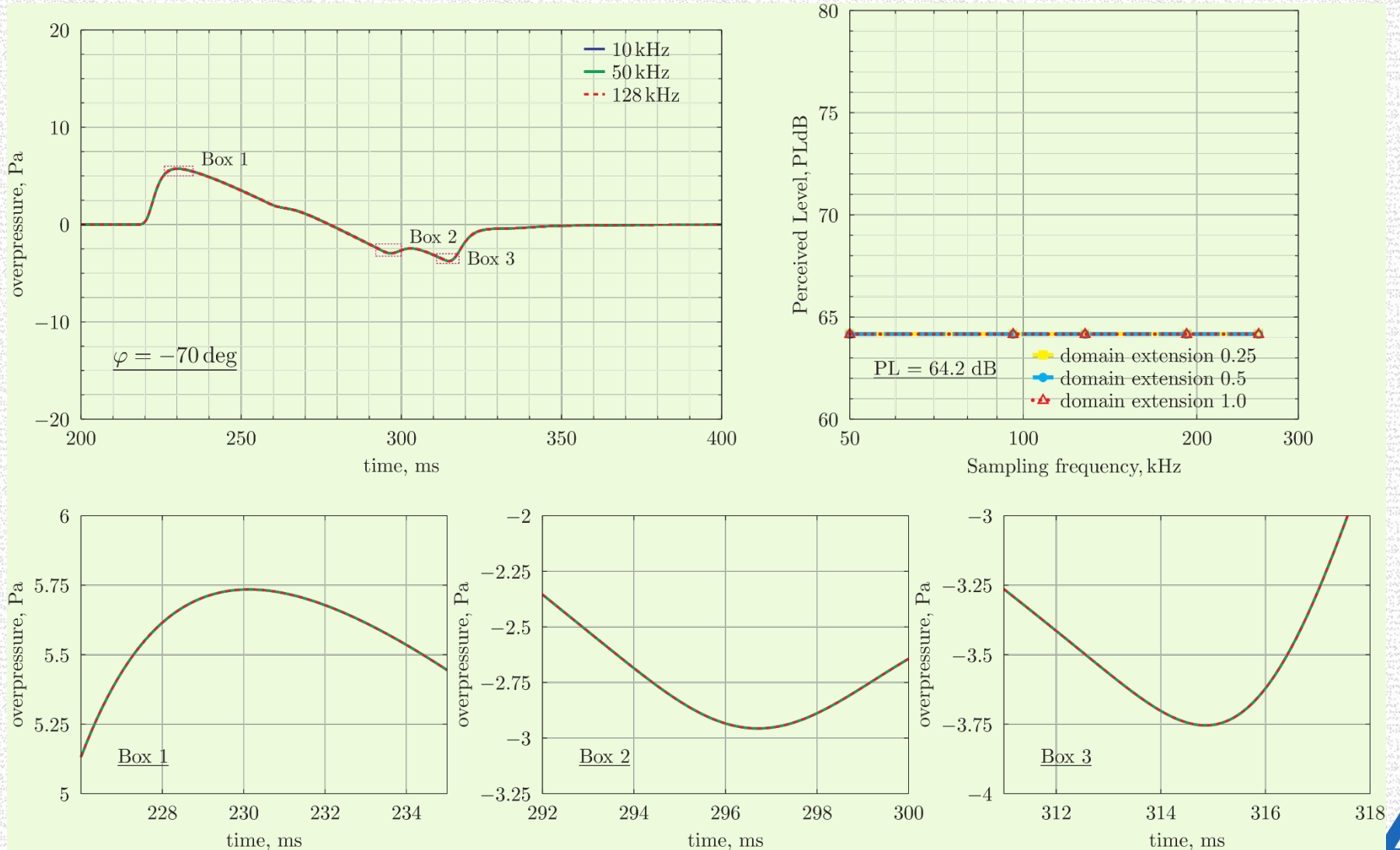
Appendix

D-SEND project in JAXA

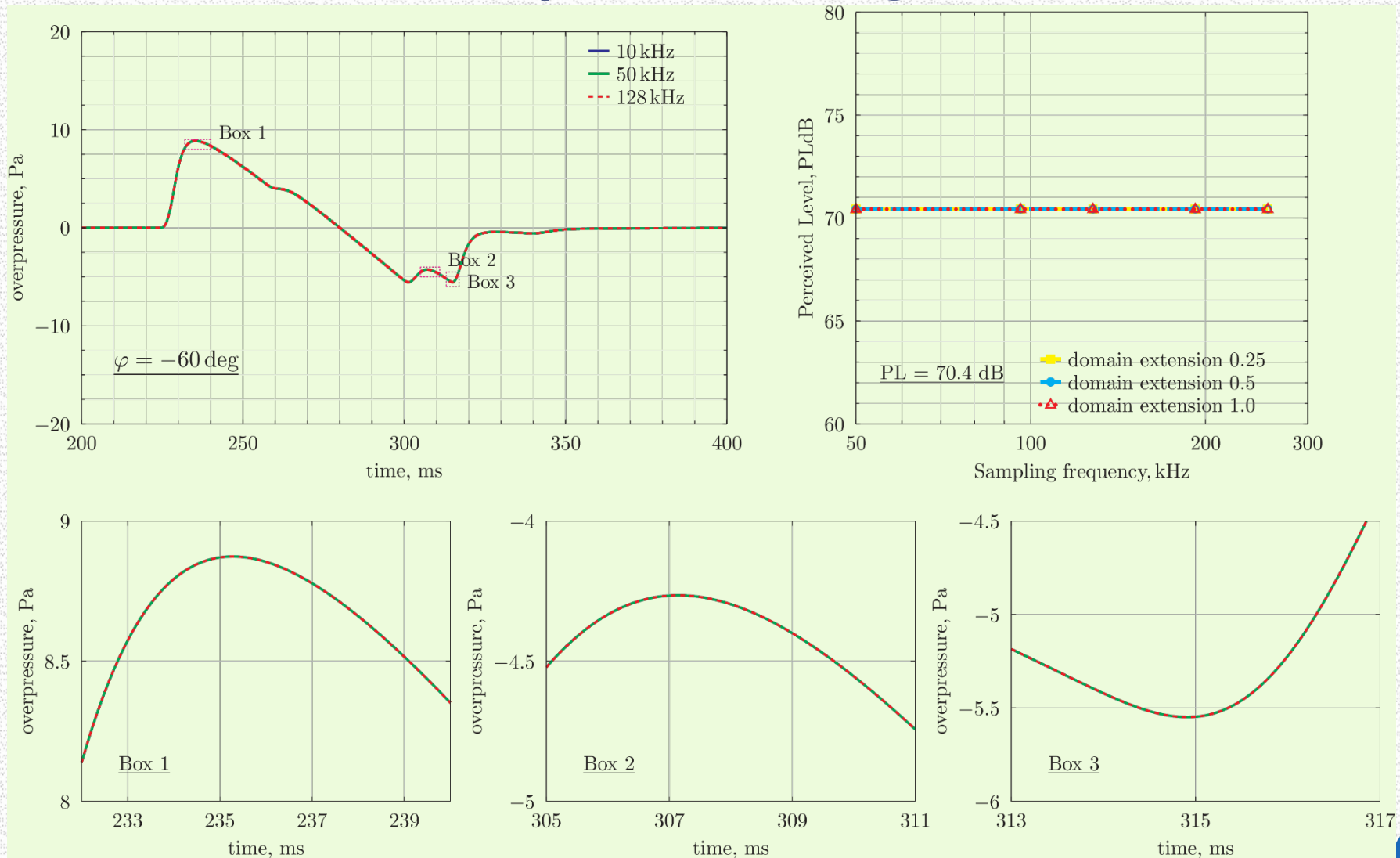
- ✓ Demonstration of JAXA's low-boom design concept
- ✓ D-SEND#1 flight test was successfully performed in 2011 (Bottom left)
- ✓ D-SEND#2 flight test demonstrated our design concept (Bottom right)



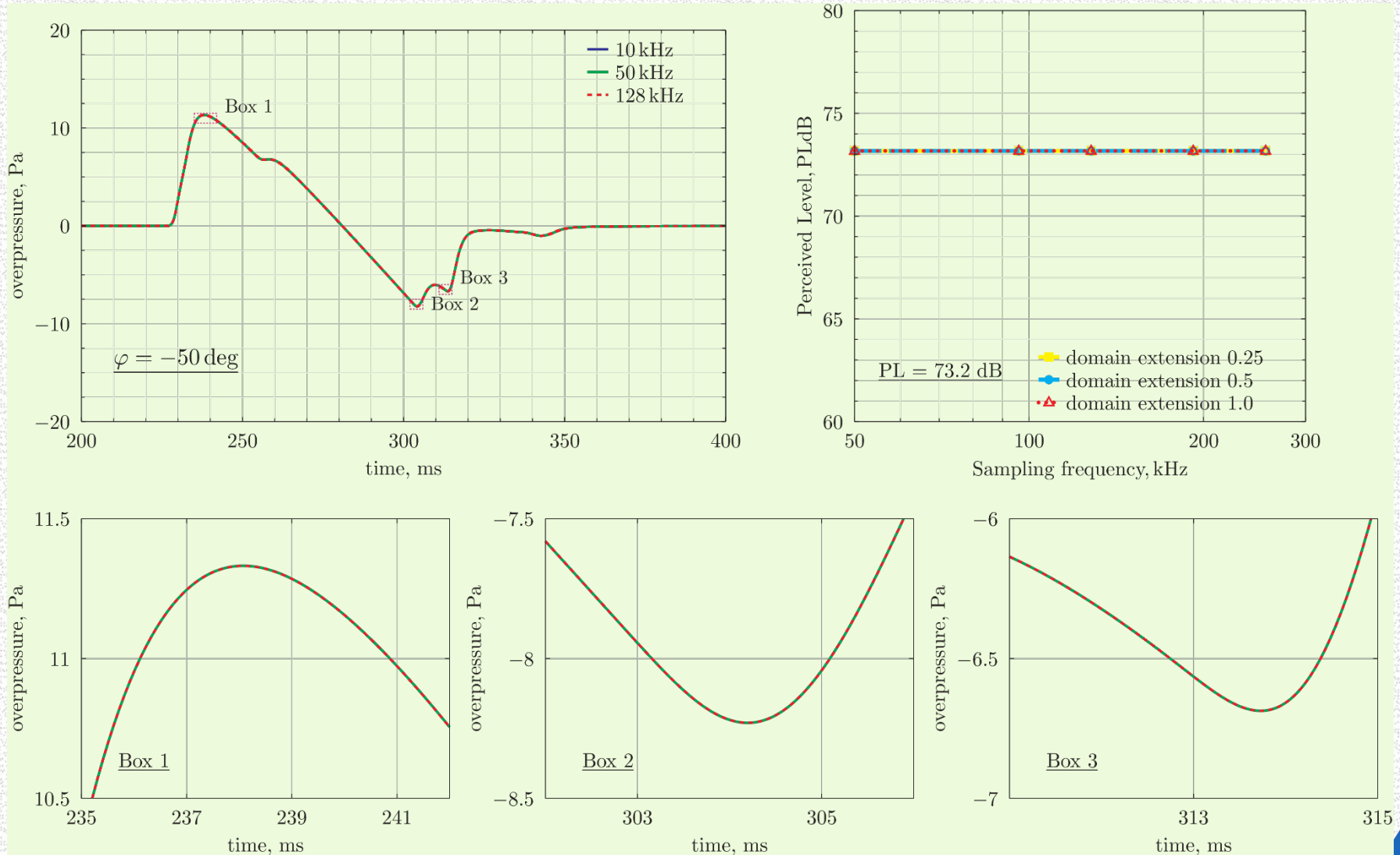
Case 1, Required, $\varphi = -70$ deg



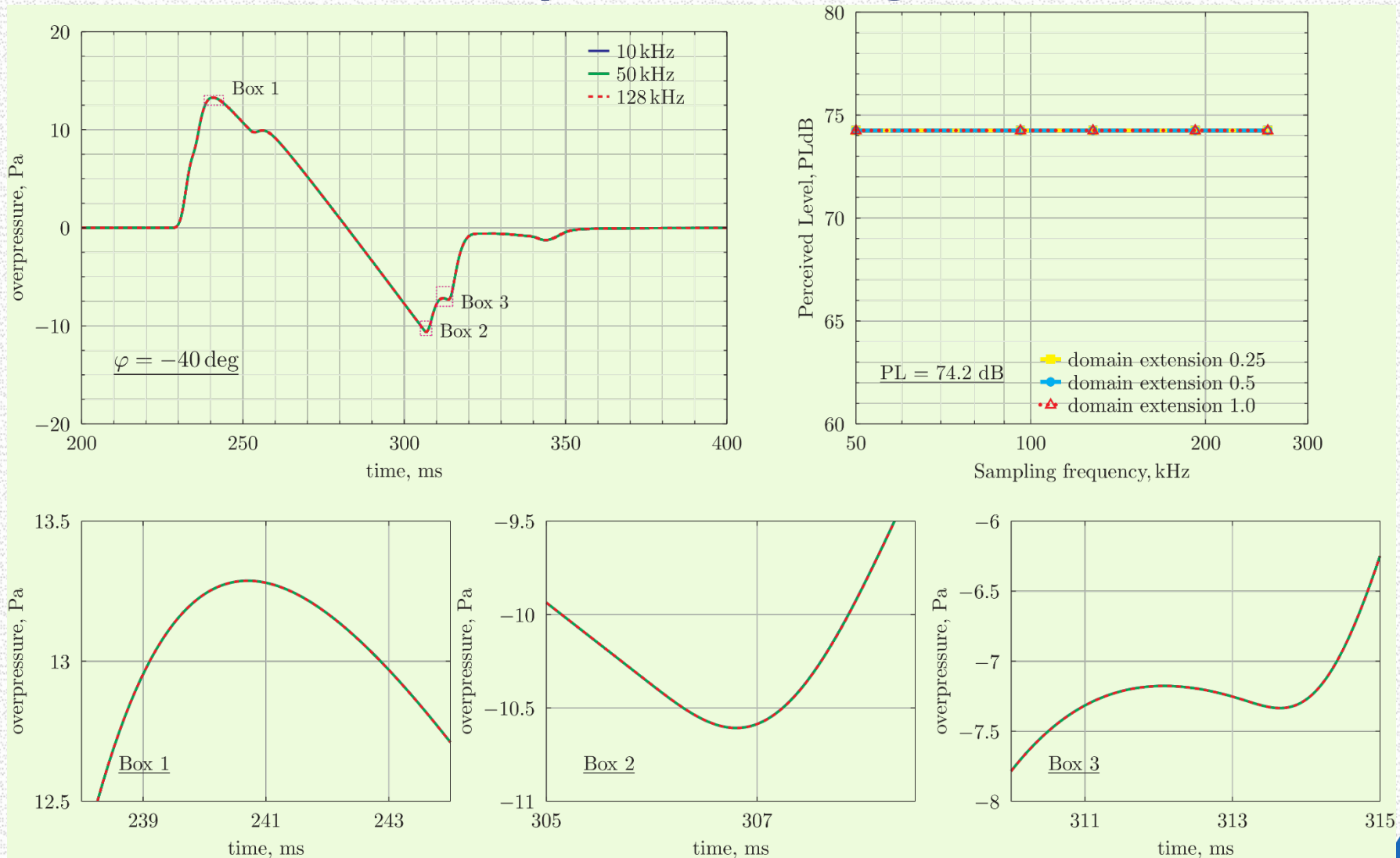
Case 1, Required, $\varphi = -60$ deg



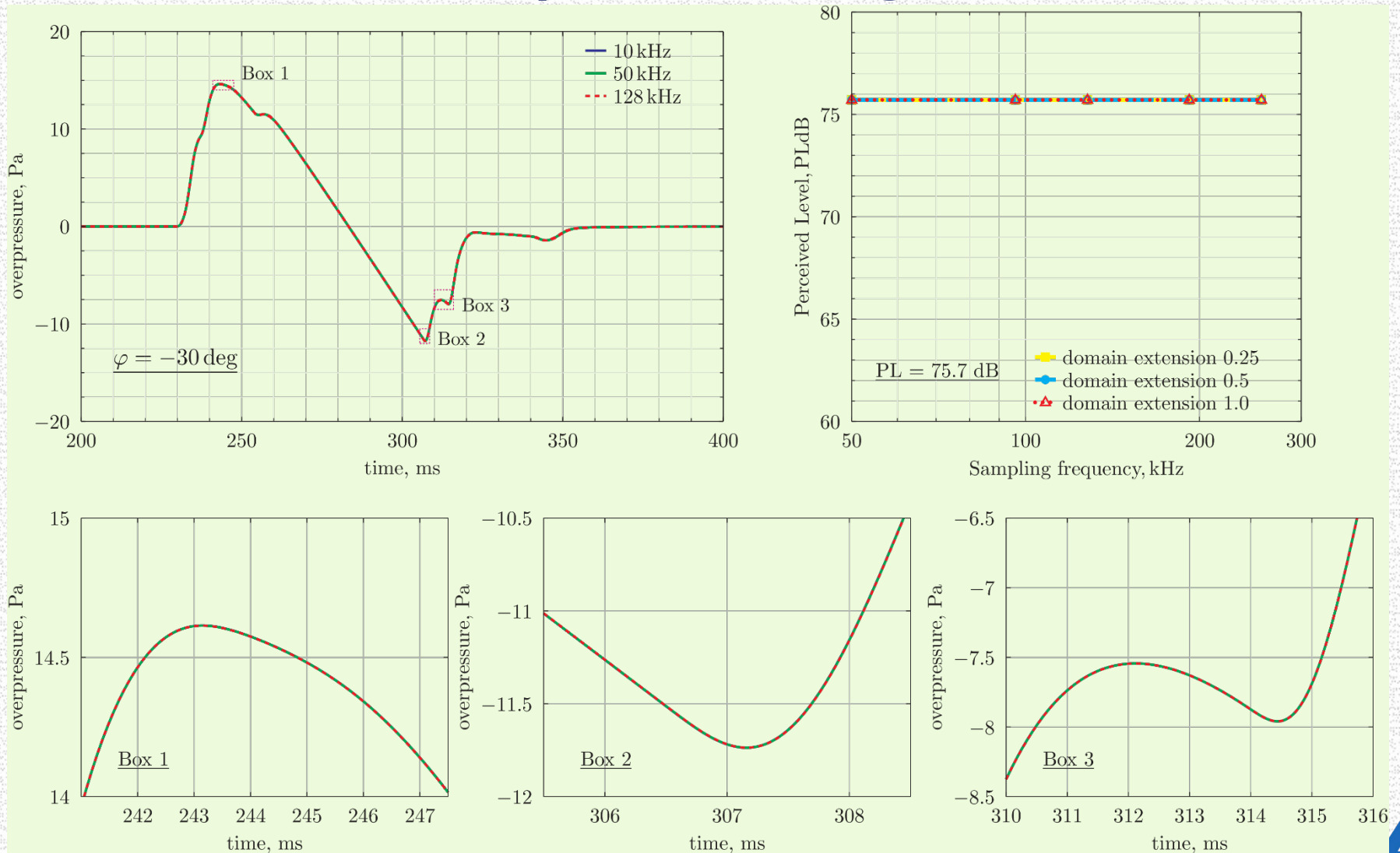
Case 1, Required, $\varphi = -50$ deg



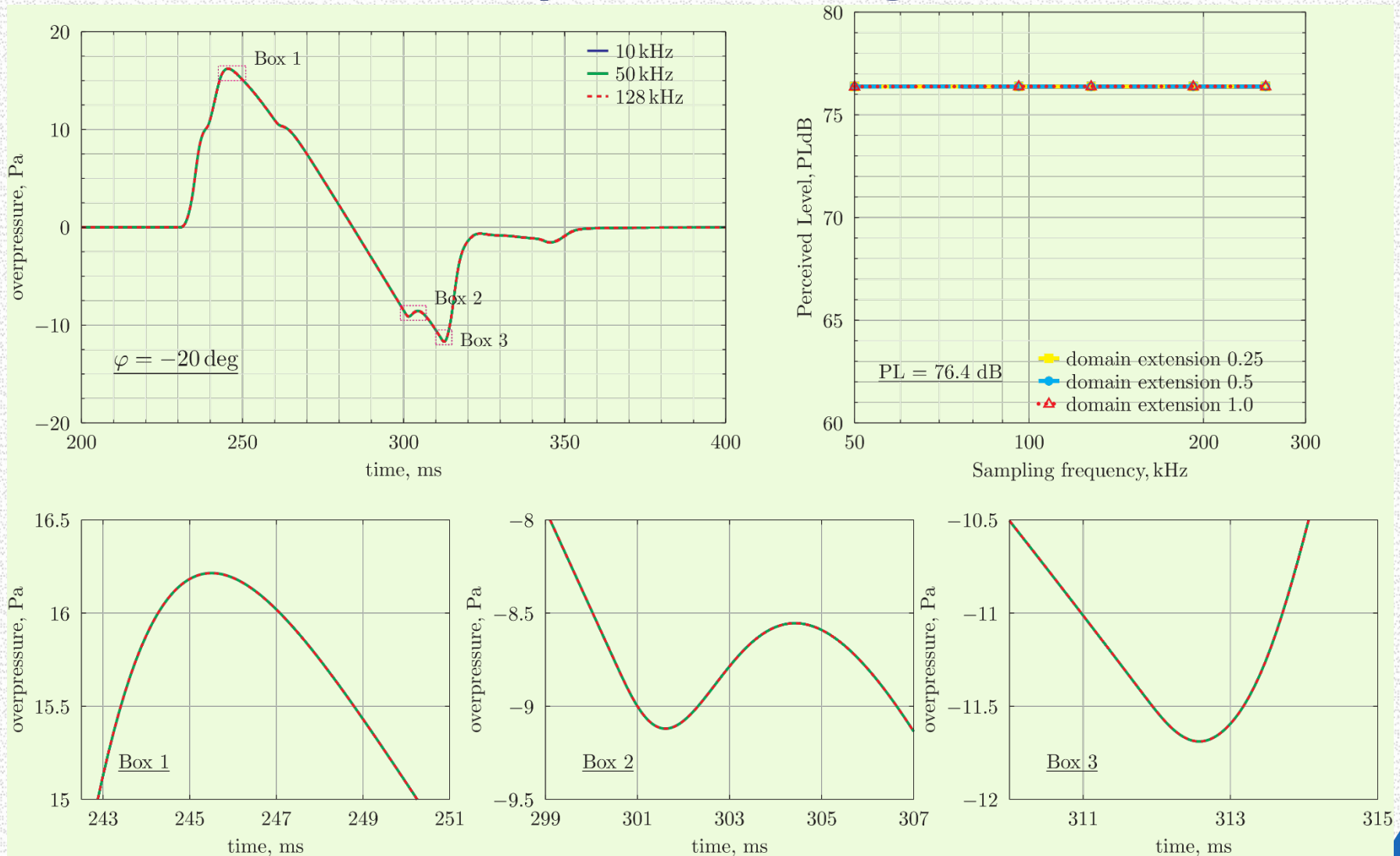
Case 1, Required, $\varphi = -40$ deg



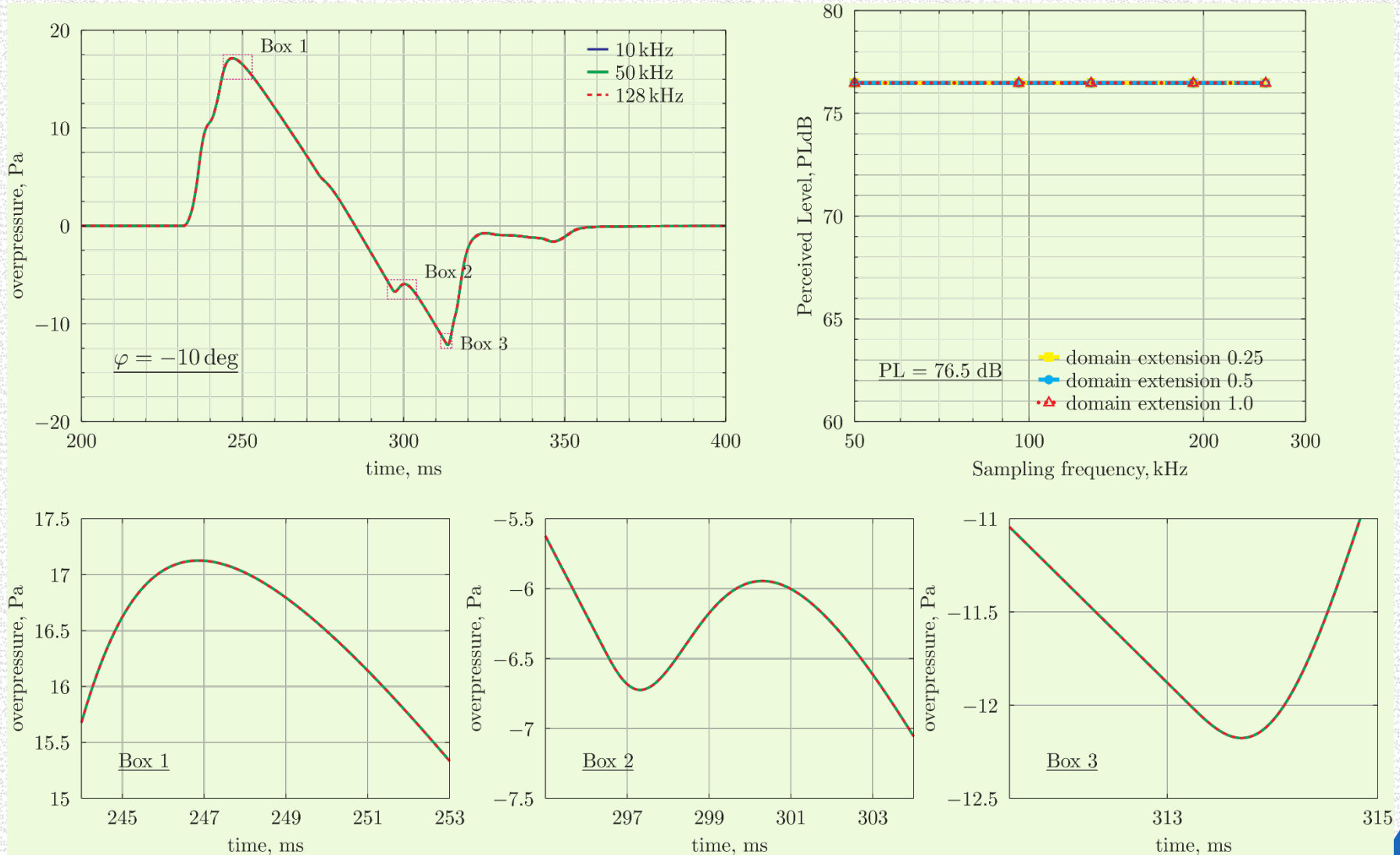
Case 1, Required, $\varphi = -30$ deg



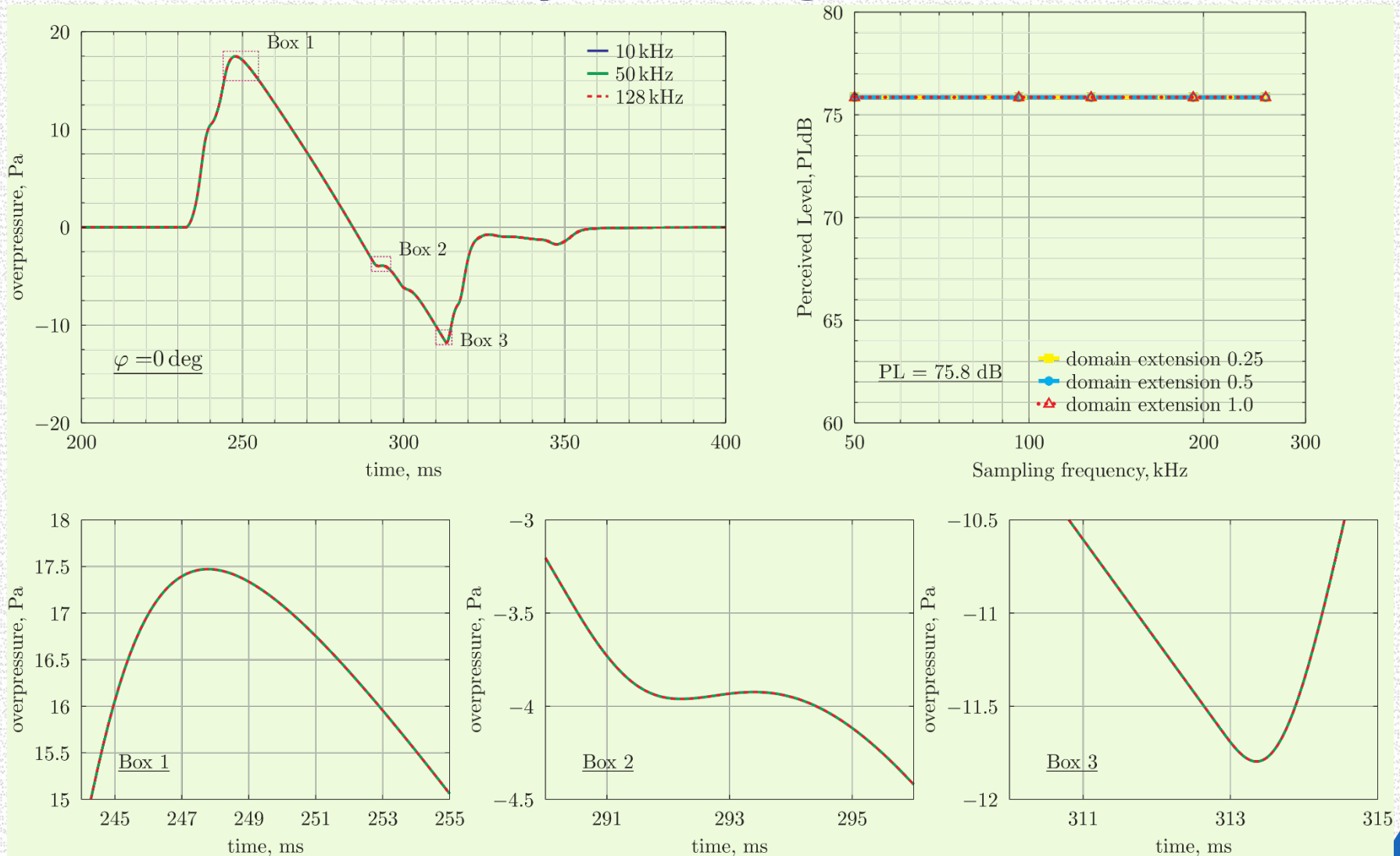
Case 1, Required, $\varphi = -20$ deg



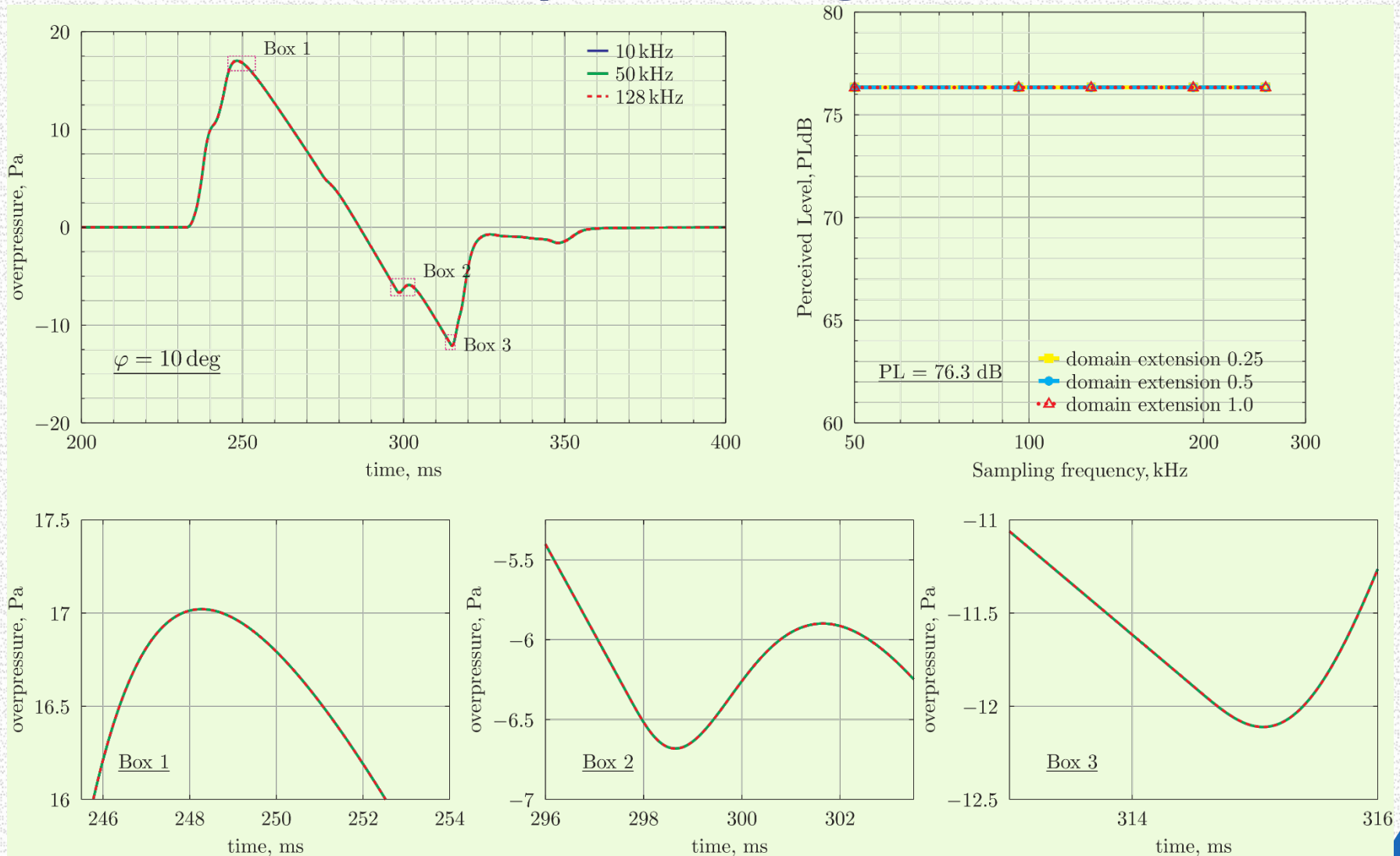
Case 1, Required, $\varphi = -10$ deg



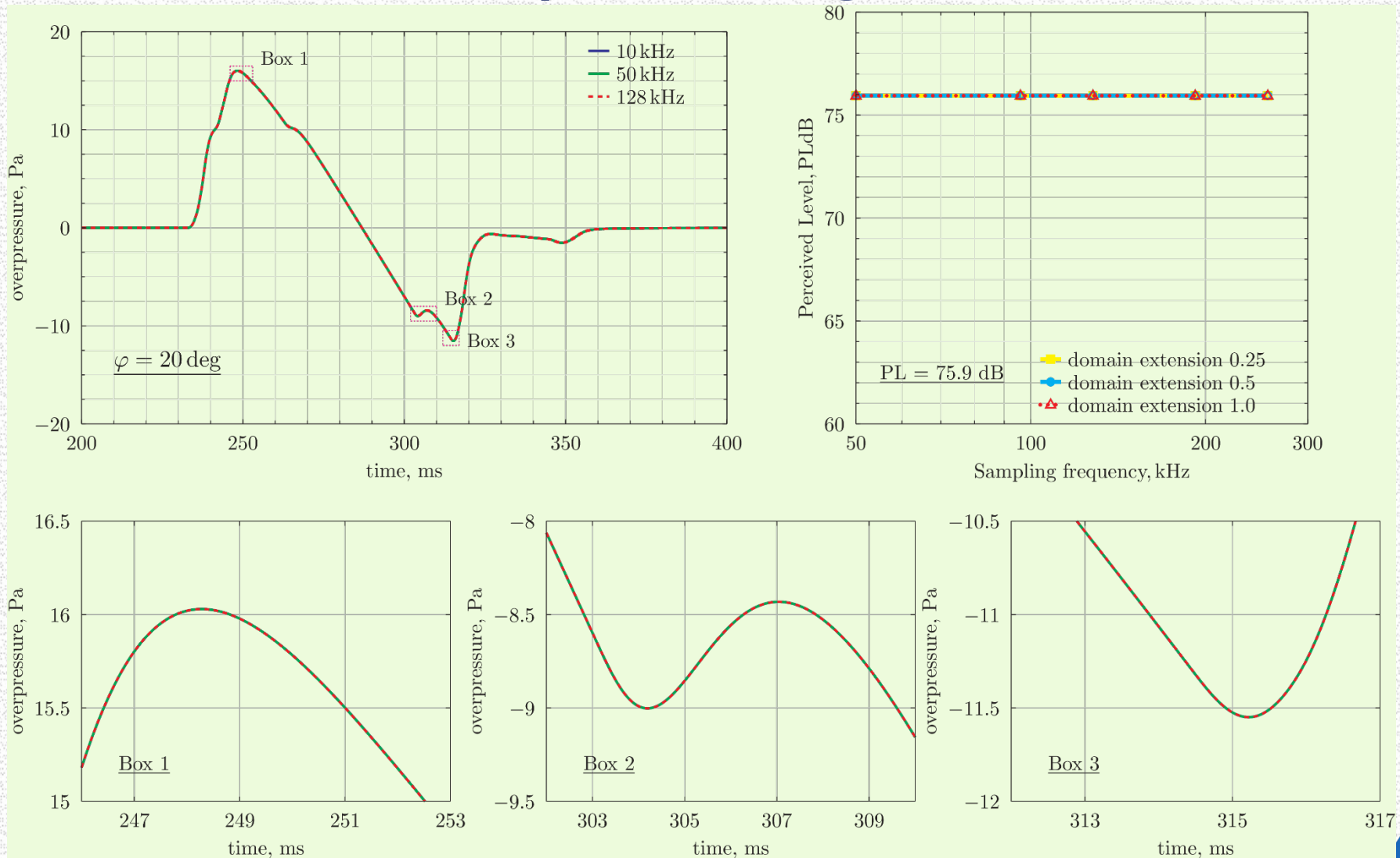
Case 1, Required, $\varphi = 0$ deg



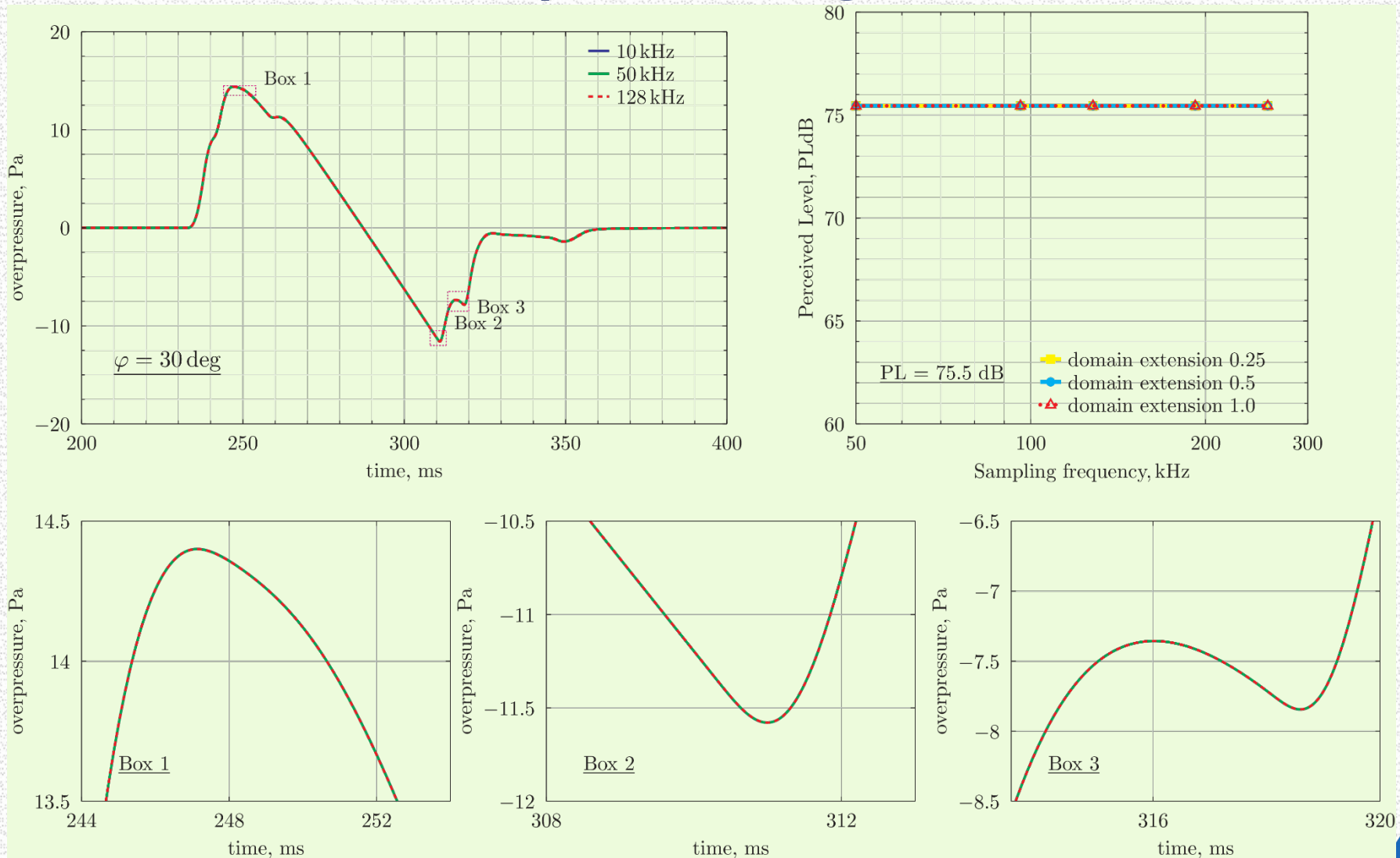
Case 1, Required, $\varphi = 10$ deg



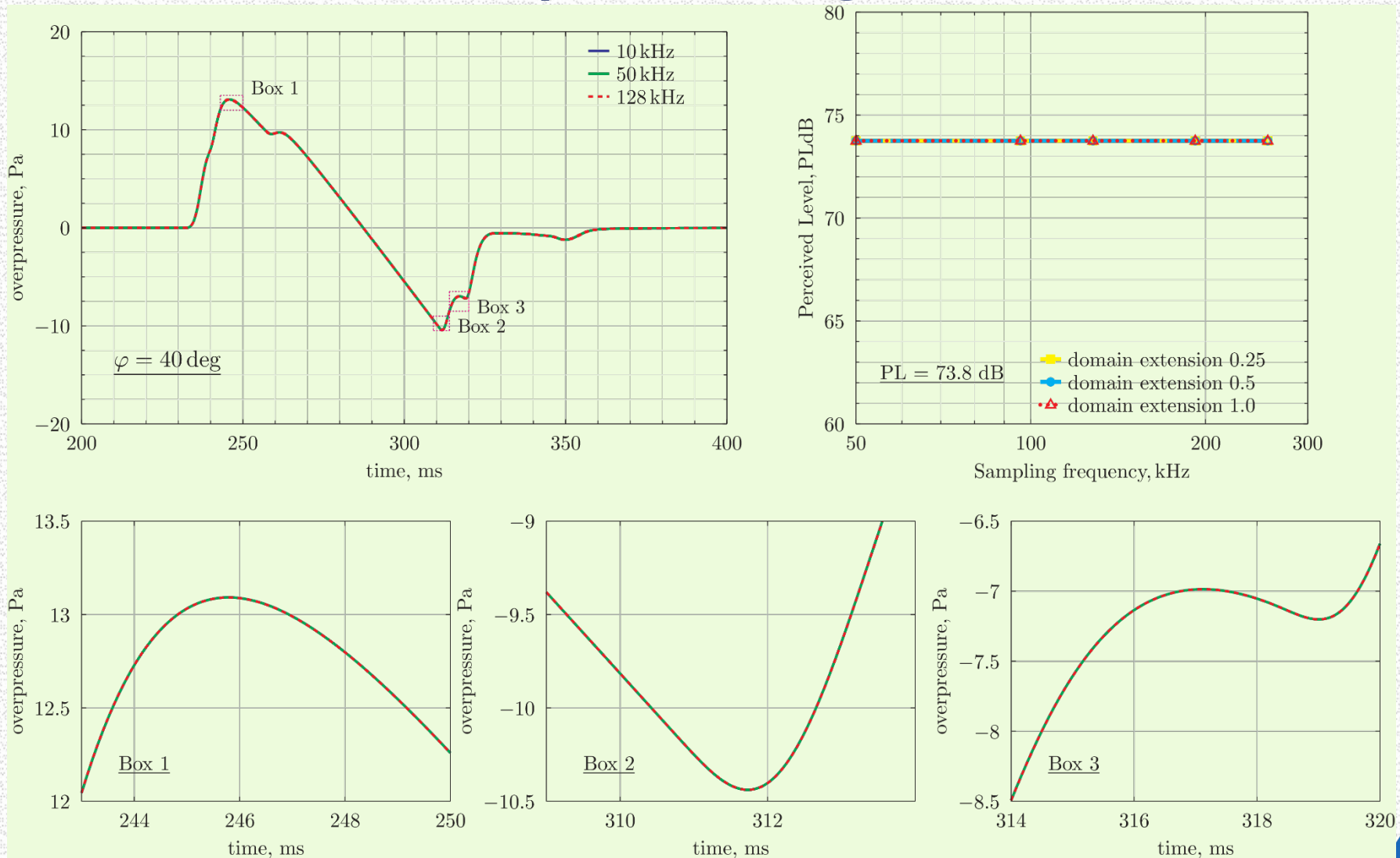
Case 1, Required, $\varphi = 20$ deg



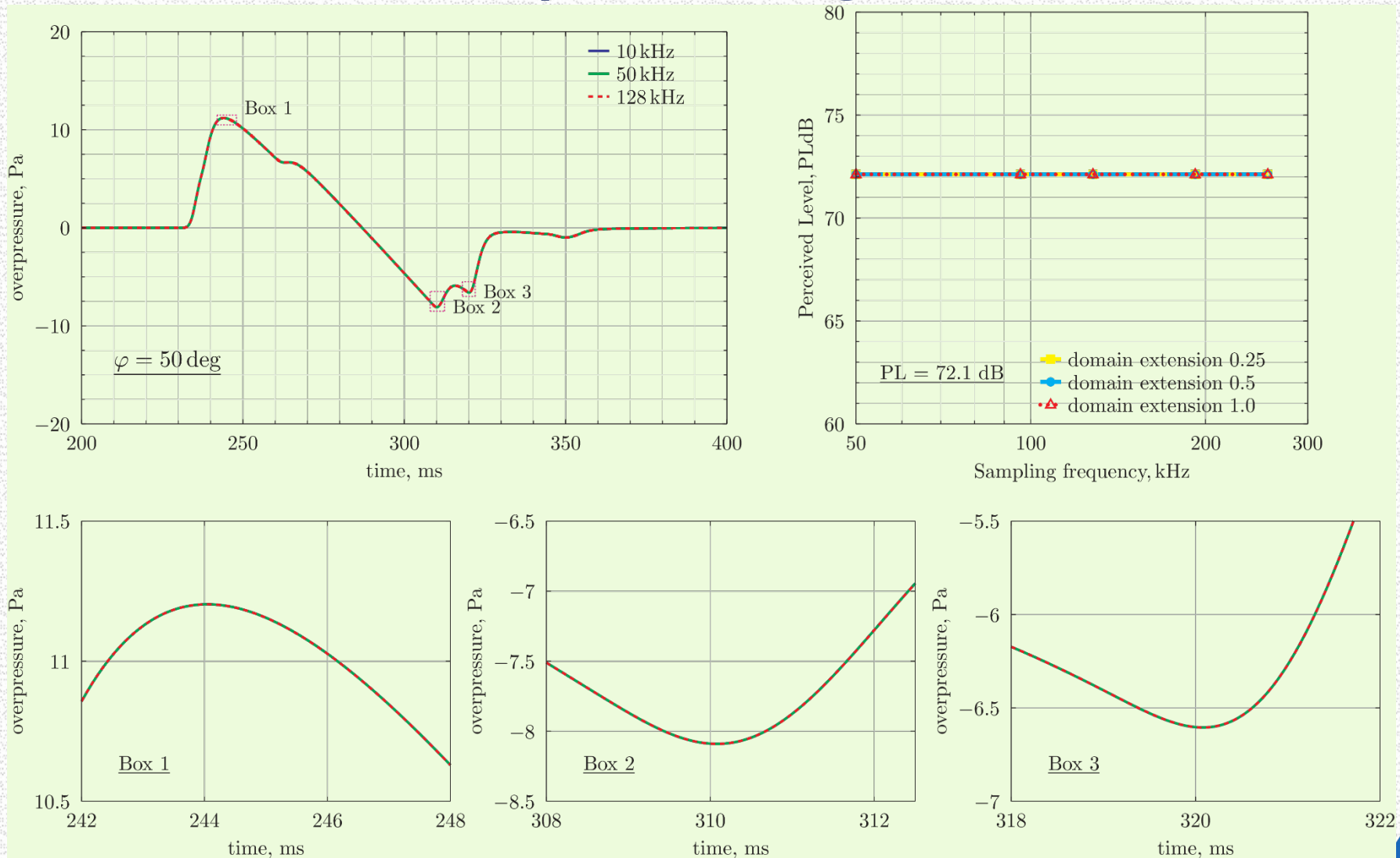
Case 1, Required, $\varphi = 30$ deg



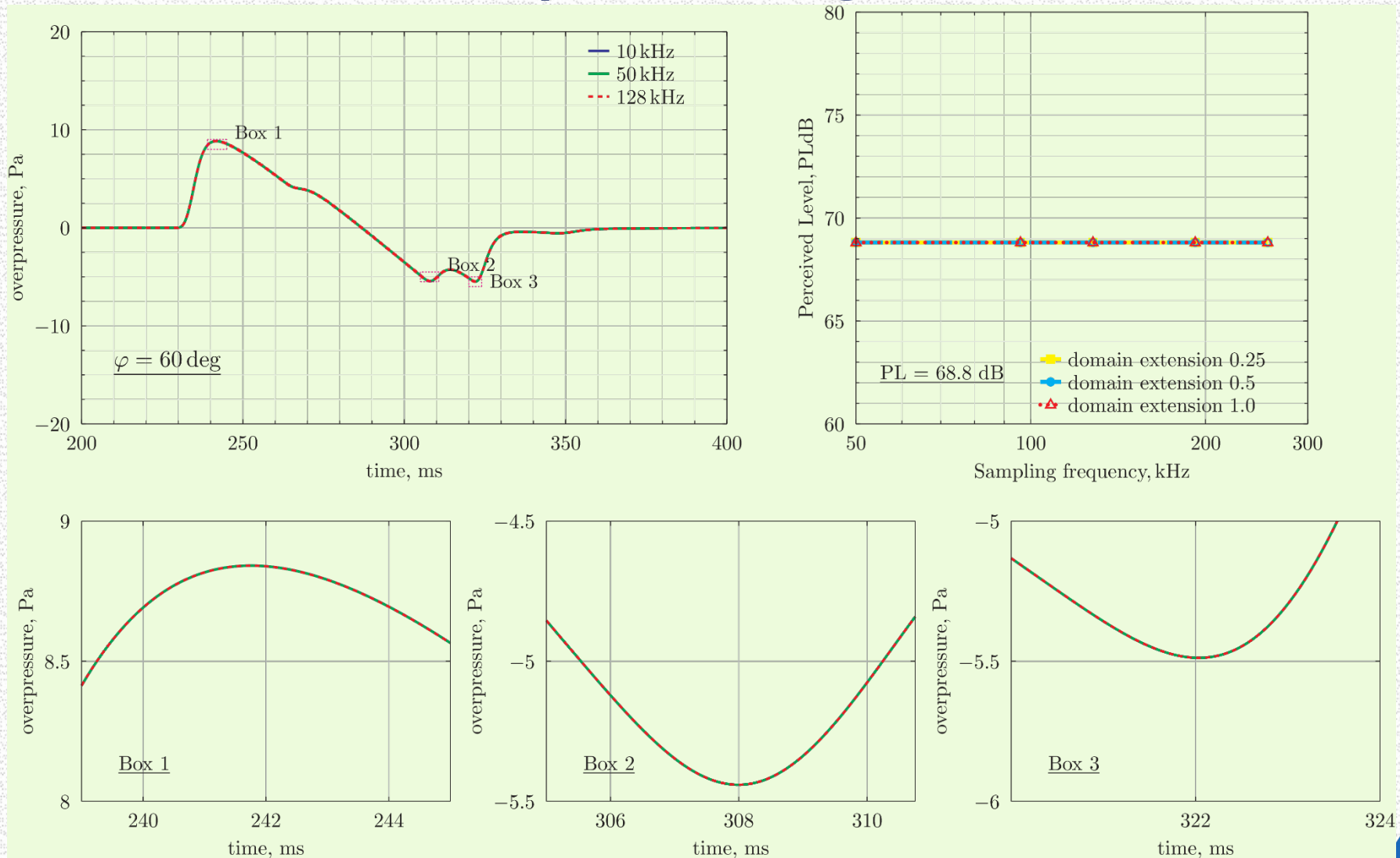
Case 1, Required, $\varphi = 40$ deg



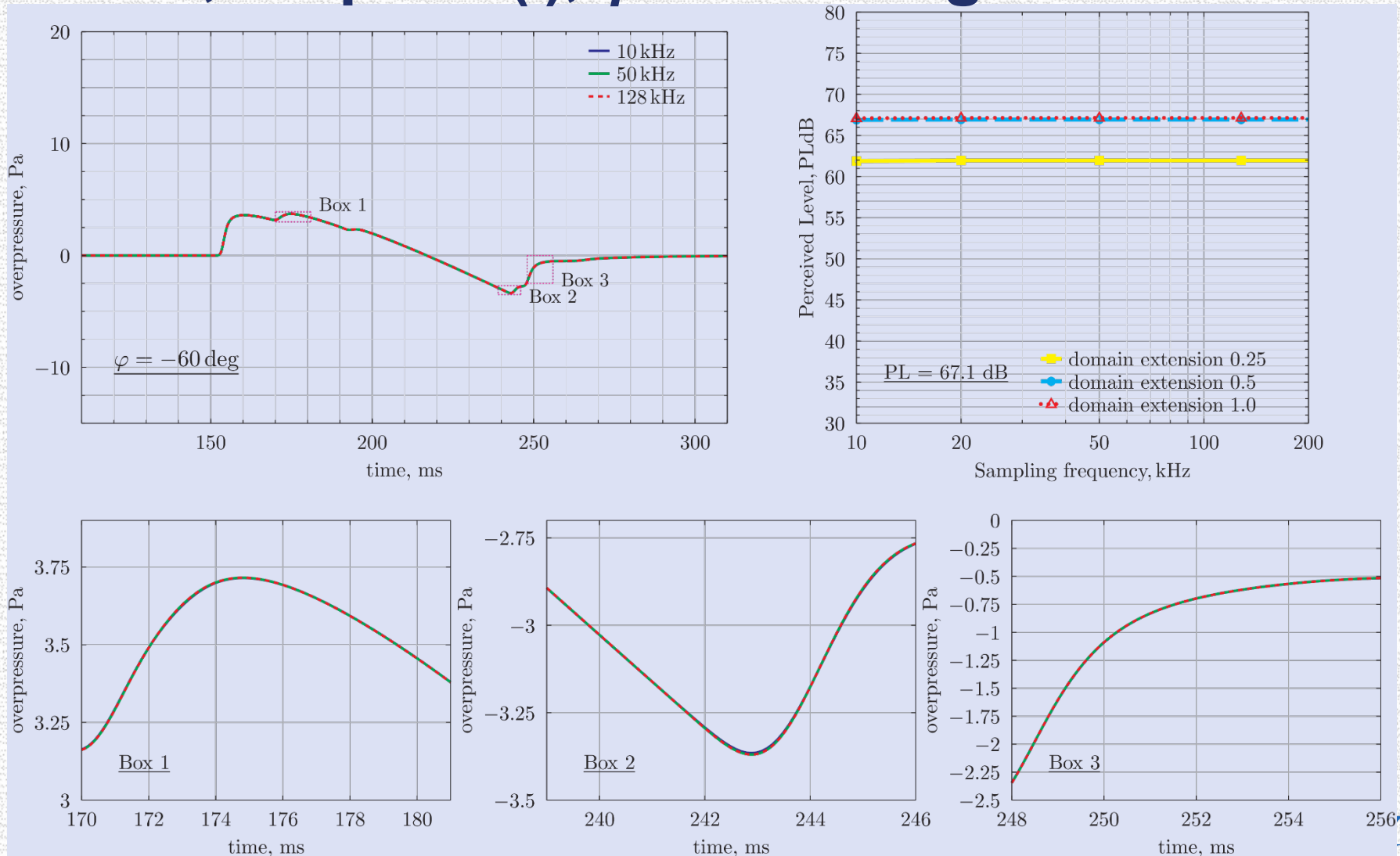
Case 1, Required, $\varphi = 50$ deg



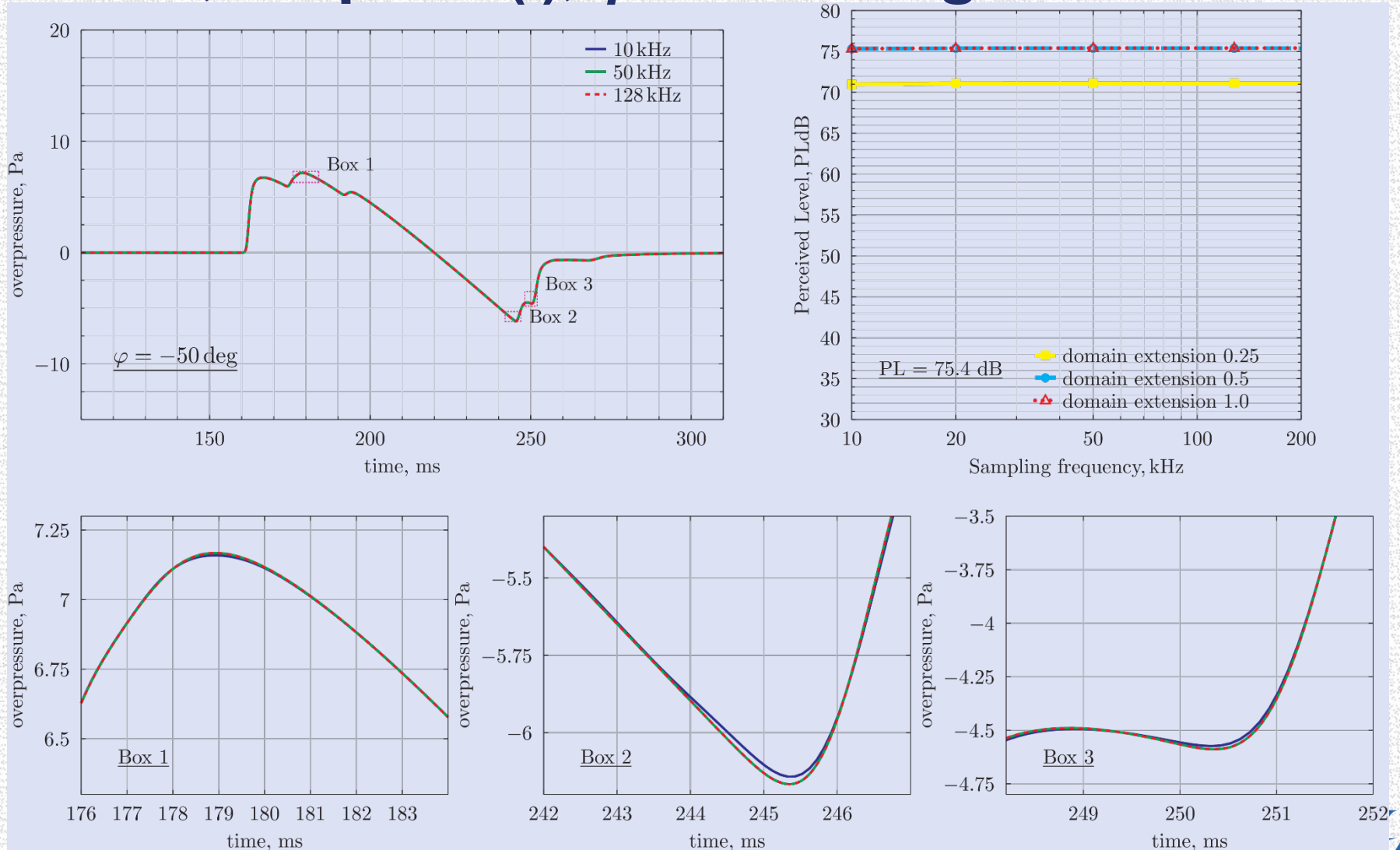
Case 1, Required, $\varphi = 60$ deg



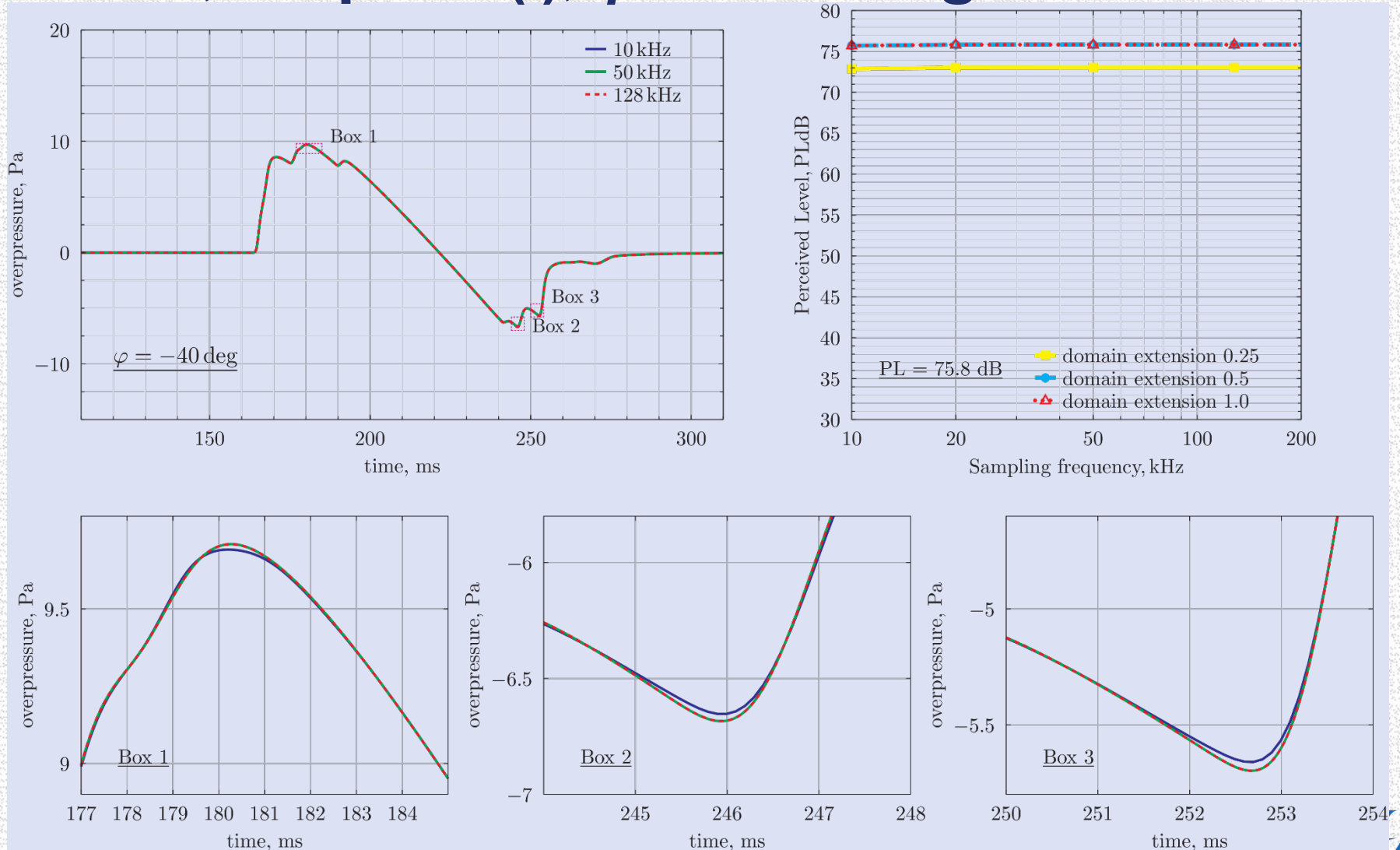
Case 2, Required(i), $\varphi = -60$ deg



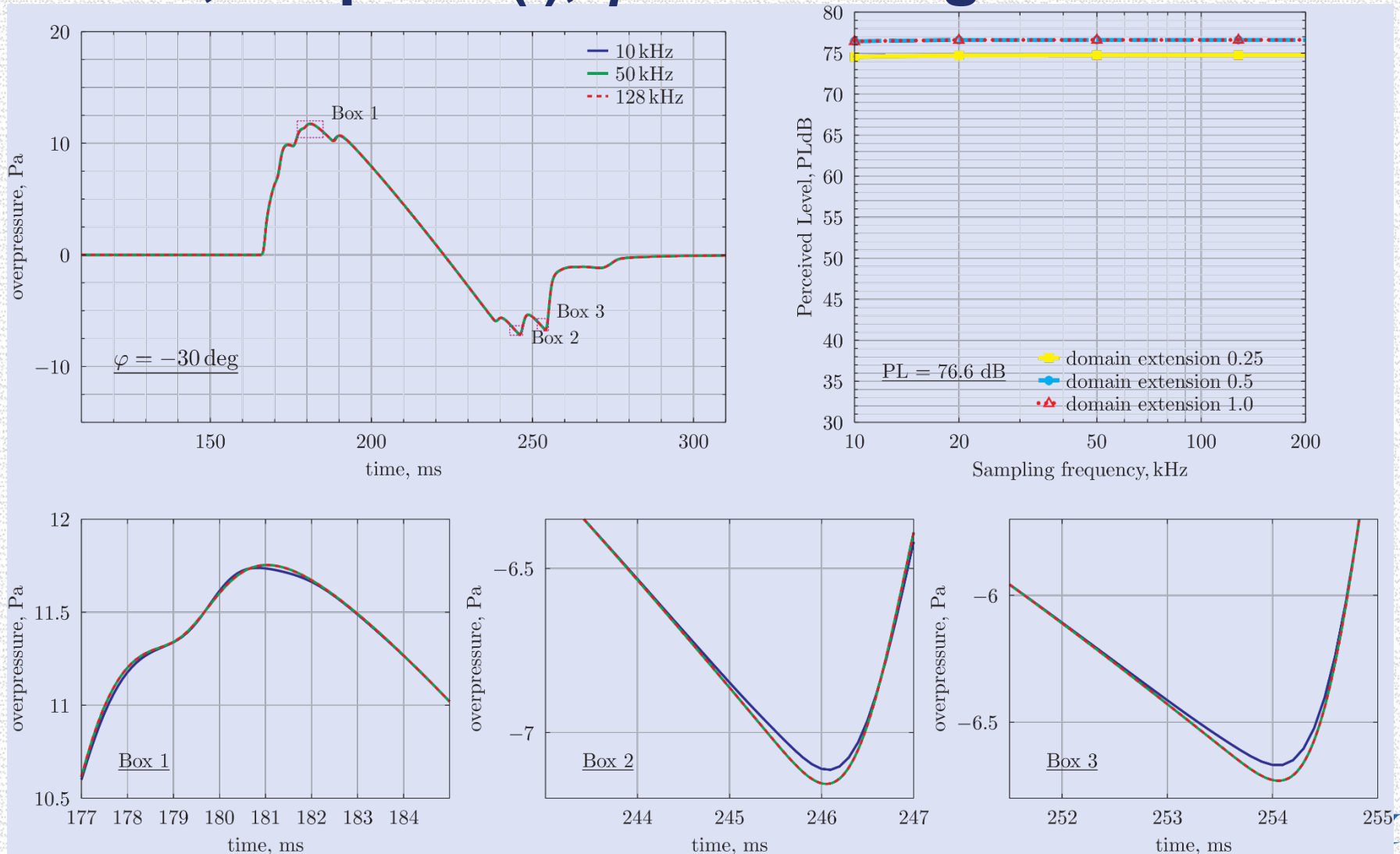
Case 2, Required(i), $\varphi = -50$ deg



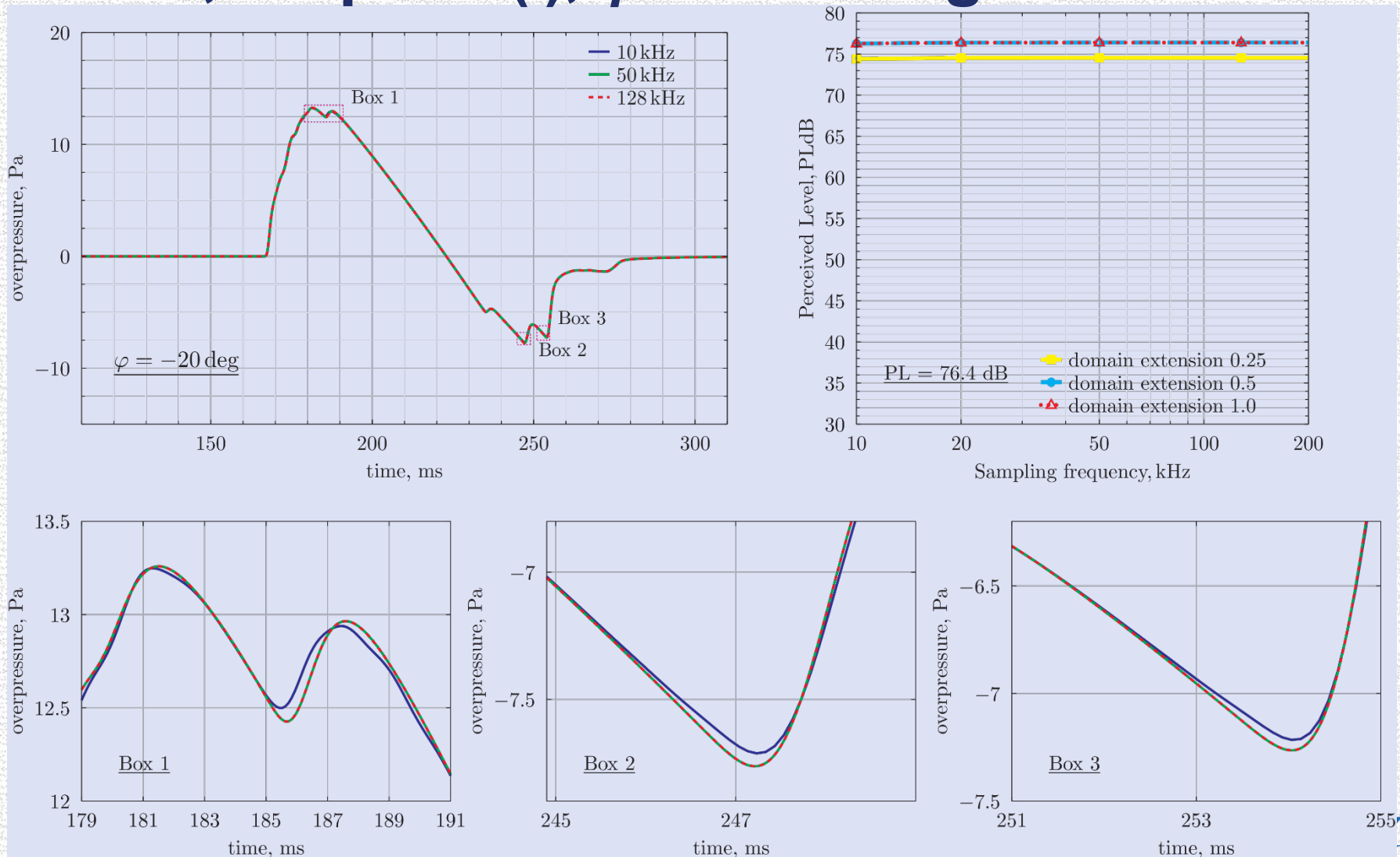
Case 2, Required(i), $\varphi = -40$ deg



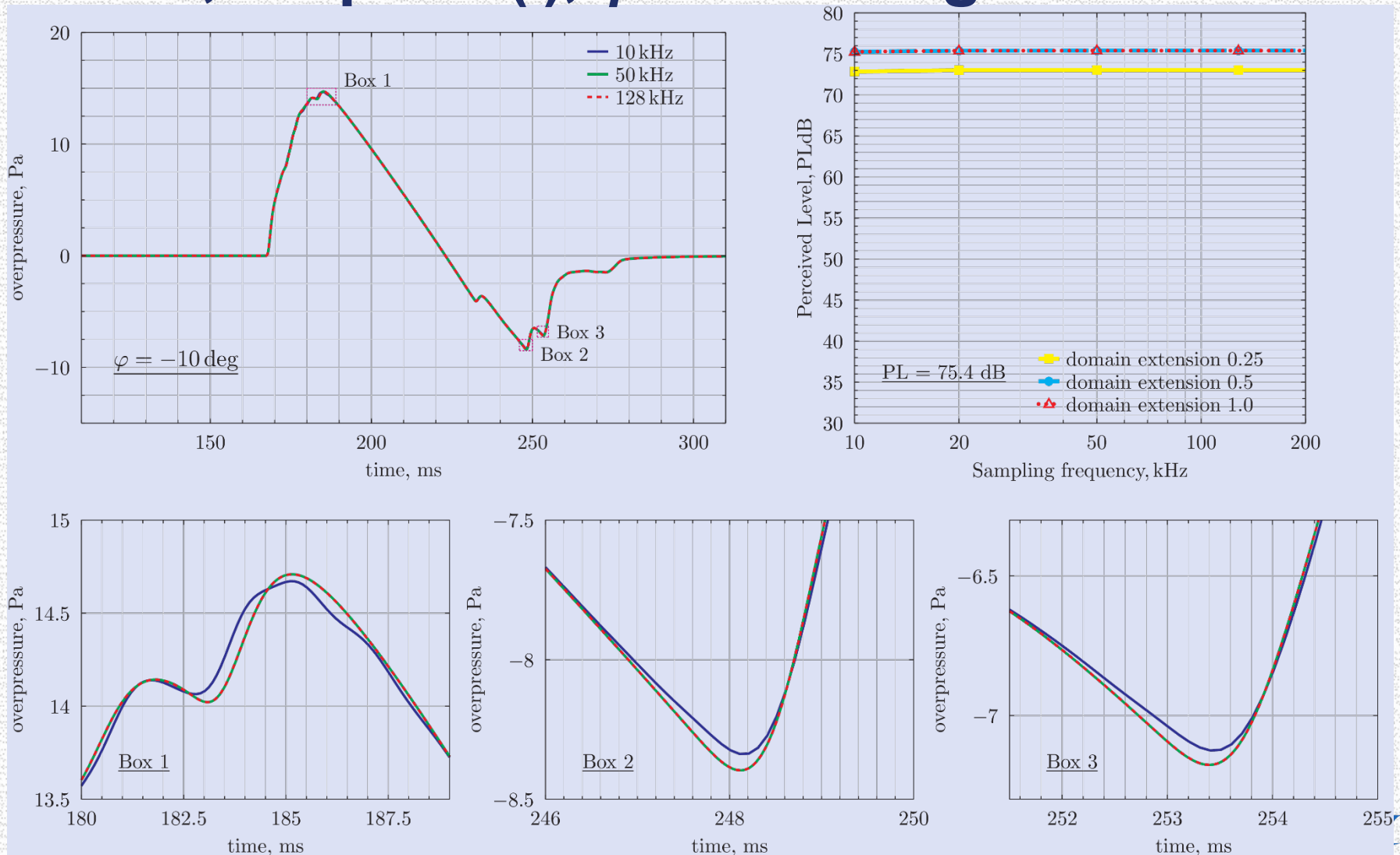
Case 2, Required(i), $\varphi = -30$ deg



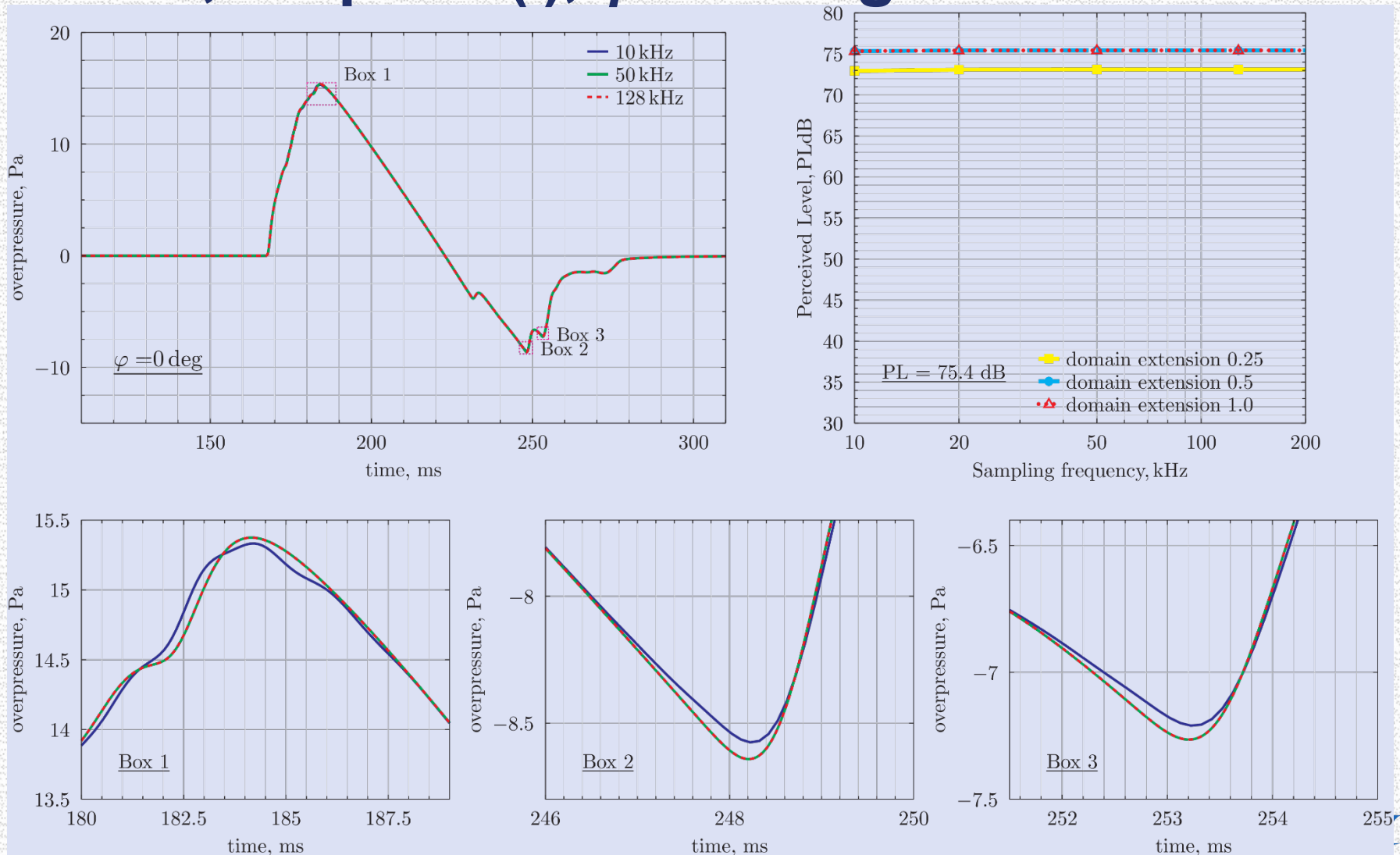
Case 2, Required(i), $\varphi = -20$ deg



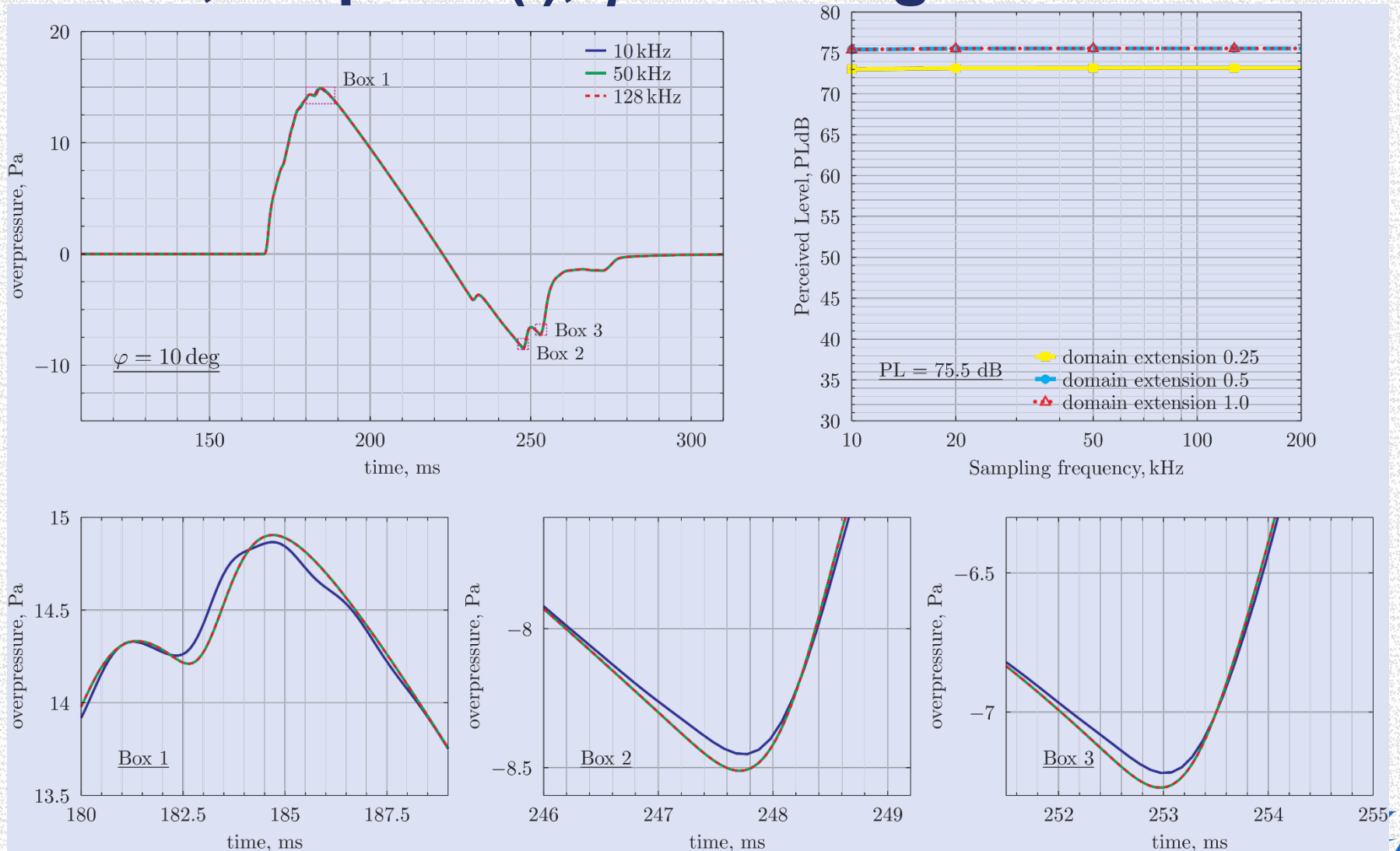
Case 2, Required(i), $\varphi = -10$ deg



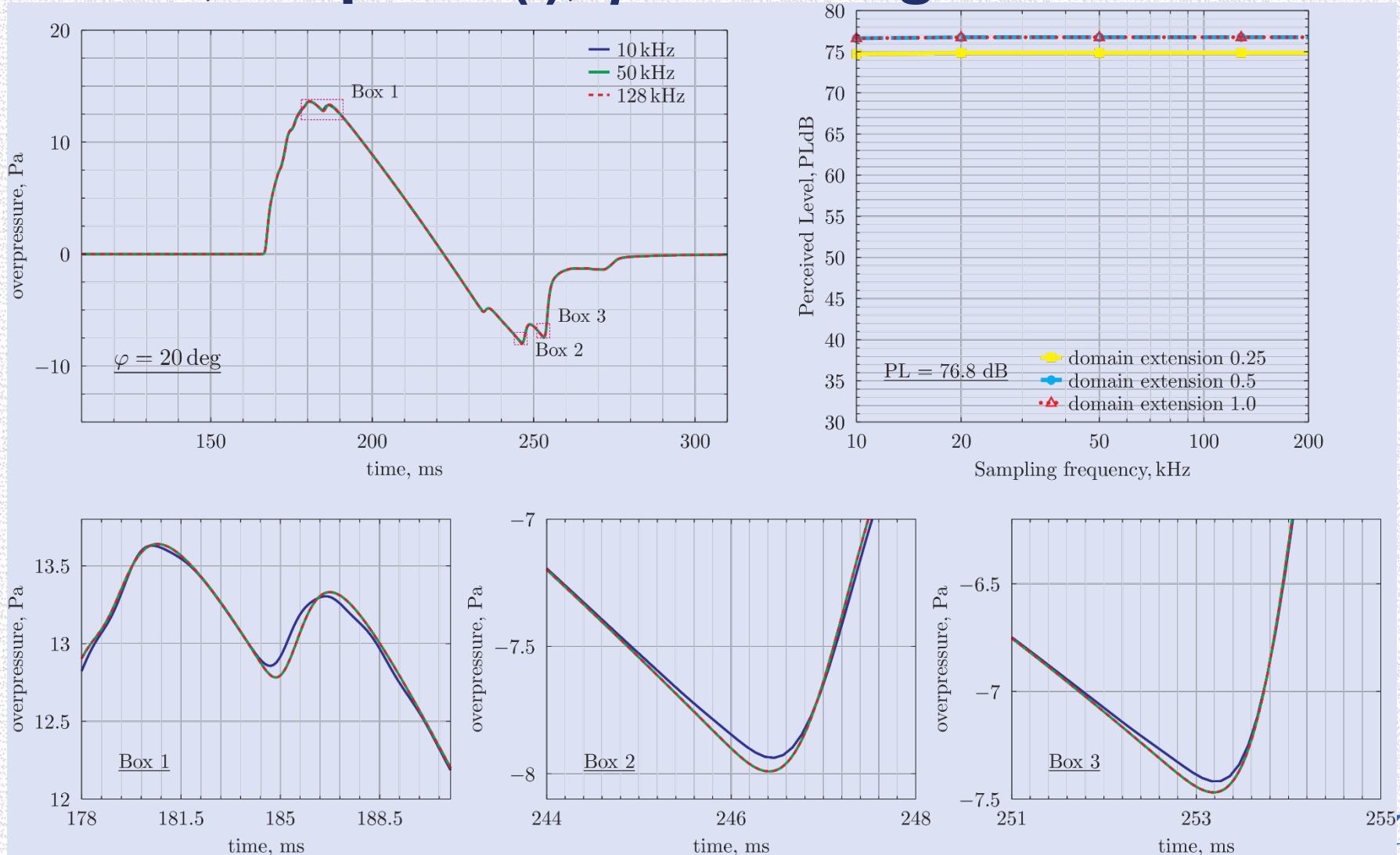
Case 2, Required(i), $\varphi = 0$ deg



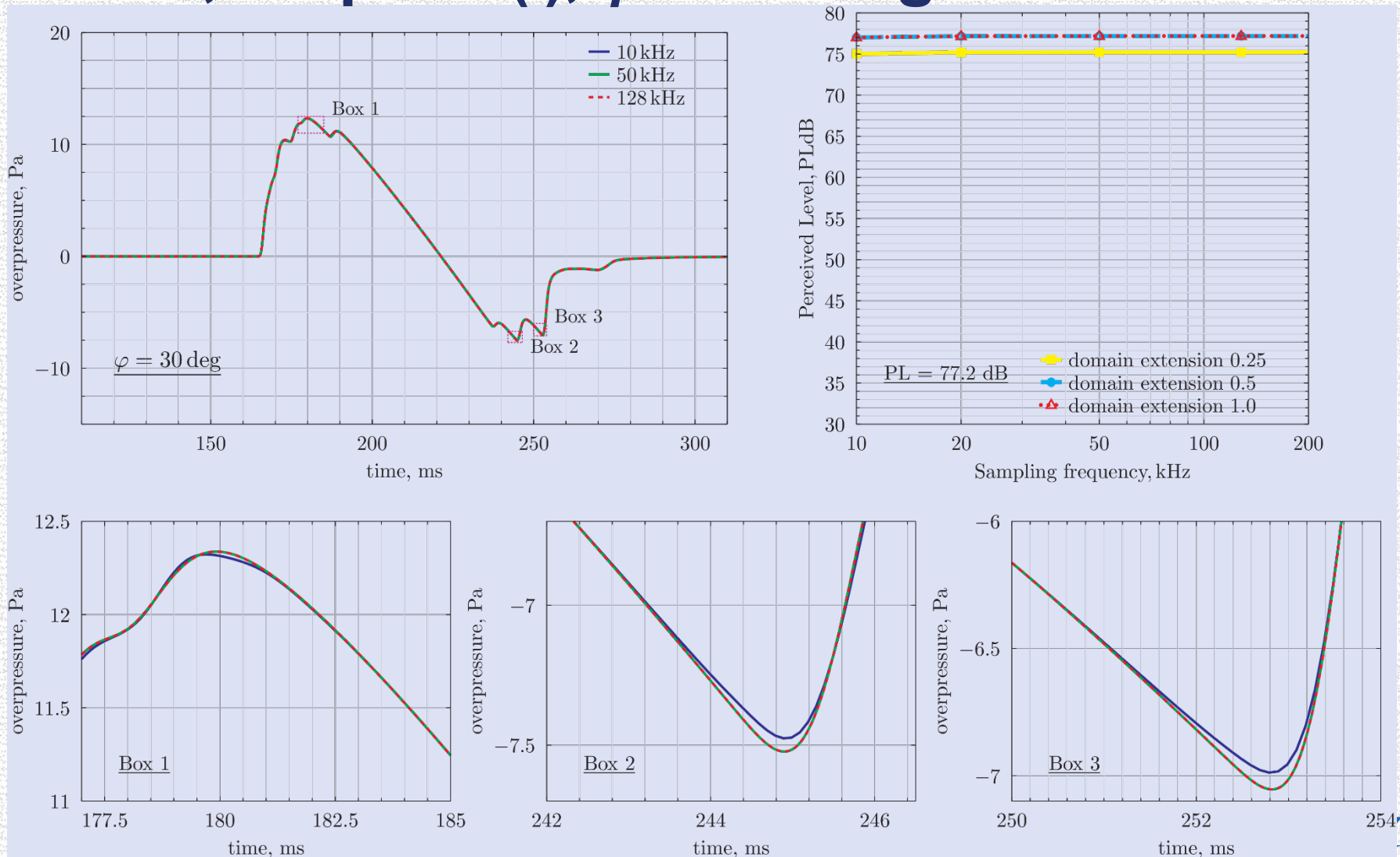
Case 2, Required(i), $\varphi = 10$ deg



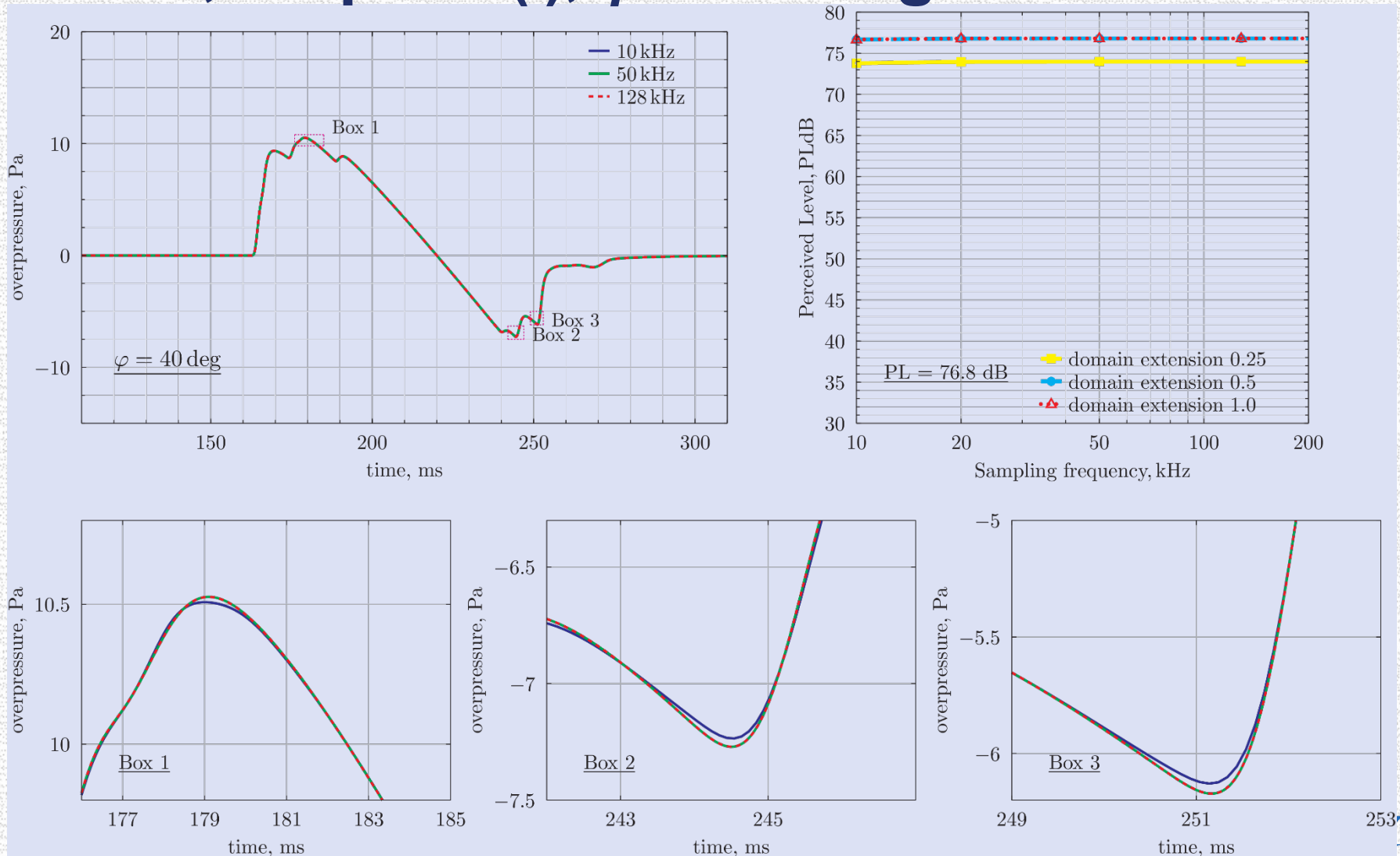
Case 2, Required(i), $\varphi = 20$ deg



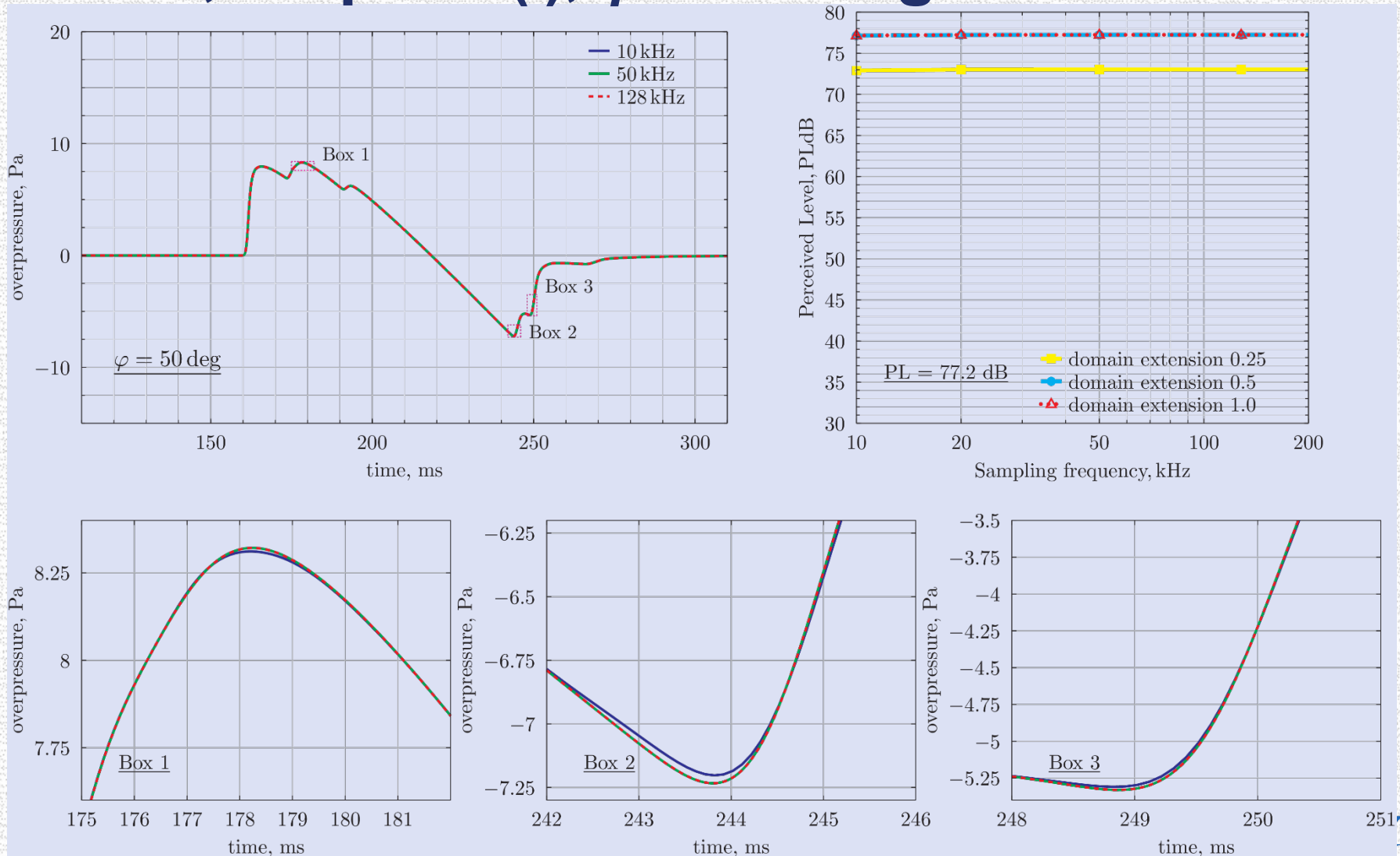
Case 2, Required(i), $\varphi = 30$ deg



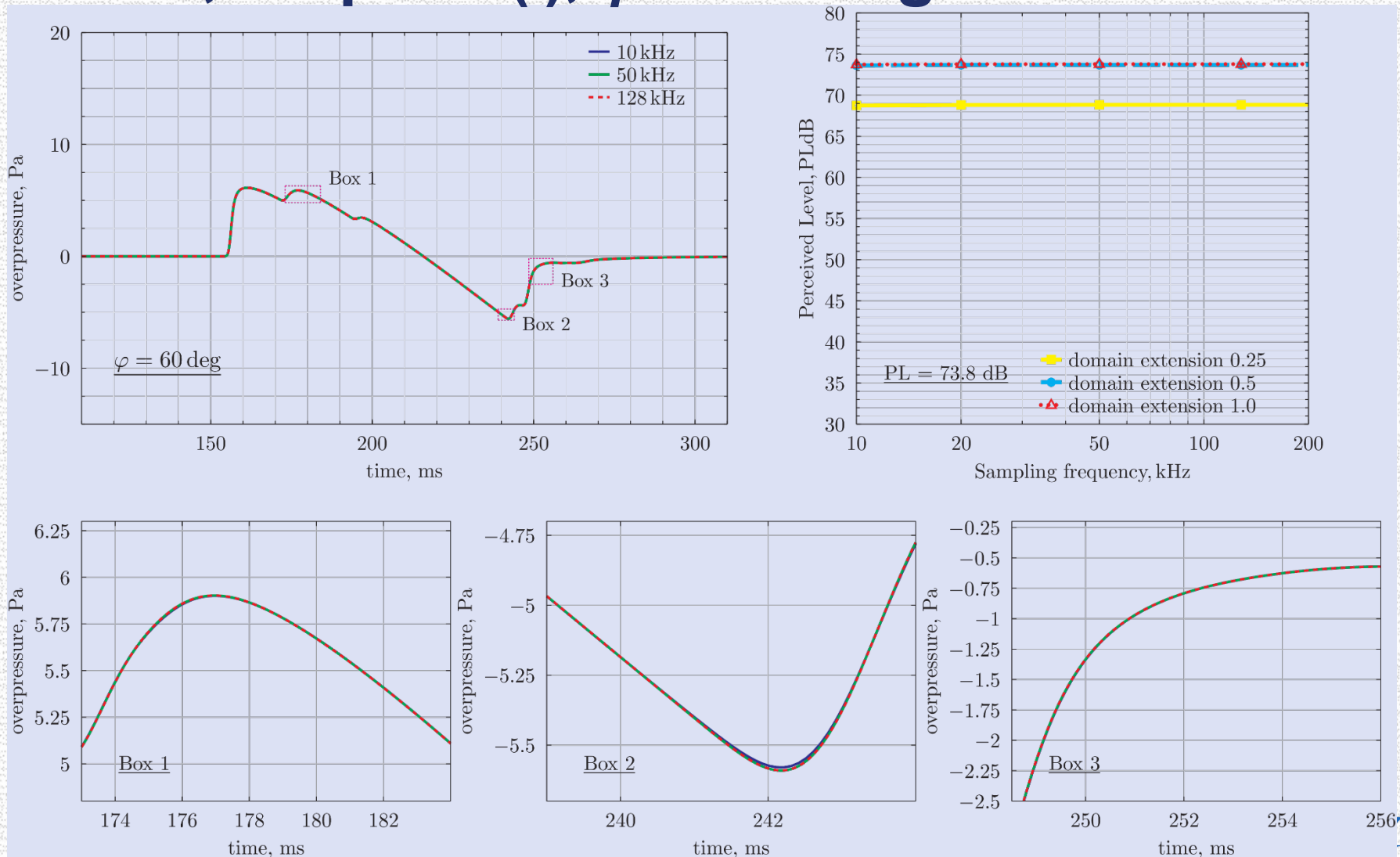
Case 2, Required(i), $\varphi = 40$ deg



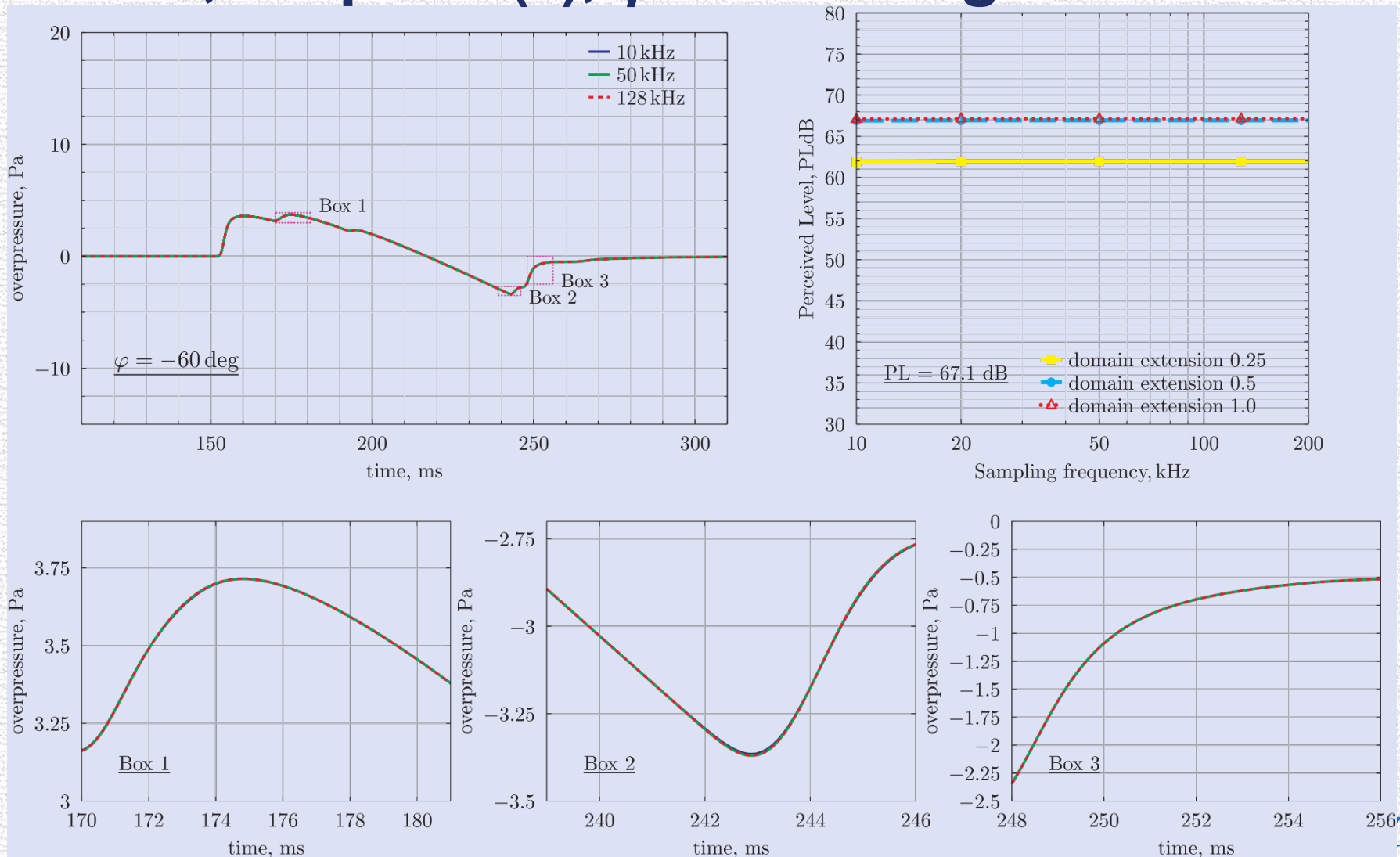
Case 2, Required(i), $\varphi = 50$ deg



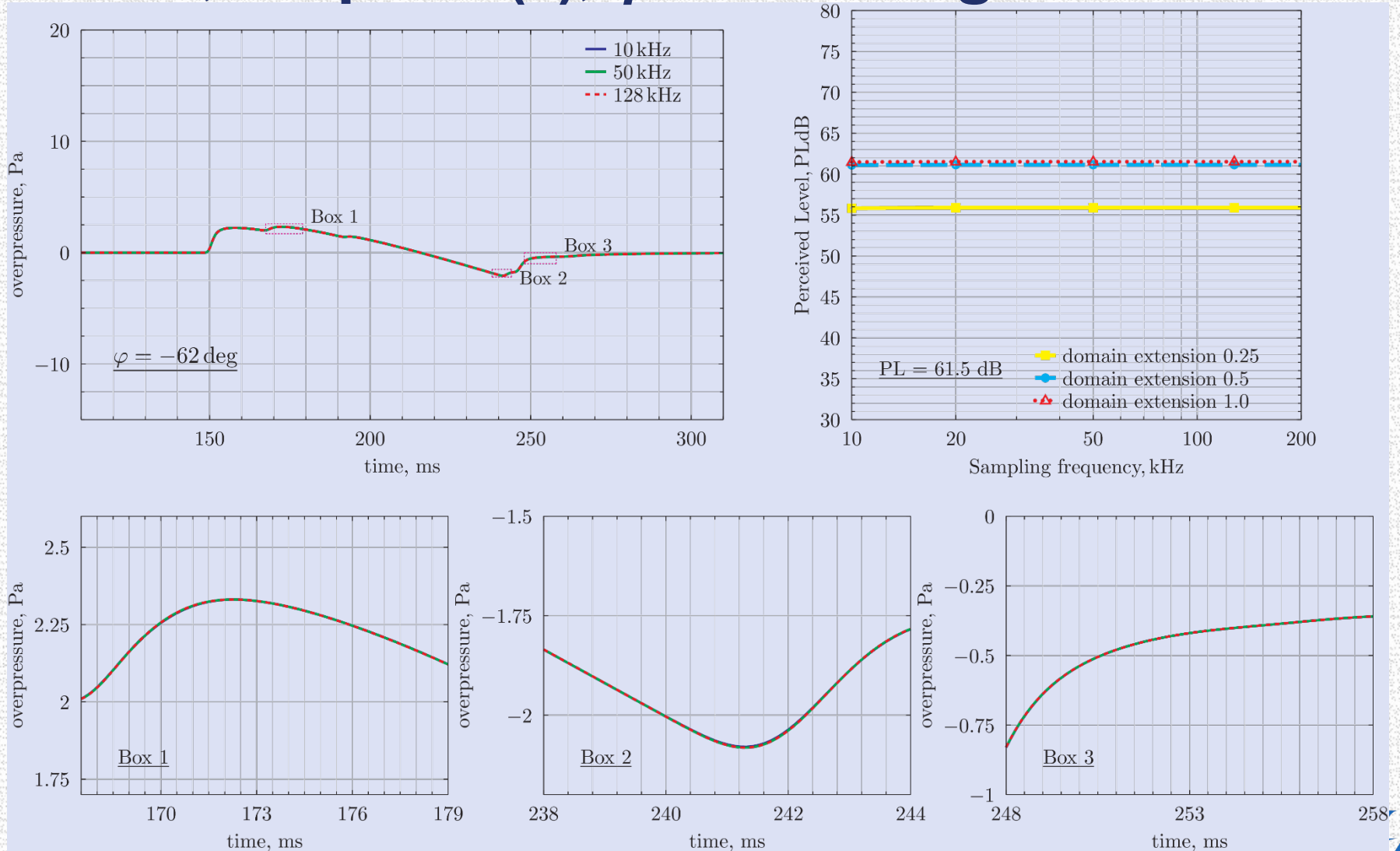
Case 2, Required(i), $\varphi = 60$ deg



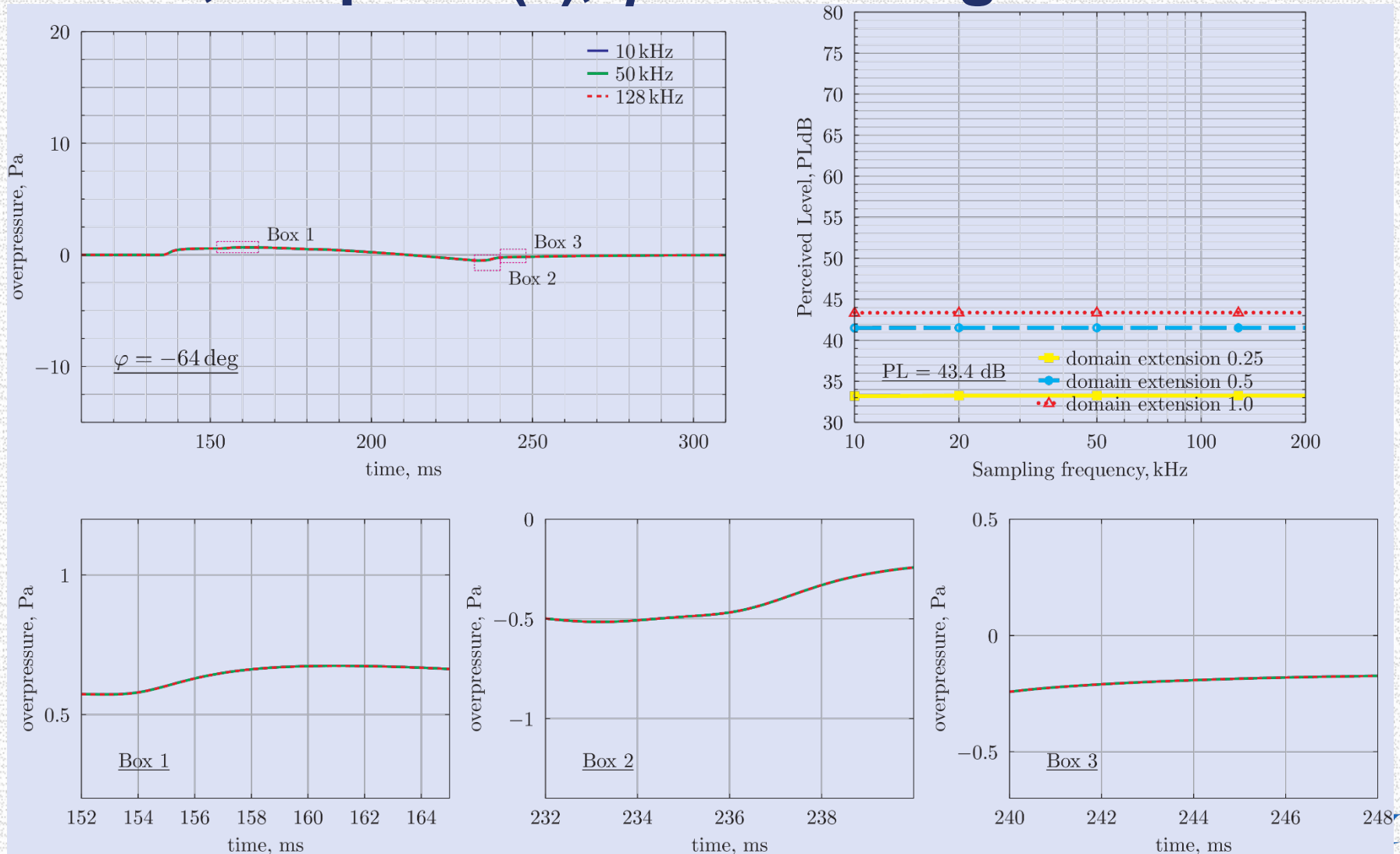
Case 2, Required(ii), $\varphi = -60$ deg



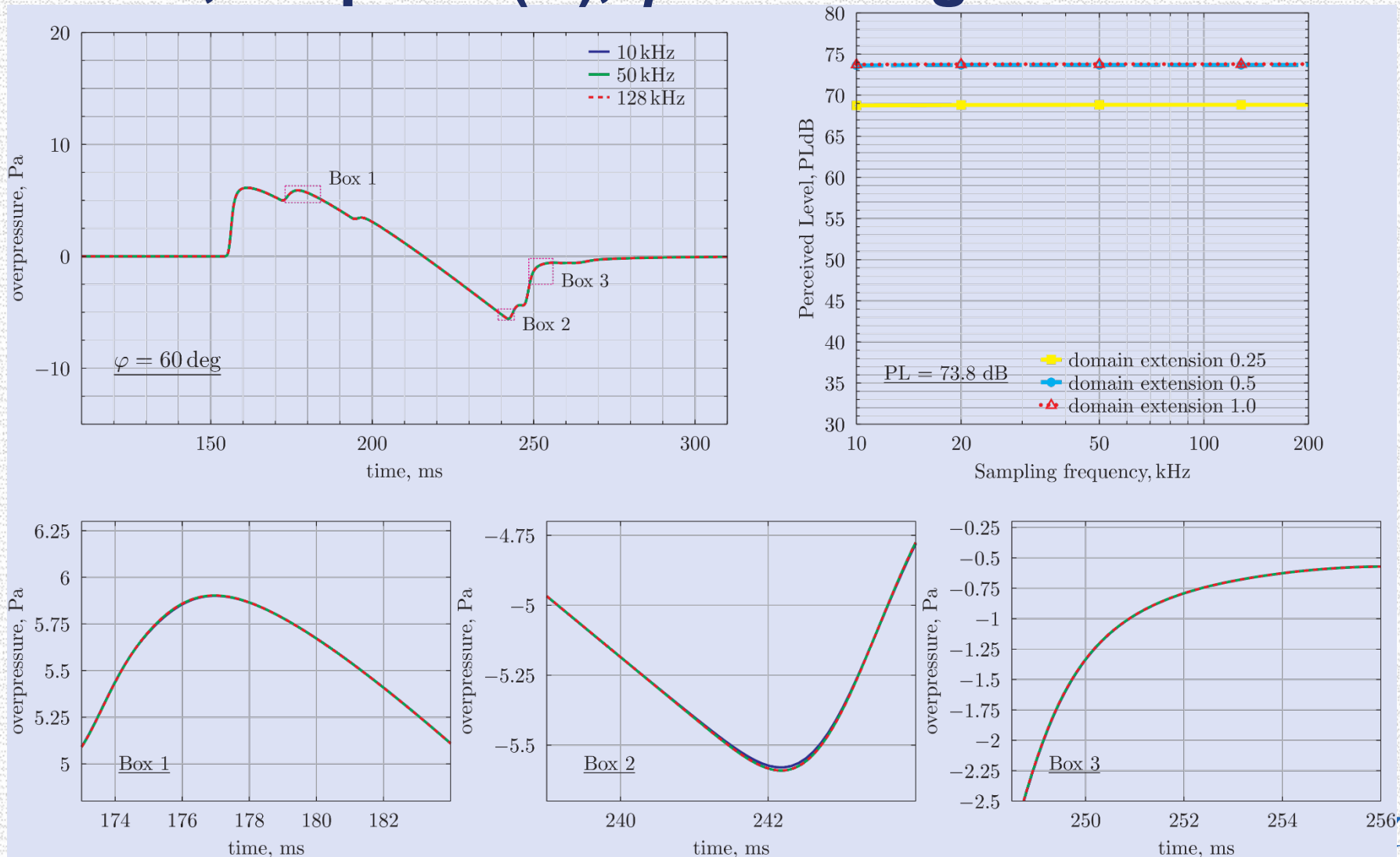
Case 2, Required(ii), $\varphi = -62$ deg



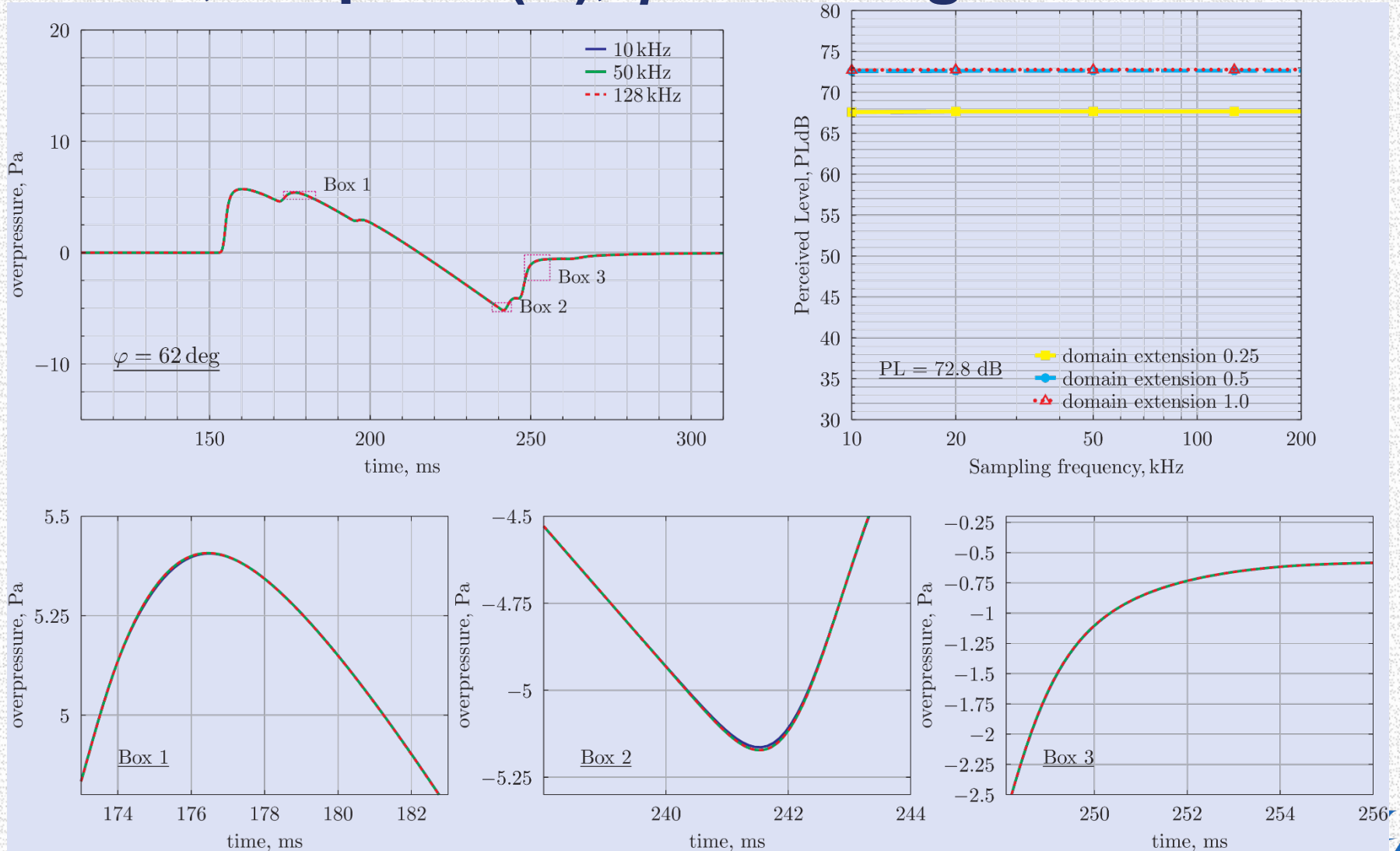
Case 2, Required(ii), $\varphi = -64$ deg



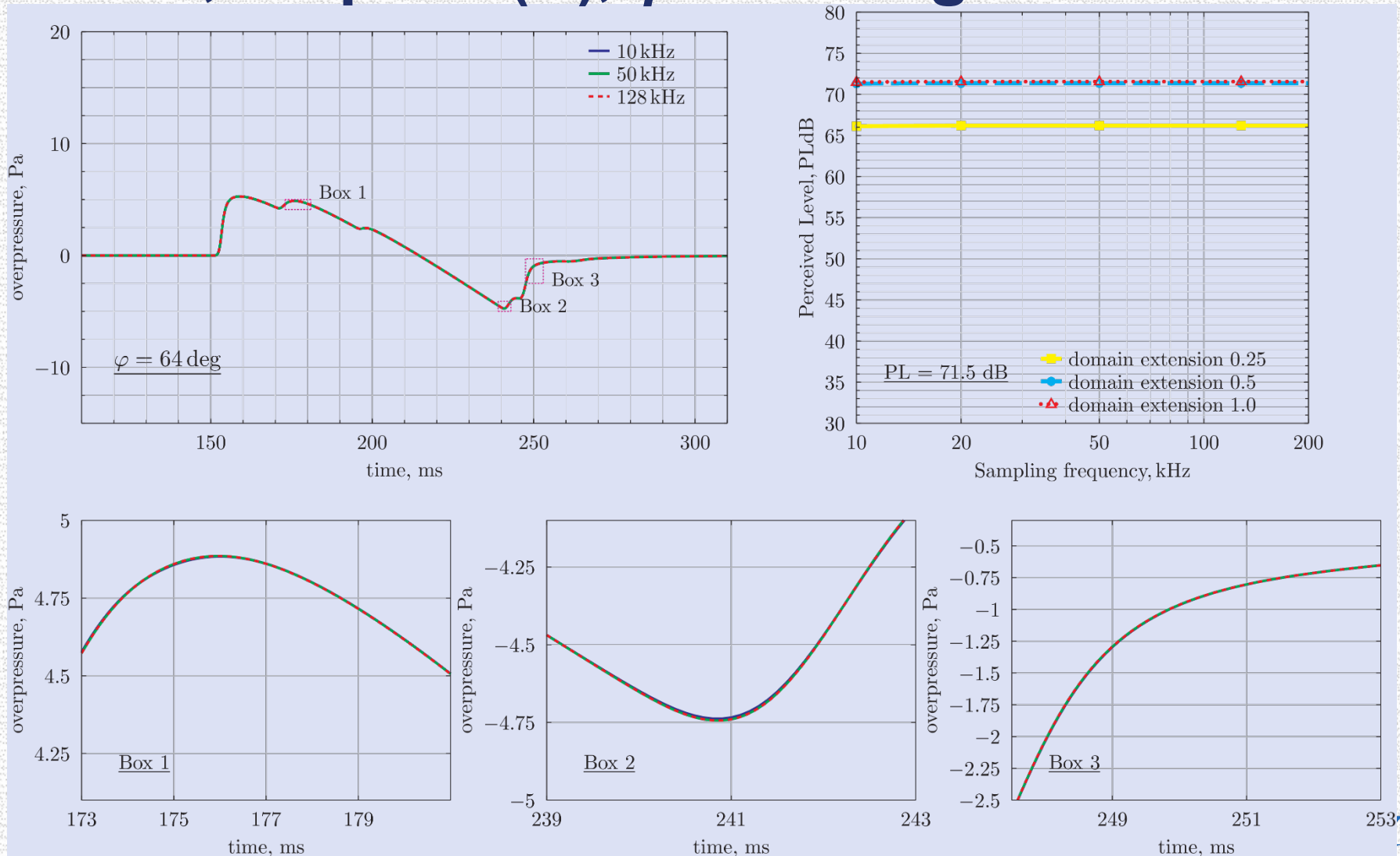
Case 2, Required(iii), $\varphi = 60$ deg



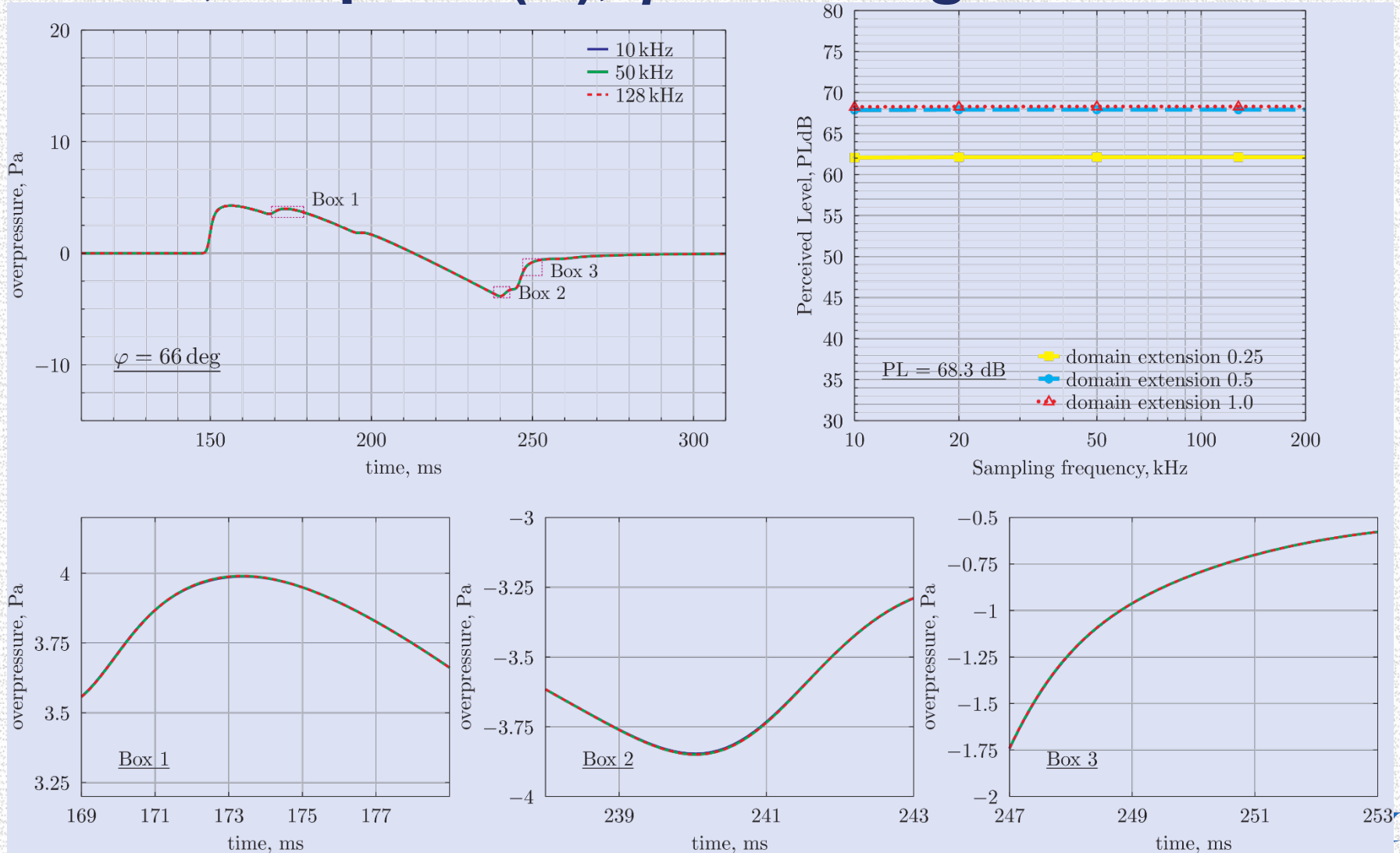
Case 2, Required(iii), $\varphi = 62$ deg



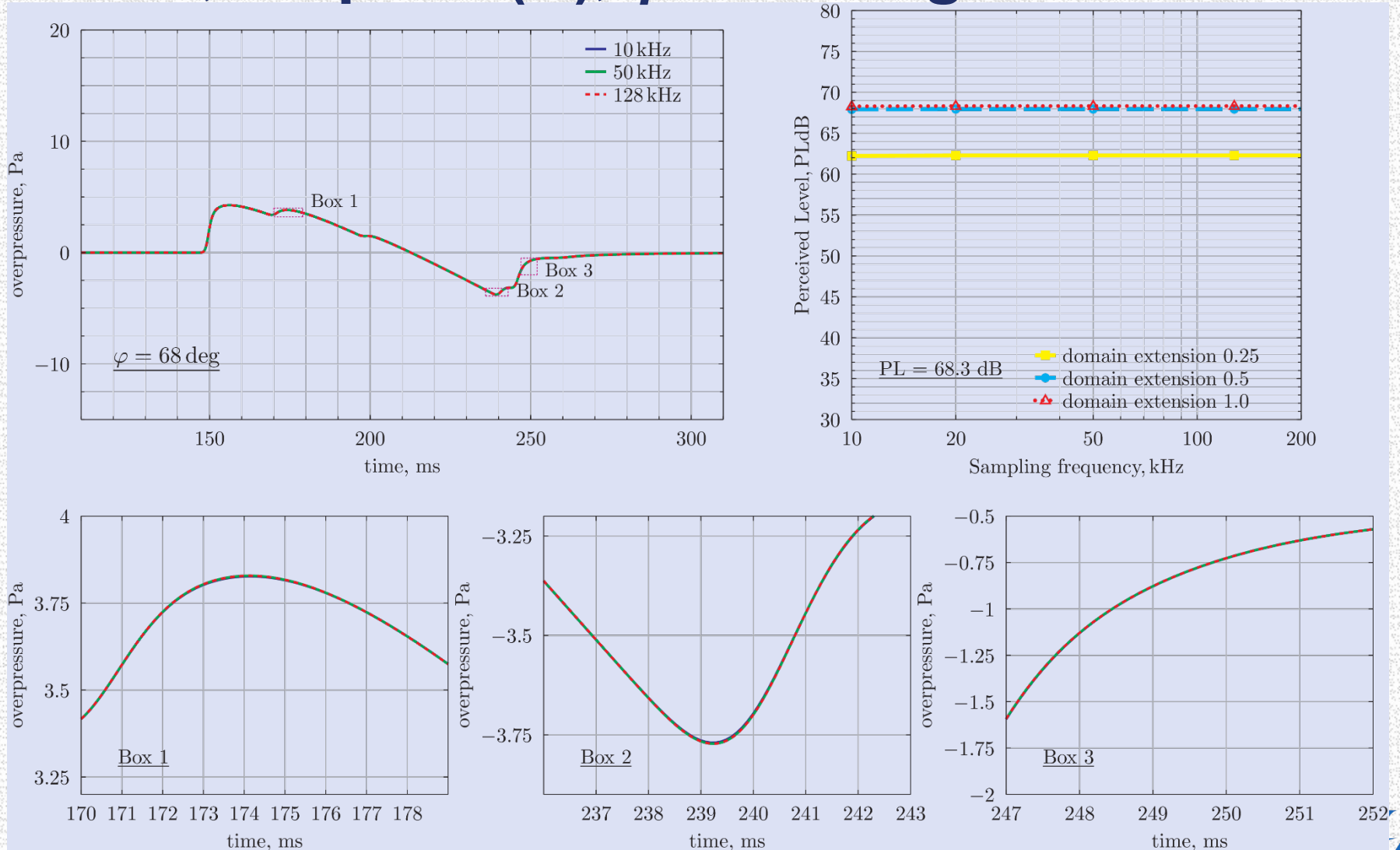
Case 2, Required(iii), $\varphi = 64$ deg



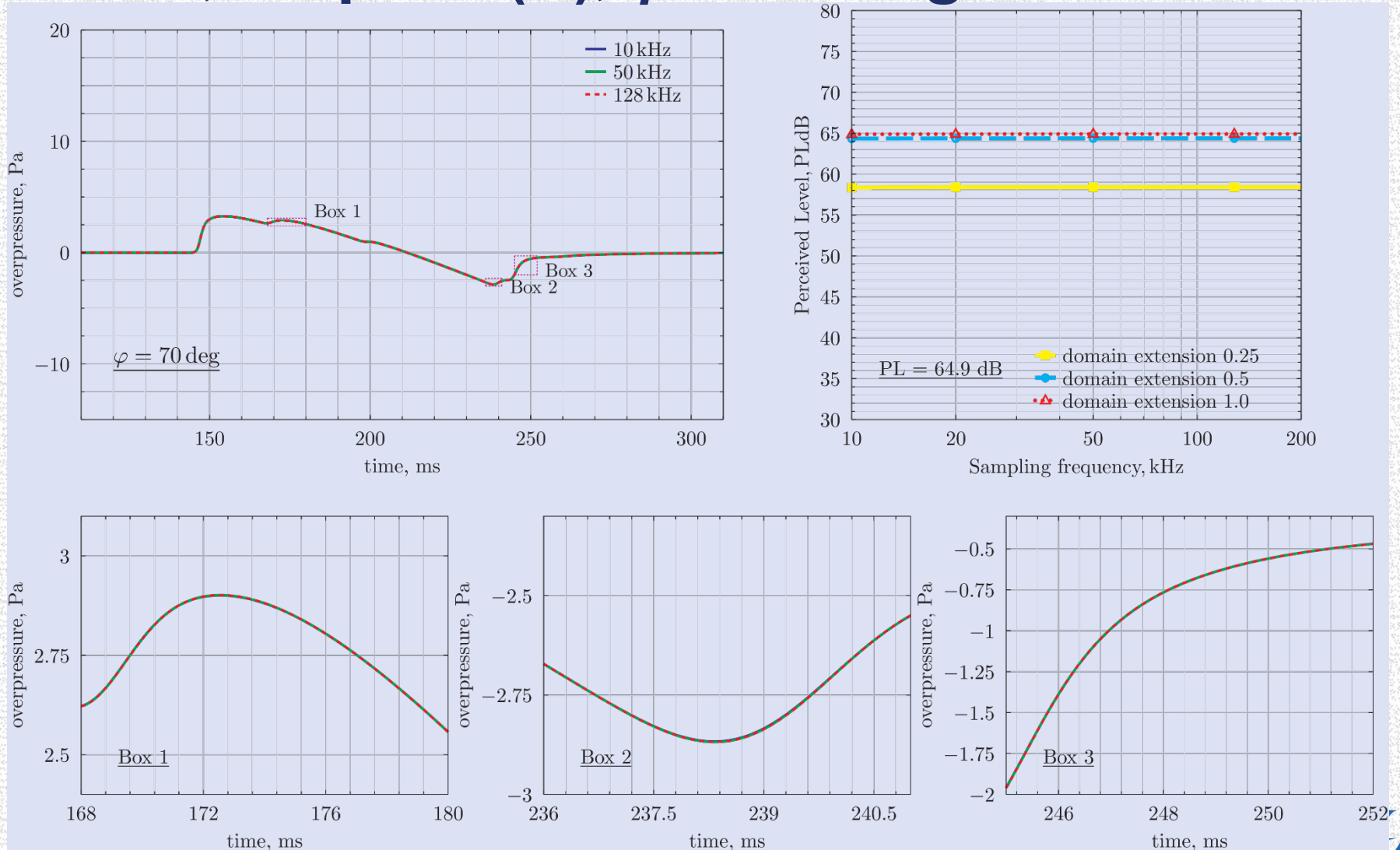
Case 2, Required(iii), $\varphi = 66$ deg



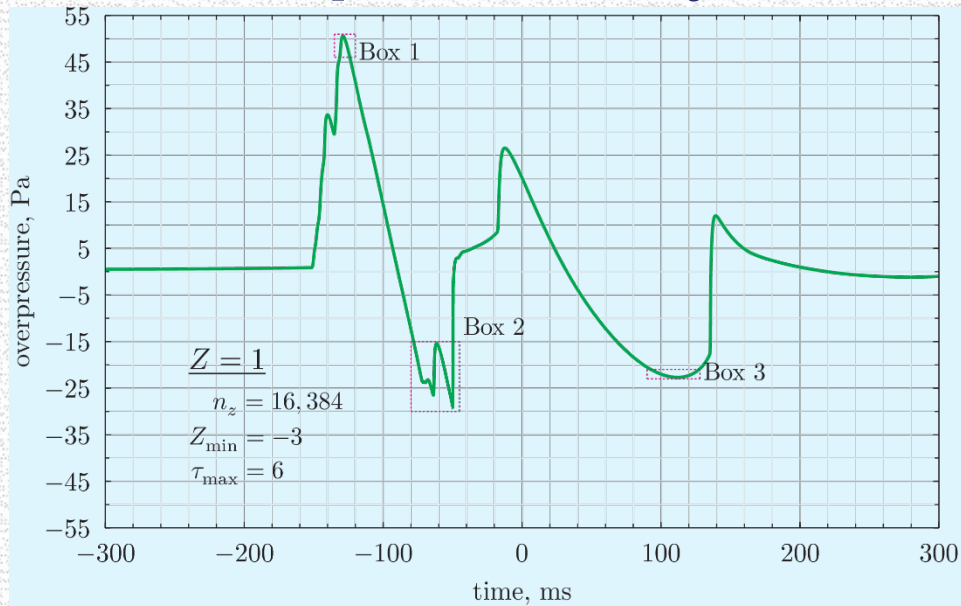
Case 2, Required(iii), $\varphi = 68$ deg



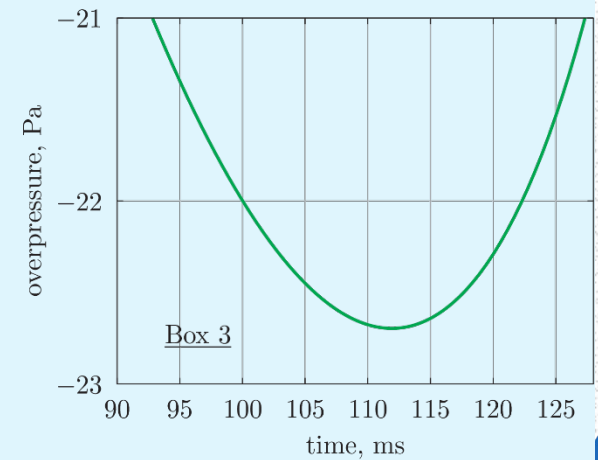
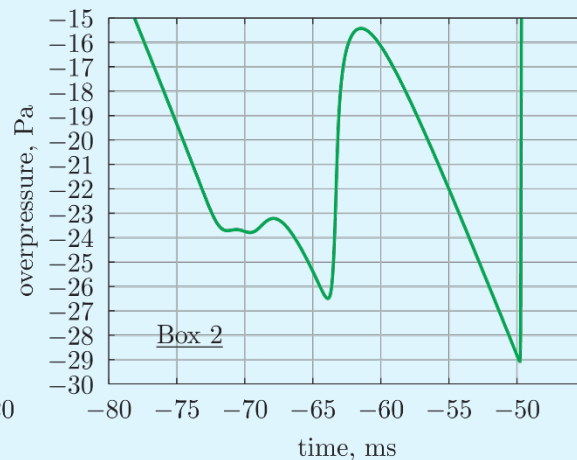
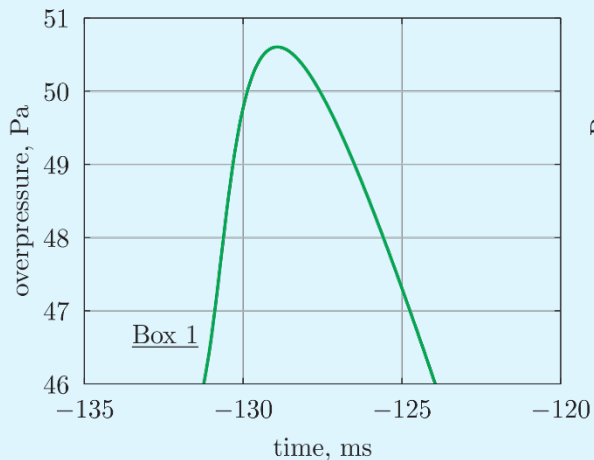
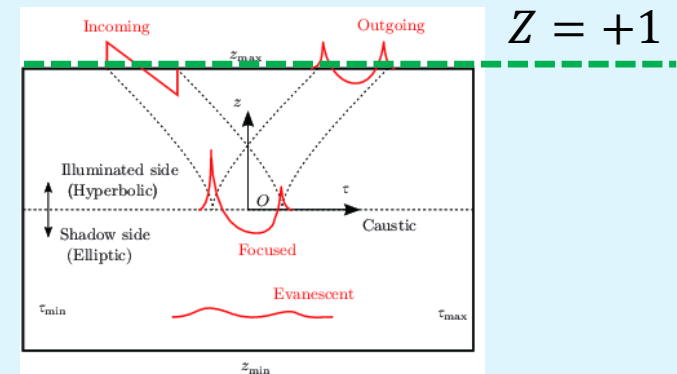
Case 2, Required(iii), $\varphi = 70$ deg



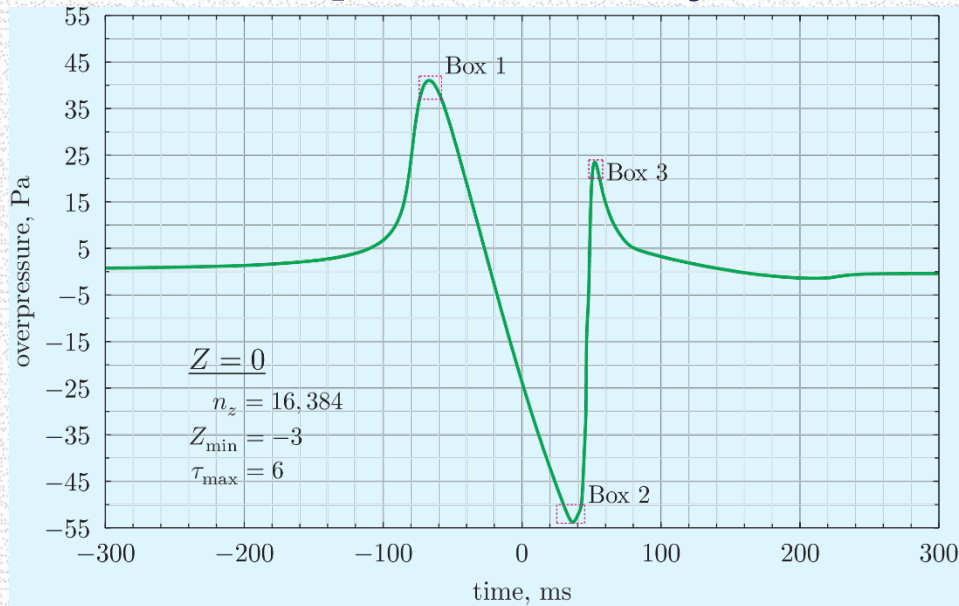
Case1, Optional, $n_\tau = 131,072$



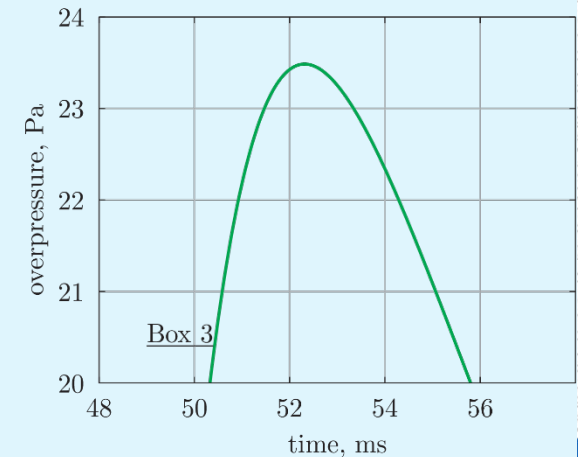
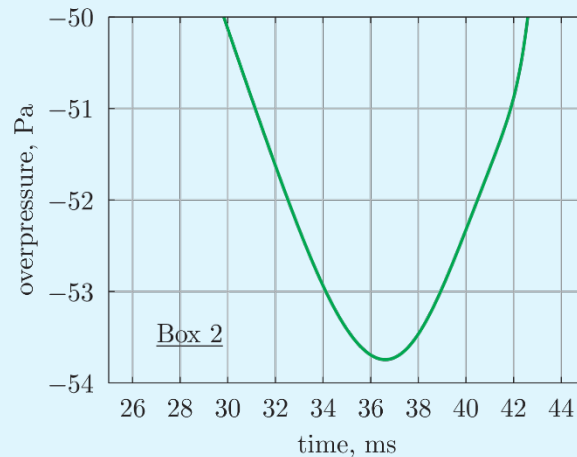
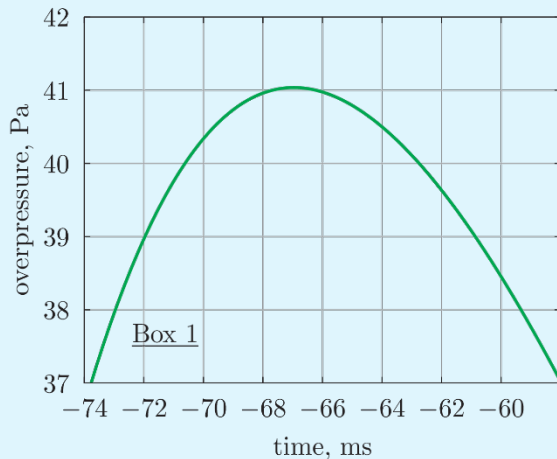
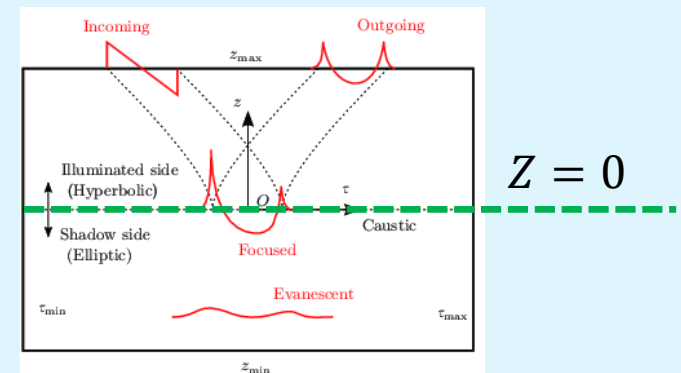
— $n_\tau = 131,072$ (freq. = 45,509 kHz)



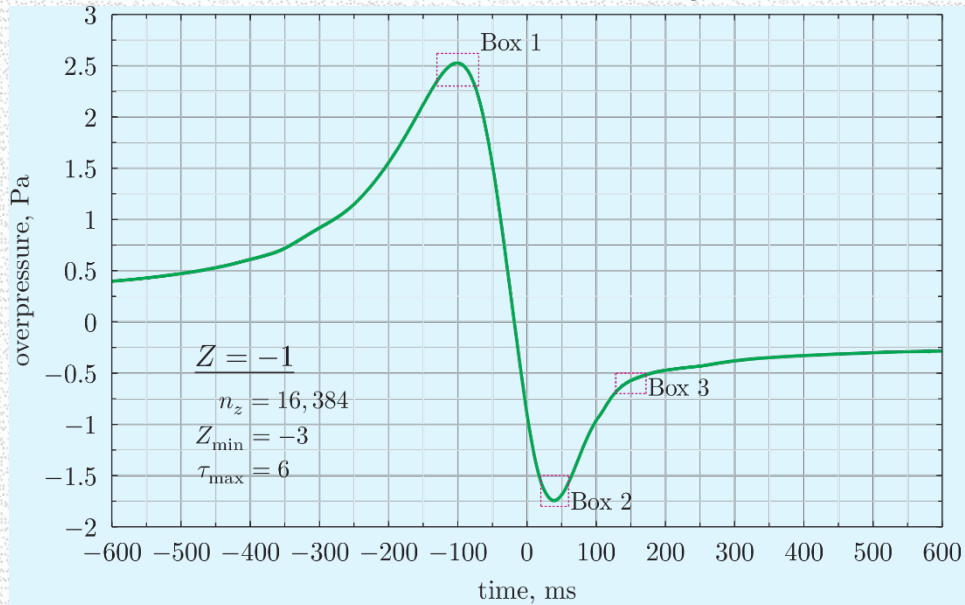
Case1, Optional, $n_\tau = 131,072$



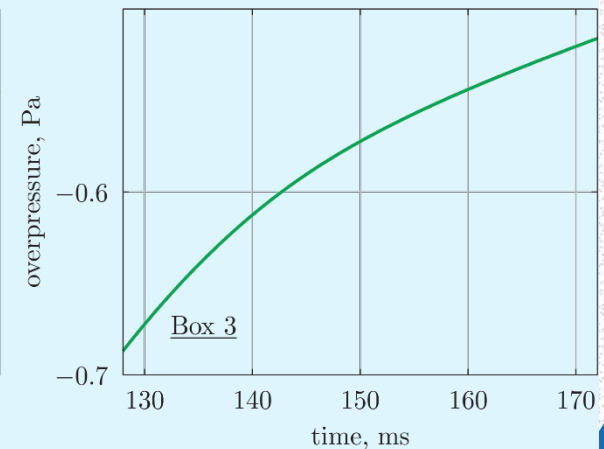
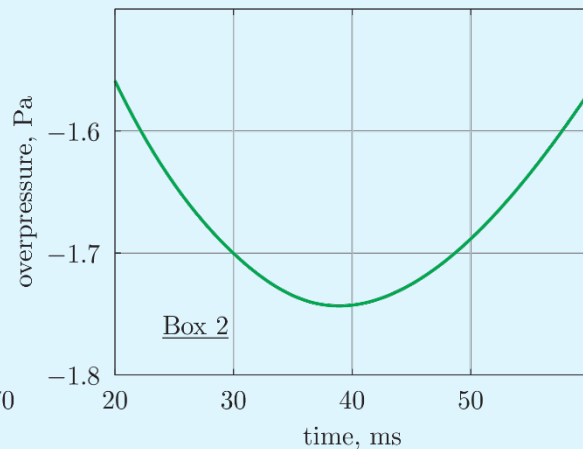
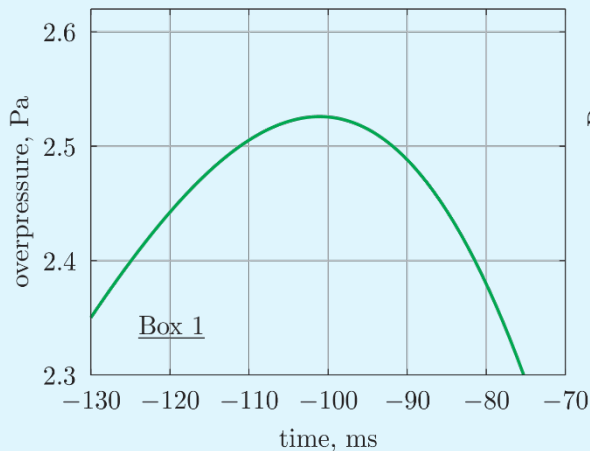
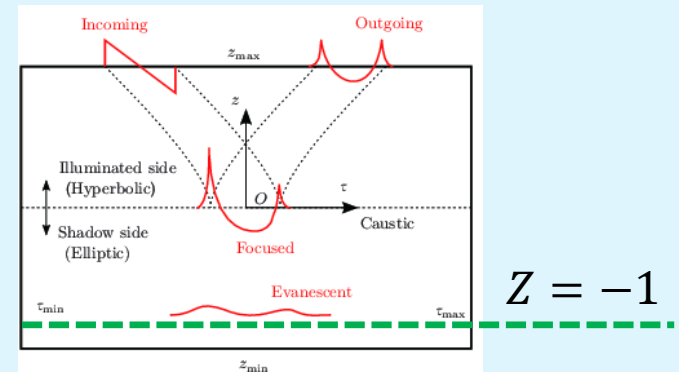
— $n_\tau = 131,072$ (freq. = 45,509 kHz)



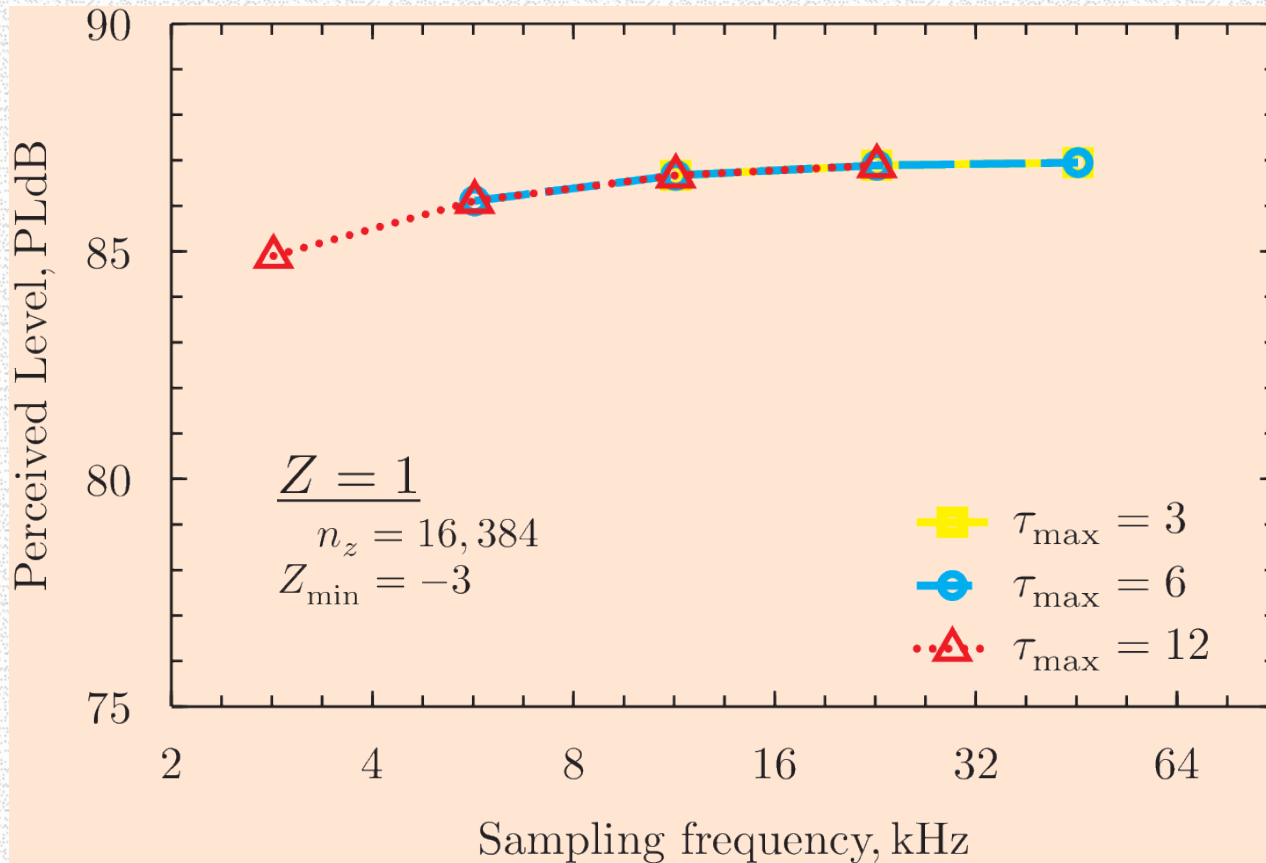
Case1, Optional, $n_\tau = 131,072$



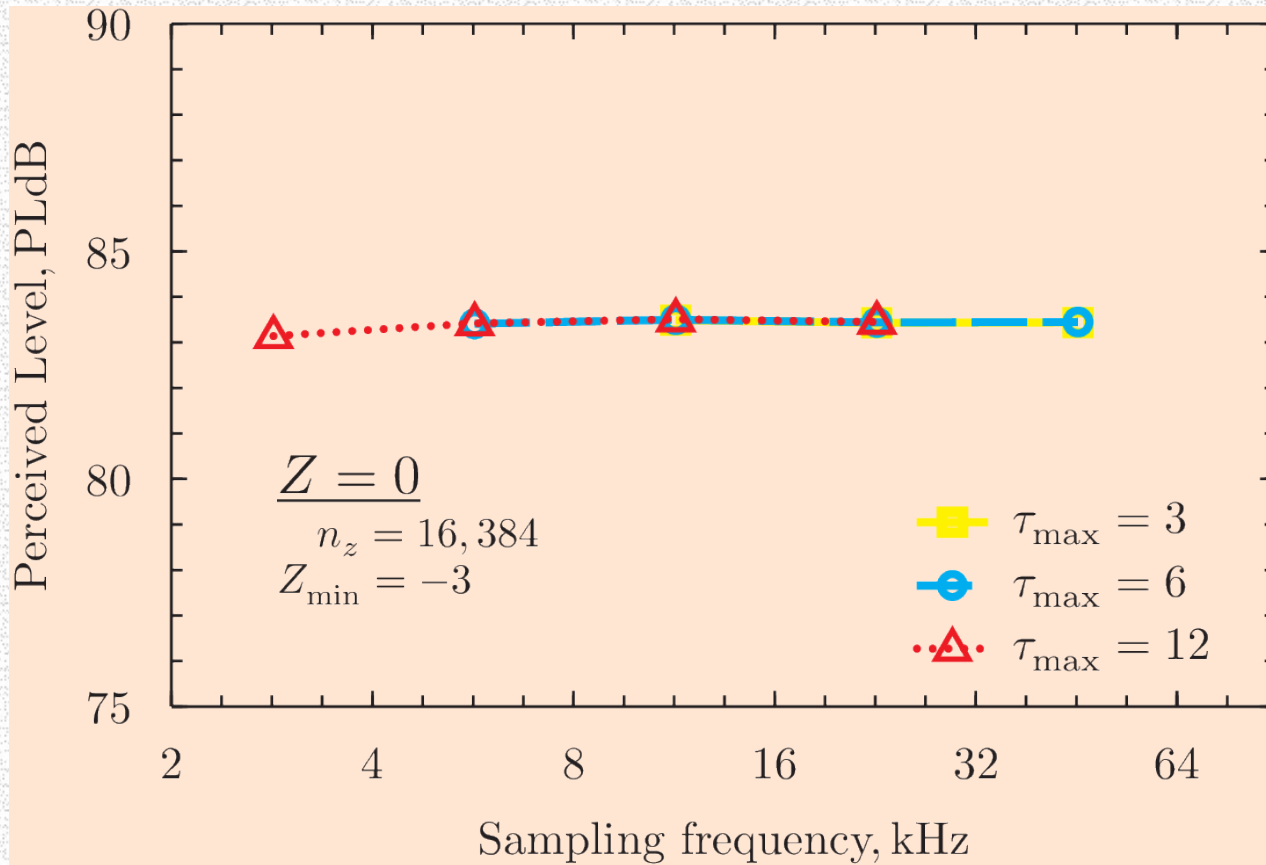
— $n_\tau = 131,072$ (freq. = 45,509 kHz)



Case1, Optional, Fixed Domain size in Z



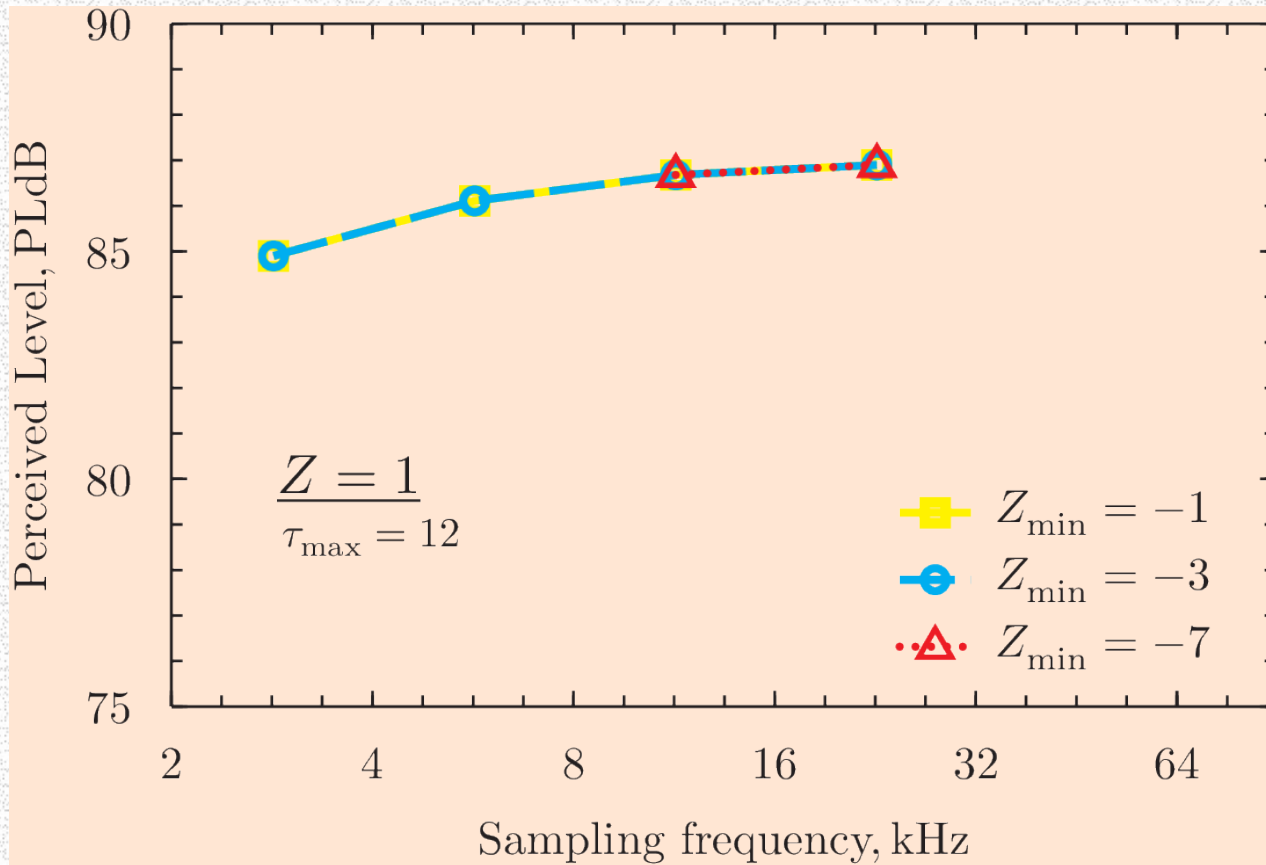
Case1, Optional, Fixed Domain size in Z



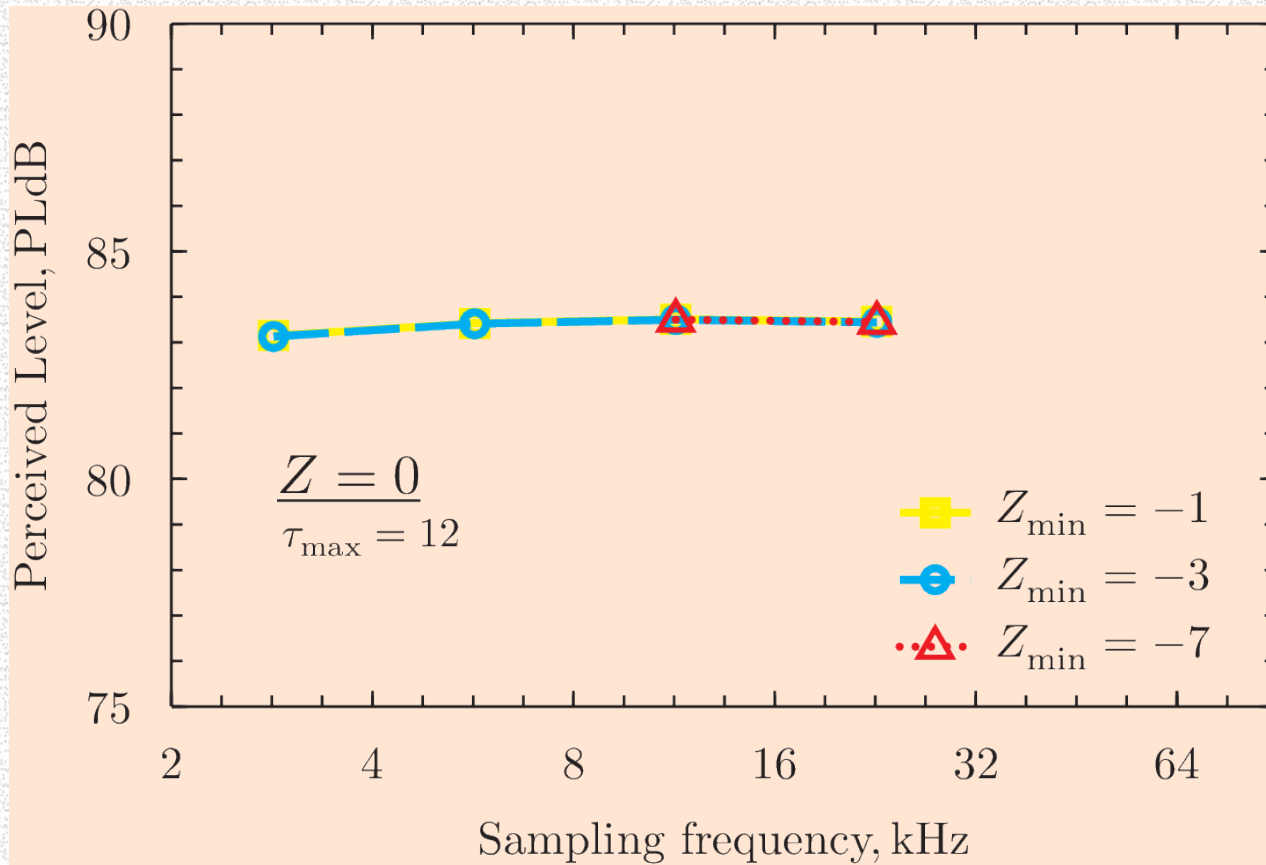
Case1, Optional, Fixed Domain size in Z

$$Z = -1, \text{ N/A}$$

Case1, Optional, Fixed Domain size in τ



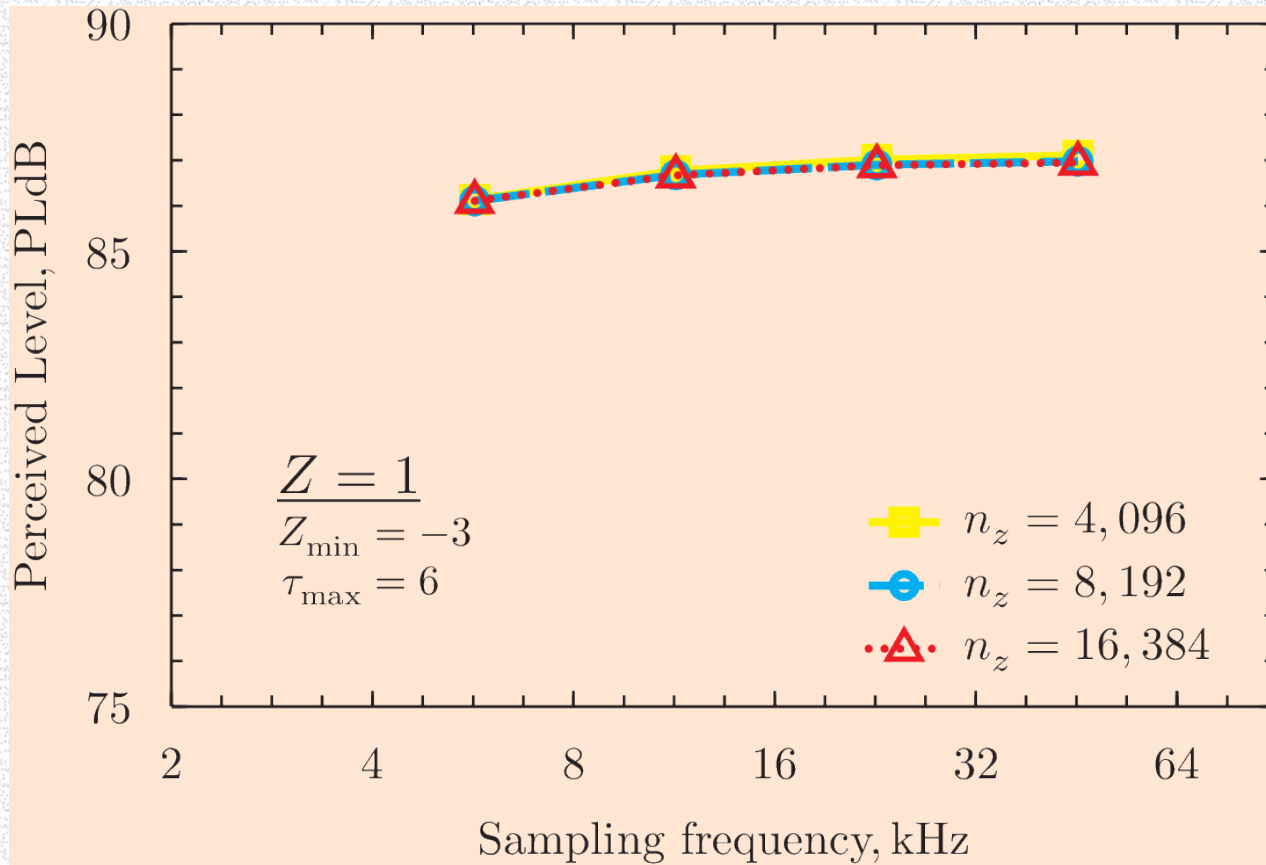
Case1, Optional, Fixed Domain size in τ



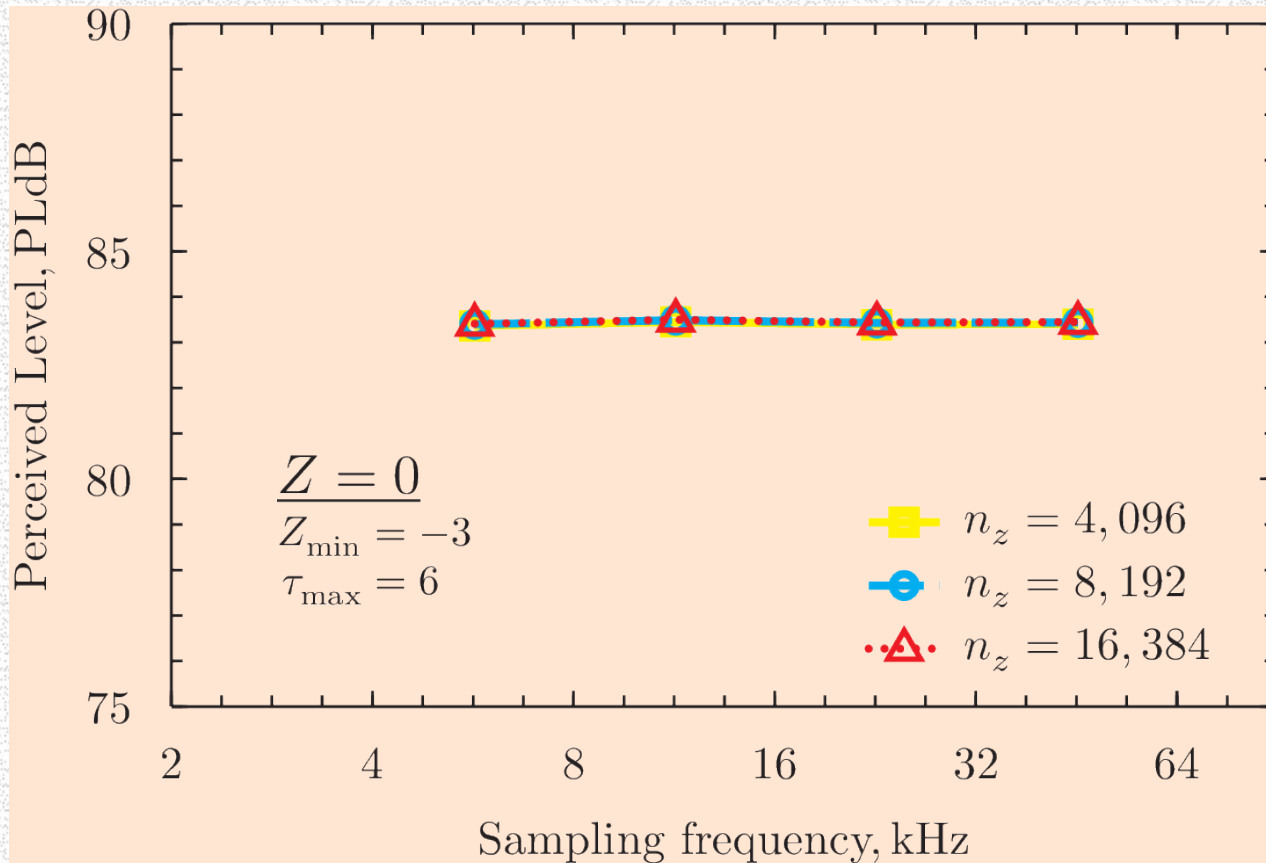
Case1, Optional, Fixed Domain size in τ

$$Z = -1, \text{ N/A}$$

Case1, Optional, Fixed Domain size in Z and τ



Case1, Optional, Fixed Domain size in Z and τ



Case1, Optional, Fixed Domain size in Z and τ

$$Z = -1, \text{ N/A}$$



Numerical Simulation
Research Unit



Specifying parameters in Lossy NTE

✓ 2 parameters appeared in Lossy NTE: μ and ε

$$\left\{ \begin{array}{l} \mu = 2\beta \frac{P_{ac}}{\rho_0 c_0^2} \left(\frac{R_{tot} f_{ac}}{2c_0} \right)^{2/3} \\ \varepsilon = \left(\frac{2c_0}{R_{tot} f_{ac}} \right)^{2/3} \end{array} \right. \quad \frac{\partial^2 P}{\partial Z^2} - Z \frac{\partial^2 P}{\partial \tau^2} + \frac{\mu}{2} \frac{\partial^2 P^2}{\partial \tau^2} + \left[\frac{\alpha}{\varepsilon^2} + \sum_{\nu} \frac{\theta_{\nu}/\varepsilon^2}{1 + \tau_{\nu} \partial/\partial \tau} \right] \frac{\partial^3 P}{\partial \tau^3} = 0$$

P_{ac}, f_{ac} : available from incoming waveform

R_{tot} : assuming $R_{tot} = R_{cau}$

R_{cau} : obtained from the definition of δ

$$\delta = \left(\frac{c_0^2 R_{cau}}{2 f_{ac}^2} \right)^{1/3} \longrightarrow R_{cau} = \frac{2 \delta^3 f_{ac}^2}{c_0^2}$$